

Slobodan Ilić



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Education

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| Habilitation in Computer Science
Technische Universität München, Germany | expected autumn 2011 |
| PhD in Computer Science (advisor Pascal Fua)
Ecole Polytechnique Fédérale de Lausanne (EPFL)
Computer Vision Lab, Lausanne, Switzerland | May 2005 |
| Pre-doctoral school in Computer Science (equivalent to MSc)
EPFL, Lausanne, Switzerland | July 2000 |
| Engineering Diploma, major in Computer Science
Faculty of Electronic Engineering, University of Niš, Serbia | Nov 1997 |
| Mathematical Gimnasium
"Bora Stanković", Niš, Serbia | June 1992 |

Research Experience

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| Visiting Scientist
Max Planck Center for Visual Computing and Communication, Saarbrücken, Germany
Hosts: Prof. Hans-Peter Seidel and Prof. Christian Theobalt | to start in August 2011 |
| <ul style="list-style-type: none">• Responsible for research of Computer Vision.• Supervision of PhD and MSc students. | |
| Independent Computer Vision Group Leader
CAMP Lab, Technische Universität München, Germany | Feb. 2009 - present |
| <ul style="list-style-type: none">• Responsible for research of Computer Vision Group of CAMP Lab.• Teaching graduate courses related to Computer Vision.• Advising seven PhD students. | |
| Senior Research Scientist
Deutsche Telekom Laboratories, Berlin University of Technology, Berlin, Germany | June 2006 - Feb. 2009 |
| <ul style="list-style-type: none">• Research on using true physical models for handling large deformations.• Research on facial pose estimation by image retrieval.• Real-time dynamic scene reconstruction from multiple cameras.• Advising two PhD students. | |

Post-doctoral fellow **May 2005 - June 2006**
EPFL, Computer Vision Lab, Lausanne, Switzerland

- Research work on Finite Element Methods (FEM) for tracking deformable objects.
- Surface Deformation Models for Non-Rigid 3-D Shape Recovery
- Co-advised one PhD student.

Research Assistant **Aug. 2000 - May 2005**
EPFL, Computer Vision and Virtual Reality Lab, Lausanne, Switzerland

- Designed *implicit meshes*, a novel surface model representation for efficient shape recovery and tracking of 3-D deformable objects in monocular and uncalibrated videos.
- Developed an automated procedure for the generic shape recovery from uncalibrated videos based on Dirichlet Free Form Deformation (DFFD).
- Co-developed an automated face reconstruction method from uncalibrated videos using PCA face morphable models.
- Developed shape modeling editor based on DFFD and supervised implementation of Maya plug-in for DFFD.

Research Assistant at pre-doctoral school **Oct. 1999 - Aug. 2000**
The School for Computer and Communication Science, EPFL, Switzerland

- Worked on obligatory pre-doctoral preparation before a PhD.

Research Assistant **Nov. 1997 - Oct. 1999**
Faculty of Electronic Engineering, University of Niš, Serbia

- Implemented and analyzed basic and advanced digital image processing algorithms.
- Designed and implemented an object-oriented digital image processing library.

Professional Experience and Consulting

Consulting **Feb. 2009 - present**
MVTec, München, Germany

- Deformable Object Detection
- 3D Object Detection and Recognition

Consulting **June 2006- Feb. 2009**
Deutsche Telekom AG, Berlin, Germany

- Preparing, managing and coordinating the Free Viewpoint TV(FVTV) project
- Planing, ordering and building multi-camera acquisition laboratory
- Directing research and development of FVTV project and also Face, gesture and deformation projects

System Manager **Jan. 2002- Dec. 2004**
EPFL, Computer Vision Lab, Lausanne, Switzerland

- Installed and maintained 10 laboratory work stations running both Linux and Windows.
- Maintained and developed laboratory's computer vision library under Linux.

Database Architect **Nov. 1997- Dec. 1998**
Local TV Station "TV5", Niš, Serbia

- Designed and created relational database to handle complete marketing and organization of the firm consisting of more then 5000 items (up to 50 items daily).

