Biomechanical simulation of respiratory motion using CUDA for collision detection
Project Management and Software Development for Medical Applications

General Info

Project Title: Biomechanical simulation of respiratory motion using CUDA for collision detection
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Project Abstract

Time-resolved imaging of the thorax or abdominal area is affected by respiratory motion. Nowadays, 1D respiratory surrogates are used to estimate the current state of the lung during its cycle, but with rather poor results. This project aims to improve the framework to predict the 3D lung motion based on a patient-specific finite element model of respiratory mechanics estimated from two CT images at end of inspiration (EI) and end of expiration (EE).

Background and Motivation

Respiratory motion is a source of artifacts in medical image acquisition, which is the basis for disease monitoring, therapy planning and intervention guidance. Currently, signals from devices such as spirometers, abdominal pressure belts or external markers are used as surrogates of respiratory motion. However, the 1D nature of these signals makes it difficult to estimate the 3D lung deformation accurately.

Two categories of methods for patient-specific estimation of respiratory movements can be distinguished: image-based and biomechanical. On the one hand, image-based methods commonly estimate the lung deformations between two or more phases of the respiratory cycle using non-linear image registration. The idea is to create a lung-motion atlas, which is subsequently adapted to the patient. Recent results are promising, but image-based methods are usually restricted to normal breathing patterns, with lower predictive power and versatility in patients. On the other hand, biomechanical approaches compute lung biomechanics, often using finite element methods (FEM), to simulate the physiological deformations during respiration cycles. Often these approaches still rely on 4D image data, which makes it difficult to predict respiratory motion.

We have presented a first framework to estimate the patient’s respiratory motion in [1]. The goal of this project is to decrease the computation time by implementing the collision detection using CUDA.

Student’s Tasks Description

The student will be introduced to the SOFA framework and the novel modules introduced recently. As a first step towards CUDA implementation, an understanding of the current functions needs to be established. Furthermore, the CUDA framework needs to be understood and presented (e.g. kick-off presentation). SOFA framework already incorporates some CUDA functions and modules. The implementation of the collision model needs to be validated using simple scenes and extended to the complex lung setup.

Please send the completed document to us (Ralf.stauder@tum.de) before the project proposal deadline, September 30th. Please note that this proposal will be evaluated by the BMC coordinators and will be assigned to a student only in the case of acceptance.
Technical Prerequisites

All coding will be done in C++ using CUDA and is therefore an important skill required. Matlab is used for evaluation of the model's quality during prediction.

Administrative Info

Working Time: 150 hours
Project Location: Garching
Required Equipment: The computer is set up and can be accessed using remote desktop.

Timeline and Milestones

The timeline and milestones are closely connected to the outline of the lecture. Therefore, kick-off, midterm and final presentations are required. Further details and milestones will be set to fit the student’s skills.

References