Research Interests

- 3D deformable object modeling, shape recovery and tracking in monocular and multiple videos
- Non-rigid registration
- Real-time 3D object reconstruction, detection and tracking
- Real-time motion-stereo and stereo fusion; Multi-view stereo; 3D Reconstruction
- 3D object (rigid and deformable) detection in depth data
- Camera-clustering and organization of photo collections

Research Grants

- Co-principal investigator with Horst Bischof from University of Graz and Pascal Fua from EPFL, *Advanced Learning for Tracking and Detection in Medical Workflow Analysis – D-A-CH program of DFG*, (April 2011, €412.650)
- Principal Investigator, *FP7 EU, Fish Biomass Estimation* (negotiation with EU commission finalizing €200.000)
- Co-principal investigator, *Third party funding from Willow Garage (Robotics Company from California, USA)*, (2009 - present, approx \$200.000, subject to further prolongation in 2011)
- Principal Investigator, *DAAD Travel Grant PROCOPE for collaboration between INRIA, Rhone-Alpes, France and TUM*, 2009-2011, approx €10.000
- Principal investigator, *Third party funding from Deutsche Telekom AG for a PhD thesis to be done at TUM*, (2009- 2010, approx €150.000)
- Principal scientific investigator, *Free Viewpoint TV*, Innovation and Development project, (2007-2008, approx. €600.000)
- Principal investigator, *Face, Gesture and Deformations*, Strategic research project, (2007-2009, approx. €90.000)
- Principal investigator, *Dynamic scene recovery from multiple cameras*, Strategic research project, (2007-2009, approx. €90.000)

Teaching Experience

TUM, Institut für Informatik, München, Germany

Lecturer and creator of the new master course at TUM from Oct 2009.

- Tracking and Detection in Computer Vision, master class, 4 hours a week (held every winter semester)

TUM, Institut für Informatik, München, Germany

Lecturer (exercises) from Feb. 2011

- Numerical Programming, bachelor class, 3 hours a week (held every semester)

TUM, Institut für Informatik, München, Germany

Lecturer (exercises) from Feb. 2009

- 3D Computer Vision I, bachelor and master class, 2 hours a week (held every summer semester)

EPFL, Faculty of Computer Science, Lausanne, Switzerland

Lecturer 2005-2006

- Selected Topics in Computer Vision, doctoral class, 4 hours a week

Teaching Assistant **2001-2002**
• Computer Graphics using OpenGL, undergraduate class, 4 hours a week

Faculty of Electronic Engineering, University of Niš, Serbia
Teaching Assistant **1997-1999**

- Compiler Theory, undergraduate class, 2 hours a week
- Introduction to Programming, undergraduate class, 2 hours a week
- Computer Systems, undergraduate class, 2 hours a week
- Programming in C/C++, course for the faculty personnel, 4 hours a week

Advising Students

PhD candidates

- Cedric Cagniard, Dynamic scene recovery from multiple cameras, 2007-present, Co-Supervised with Prof. Edmond Boyer
- Bertram Drost, Detection of 3D objects in range data, 2009-present, External PhD student with MVTec
- Christian Unger, Automatic car parking system, 2009-present, External PhD student with BMW
- Sebastian Lieberknecht, Dense SLAM, 2009-present, External PhD student with METAIO
- Stefan Holzer, Real-time object detection, tracking and modeling for robotics, 2008-present, Co-Supervised with Prof. Navab
- Stefan Hinterstoisser, Real-time object detection and pose estimation of low-textured and texture-less objects, 2008-present, Co-Supervised with Prof. Navab and V. Lepetit
- Alexander Ladikos, Camera clustering of large scenes, 2008-2010, Co-Supervised with Prof. Navab
- Nemanja Grujic, Facial Animation from Video, 2007-present, Co-Supervised with Prof. Pascal Fua
- Mathiew Salzmann, Modeling Deformable Surfaces from Video, 2004-2006, Co-Supervised with Prof. Pascal Fua

Diploma, master and internship students

- Vasilis Belagiannis, fast and Robust Object Localization by Combining Tracking and Detection with Application to onboard UAV Image Processing, Master with EADS, 2011
- Vladimir Haltakov, Parking Slot Detection, Master thesis with BMW, 2011
- Guillaume Bonnier, Monocular Tracking of Wing Deformations of the Flying Airplane, researcher at CVLAB, EPFL with Pascal Fua, 2010
- Benoit Diotte, Skeleton-based Human Motion Tracking in Multi-Camera Setups, Interdisciplinary Project 2009-10, TUM
- Hagen Kaiser, Real-time Structure from Motion for Industrial Augmented Reality, Diploma student at LMU, project with SIEMENS, 2009-2010
- Aydin Varol, Recovering forces and material properties from images, PhD student of CVLAB, EPFL with Pascal Fua, 2008
- Andrei Zaharescu, Piecewise Multi-Resolution 3-D Surface Reconstruction, PhD student of INRIA, Rhone-Alpes with Radu Horaud, 2008
- Ronan Sicre, Wide baseline stereo, 2007
- S. Stanković, Dirichlet Free Form Deformation plug-in for Maya, 2004

- R. A. Tafihery, 3-D Object Modeling Using Radial Basis Functions (RBFs), 2003
- B. Peny, Using Free Form Deformation(FFD) to fit deformable models to noisy 3D data, 2003
- A. Ebadi, Active Contours: Snakes, 2002

Professional Activities

Program Chair

- 1st IEEE ICCV11 Workshop on Dynamic Shape Capture and Analysis(4DMOD)

Area Chair

- International Conference on Computer Vision (ICCV 2011)

Technical Program Committee

- IEEE International Conference in Computer Vision (ICCV), 2007, 2009
- IEEE Computer Vision and Pattern Recognition (CVPR), 2007, 2008, 2009, 2010, 2011
- European Conference on Computer Vision (ECCV), 2006, 2008, 2010
- IEEE Asian Conference on Computer Vision (ACCV), 2009, 2010
- IEEE International Conference on Pattern Recognition (ICPR), 2008
- IEEE Workshop on Motion and Video Computing (WMVC), 2011
- IEEE Workshop on Human Activity Understanding from 3D Data (HAU3D11) , 2011
- 16th International Workshop on Vision, Modeling and Visualization VMV, 2011
- Pacific Graphics (PG), 2009

Reviewer

- European Conference on Computer Vision (ECCV), 2000, 2002, 2004
- International Conference on Computer Vision (ICCV), 2001, 2003, 2005
- Conference on Computer Vision and Pattern Recognition (CVPR), 2001, 2002, 2003, 2004, 2005
- IEEE Journal of Transactions on Pattern Analysis and Machine Intelligence (PAMI)
- International Journal of Computer Vision (IJCV)
- Journal of Computer Graphics and Animation (CGA)
- Journal of Computer Vision and Image Understanding (CVIU)
- Journal on Image and Vision Computing (IMAVIS)
- The Visual Computer Journal (TVCJ)
- The International Journal of Robotics Research (IJRR)

PhD committee member

- Contributions to Spatial and Temporal 3-D Reconstruction from Multiple Cameras, Andrei Zaharescu, Perception, INRIA, Rhone-Alpes, France
- Spatio-Temporal Modeling of Dynamic 3D Scenes from Visual Data, Kiran Varanasi, Perception, INRIA, Rhone-Alpes, France

Honors and Awards

- EPFL predoctoral fellowship for the distinguished students **1999-2000**
- Ministry of Science and Technology grant for the prominent young researchers **1997-1999**
- Municipality fellowship for the best undergraduate students **1996-1997**
- Second grade best student faculty award **1994**
- Ministry of education fellowship for the best undergraduate students **1993-1994**
- First grade best student faculty award **1993**
- Mathematical High School best graduated student special award **1992**

Languages

Serbian	– native
English	– fluent
French	– fluent
German	– fluent
Russian	– good understanding

Invited Talks

1. Probabilistic Deformable Surface Tracking from Multiple Videos: A Patch-Based Approach – MPI for Intelligent Systems(Michael Black), Tübingen, Germany, April 2011
2. Probabilistic Deformable Surface Tracking from Multiple Videos: A Patch-Based Approach – The 28th Pattern Recognition and Computer Vision Colloquium, Spring 2011(Jiri Matas), Czech Technical University, April 2011
3. Probabilistic Deformable Surface Tracking From Multiple Videos – MPI for Informatics(Hans-Peter Seidel and Christian Theobalt), Saarbruecken, Germany, January 2011
4. Research Topics in Computer Vision at CAMP, TUM – EADS, Munich, Germany, January 2011
5. Tracking, Detection and Recognition for Camera Systems in the Vehicles – BMW, Munich, Germany, January 2011
6. Free-Form Surface Tracking: A Patch-Based Approach, CVLAB (Pascal Fua), EPFL, Switzerland, August 2010
7. Real-time Object Detection and Tracking, INRIA (Radu Horaud), Rhone-Alpes August 2010
8. Free-Form Surface Tracking: A Patch-Based Approach, Stanford University; Image, Video and Multimedia Systems Group (Prof. Bernd Girod), June 2010
9. Model Globally, Match Locally: Efficient and Robust 3D Object Recognition, Willow Garage (Radu Rusu), June 2010
10. Iterative mesh deformation for dense surface tracking, CVLAB (Pascal Fua), EPFL, Switzerland, June 2009
11. Deformable Surface Models for Non-rigid 3D Shape Recovery, Metaio, (Selim Benhiman) Munich, November 2008
12. Deformable Surface Models for Non-rigid 3D Shape Recovery, MVTec, (Carsten Steger)Munich, November 2008
13. Physically Based Surface Deformation, INRIA (Edmond Boyer), Grenoble, August 2008
14. Non-Rigid 3-D Shape Recovery, TUM (Nassir Navab), June 2008

15. Implicit Meshes: Unifying Implicit and Explicit Surface Representations for 3D Reconstruction and Tracking, IDIAP, Switzerland, March 2006
16. Implicit Meshes for Surface Reconstruction, University of Surrey (Adrian Hilton), UK, April 2006
17. Deformable Surface Models in Computer Vision, Deutsche Telekom Laboratories, Germany, 18-20 November 2005

Publications

PhD Thesis

- **Ilić, S.** Implicit Meshes: Unifying Implicit and Explicit Surface Representations for 3D Reconstruction and Tracking. PhD thesis, EPF Lausanne, Computer Vision Laboratory, Station 14, CH-1015 Lausanne, 2005. Diss. EPFL No. 3243.

Journal Papers

1. CAGNIART, C., BOYER, E., **Ilić, S.** A Bayesian Approach to Multi-view 4D Modeling. In *International Journal of Computer Vision IJCV* (submitted March 2011).
2. UNGER, C., WAHL E. , **Ilić, S.** Probabilistic Disparity Fusion for Real-Time Motion-Stereo . *IEEE Transactions on Pattern Analysis and Machine Intelligence PAMI* (submitted January 2011).
3. HOLZER, S., **Ilić, S.**, NAVAB, N. Multi-Layer Adaptive Linear Predictors for Real-Time Tracking. *IEEE Transactions on Pattern Analysis and Machine Intelligence PAMI* . (under minor revision).
4. UNGER, C., WAHL E. , **Ilić, S.** Parking Assistance using Dense Motion-Stereo: Real-Time Parking Slot Detection, Collision Warning and Augmented Parking . *Machine Vision and Applications MVA* (special issue on Car Navigation and Vehicle Systems) (submitted August 2010).
5. HINTERSTOISER, S., **Ilić, S.**, STURM, P., FUA, P., NAVAB, N., LEPETIT, V. Gradient Response Maps for Real-Time Detection of Texture-Less Objects. *IEEE Transactions on Pattern Analysis and Machine Intelligence PAMI* . (under major revision).
6. **Ilić, S.**, SALZMANN, M., FUA, P. Implicit Meshes for Effective Silhouette Handling. *International Journal of Computer Vision IJCV* . Volume 72 , Issue 2, April 2007.
7. SALZMANN, M., PILET, J., **Ilić, S.**, FUA, P. Surface Deformation Models for Non-Rigid 3-D Shape Recovery. *IEEE Transactions on Pattern Analysis and Machine Intelligence PAMI* . Vol. 29, Issue 8, 2007.
8. **Ilić, S.**, FUA, P. Implicit Meshes for Surface Reconstruction. *IEEE Transactions on Pattern Analysis and Machine Intelligence PAMI* . Vol. 28, Nr. 2, pp. 328–333, February 2006..

Refereed Conference Papers

9. LIEBERKNECHT, B., BEN HIMANE, S. , **Ilić, S.** Simultaneous Reconstruction and Tracking of non-planar Templates . *DAGM Conference (accepted, Frankfurt, Germany, 2011)*.
10. UNGER, C., WAHL E. , **Ilić, S.** Efficient Stereo and Optical Flow with Robust Similarity Measures . *DAGM Conference (accepted, Baden-Baden, Germany, 2011)*.
11. UNGER, C., WAHL E. , **Ilić, S.** Efficient Stereo Matching for Moving Cameras and Decalibrated Rigs . *IEEE Intelligent Vehicles Symposium IV (Baden-Baden, Germany, June 2011)*.
12. CAGNIART, C., BOYER, E., **Ilić, S.** Probabilistic Deformable Surface Tracking From Multiple Videos . In *European Conference on Computer Vision (ECCV)* (Crete, Greece, September 2010).
13. LADIKOS, A., E. BOYER, NAVAB, N., **Ilić, S.** Region Graphs for Organizing Image Collections. In *IEEE First Workshop on Reconstruction and Modeling of Large-Scale 3D Virtual Environments (RMLE) in conjunction with ECCV* (Crete, Greece, September 2010).
14. CAGNIART, C., BOYER, E., **Ilić, S.** Free-Form Mesh Tracking : a Patch-Based Approach. In *IEEE Conference on Computer Vision and Pattern Recognition (CVPR)* (San Francisco, CA, USA, June 2010).
15. DROST, B., ULRICH, M., NAVAB N., **Ilić, S.** Model Globally, Match Locally: Efficient and Robust 3D Object Recognition. In *IEEE Conference on Computer Vision and Pattern Recognition (CVPR)* (San Francisco, CA, USA, June 2010).
16. HOLZER, S., **Ilić, S.**, NAVAB, N. Adaptive Linear Predictors for Real-Time Tracking. In *IEEE Conference on Computer Vision and Pattern Recognition (CVPR)* (San Francisco, CA, USA, June 2010).
17. HINTERSTOISER, S., LEPETIT, V., **Ilić, S.**, FUA, P., NAVAB, N. Dominant Orientation Templates for Real-Time Detection of Texture-Less Objects. In *IEEE Conference on Computer Vision and Pattern Recognition (CVPR)* (San Francisco, CA, USA, June 2010).
18. CAGNIART, C., BOYER, E., **Ilić, S.** Iterative Deformable Surface Tracking in Multi-View Setups. In *3D Data Processing, Visualization and Transmission (3DPVT)* (Paris, France, May 17-20, 2010).
19. CAGNIART, C., BOYER, E., **Ilić, S.** Iterative Mesh Deformation for Dense Surface Tracking. In *IEEE International Workshop on 3-D Digital Imaging and Modeling (3DIM) in conjunction with ICCV09* (Kyoto, Japan, October 3-4, 2009).
20. LADIKOS, A., **Ilić, S.**, NAVAB, N. Spectral Camera Clustering. In *IEEE First Workshop on Emergent Issues in Large Amounts of Visual Data (WS-LAVD) in conjunction with ICCV09* (Kyoto, Japan, October 3-4, 2009).
21. HOLZER, S., HINTERSTOISER, S., **Ilić, S.**, NAVAB, N. Distance Transform Templates for Object Detection and Pose Estimation . In *IEEE Conference on Computer Vision and Pattern Recognition (CVPR)* (Miami, Florida, USA, June 2009).
22. **Ilić, S.** Object Labeling for Recognition Using Vocabulary Trees. In *IEEE International Conference in Pattern Recognition (ICPR)* (Tampa, Florida, USA, December, 2008).

23. ZAHARESCU, A., CAGNIART, C., **Ilić, S.**, BOYER, E., HORAUD, R. Camera Clustering for Multi-resolution 3D Surface Reconstruction. In *IEEE International Workshop on Multi-camera and Multi-modal Sensor Fusion Algorithms and Applications M²SFA² in conjunction with (ECCV)* (Marseille, France, October, 2008).
24. GRUJIĆ, N., **Ilić, S.**, LEPETIT, V., FUA, P. 3D Facial Pose Estimation by Image Retrieval. In *Automatic Face and Gesture Recognition (FG)* (Amsterdam, Netherlands, September, 2008).
25. **Ilić, S.** Comparing Timoshenko Beam to Energy Beam for Fitting Noisy Data. In *Asian Conference in Computer Vision (ACCV)* (Tokyo, Japan, November, 2007).
26. **Ilić, S.**, FUA, P. Non-Linear Beam Model for Tracking Large Deformations. In *IEEE International Conference on Computer Vision (ICCV)* (Rio de Janeiro, Oct 2007).
27. **Ilić, S.** Using Subdivision Surfaces for 3-D Reconstruction from Noisy Data. In *DEFORM workshop in conjunction with British Machine Vision Conference BMVC* (Edinburgh, Sep 2006).
28. **Ilić, S.**, SALZMANN, M., FUA, P. Implicit Mesh Make for Better Silhouettes. In *IEEE Conference on Computer Vision and Pattern Recognition (CVPR)* (San Diego, CA, June 2005).
29. SALZMANN, M., **Ilić, S.**, FUA, P. Physically Valid Shape Parameterization for Monocular 3-D Deformable Surface Tracking. In *British Machine Vision Conference BMVC* (Oxford, UK, September 2005).
30. DIMITRIJEVIĆ, M., **Ilić, S.**, FUA, P. Accurate Face Models from Uncalibrated and Ill-Lit Video Sequences. In *IEEE Conference on Computer Vision and Pattern Recognition (CVPR)* (Washington, DC, June 2004).
31. **Ilić, S.**, FUA, P. Implicit Mesh Models for Modeling and Tracking. In *IEEE Conference on Computer Vision and Pattern Recognition (CVPR)* (Madison, WI, June 2003).
32. **Ilić, S.**, FUA, P. From Explicit to Implicit Surfaces for Visualization, Animation and Modeling. In *ISPRS workshop on Visualization and Animation of Reality-based 3D Models* (Vulpera, Switzerland, February 2003).
33. **Ilić, S.**, FUA, P. Generic Deformable Implicit Mesh Models for Automated Reconstruction. In *International Workshop on Higher-Level Knowledge in 3D Modeling and Motion Analysis in conjunction with ICCV* (Nice, France, October 2003).
34. **Ilić, S.**, FUA, P. Using Dirichlet Free Form Deformation to Fit Deformable Models to Noisy 3-D Data. In *European Conference on Computer Vision ECCV* (Copenhagen, Denmark, May 2002).

Other Publications

35. UNGER, C., WAHL E. , STURM P., **Ilić, S.** Probabilistic Disparity Fusion for Real-Time Motion-Stereo . Technical Report, TUM, August 2010
36. CAGNIART, C., BOYER, E., **Ilić, S.** Suivi de Surfaces par Déformations Itératives. 22es journées de l'Association Française d'Informatique Graphique, November 2009
37. SALZMANN, M., PILET, J., **Ilić, S.** AND FUA, P. Parameterizing Deformable Surfaces for Monocular 3-D Tracking. Technical Report IC/2005/20

38. **Ilić, S.**, SALZMANN, M. AND FUA, P. Implicit Meshes Make for Better Silhouettes. Technical Report IC/2004/92
39. **Ilić, S.**, FUA, P. Implicit Meshes for Surface Reconstruction. Technical Report IC/2004/25
40. DIMITRIJEVIC, M., **Ilić, S.** AND FUA, P. Accurate Face Models from Uncalibrated and Ill-Lit Video Sequences. Technical Report IC/2004/05
41. **Ilić, S.** Well Textured Avatars. Master Project Report, EPFL, Lausanne, June 2000
42. **Ilić, S.**, STANKOVIĆ, T., VELICKOVIĆ, M. Library Class Hierarchy for Digital Image Processing, In *ETRAN*, pp. 188-191 (Vrnjačka Banja, Jun 2-6, 1998)
43. **Ilić, S.**, PETKOVIĆ, M. Shortest Path Graph Algorithms, In *YUINFO*, pp. 19-24 (Kopaonik, March 23-27, 1997)

References

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