

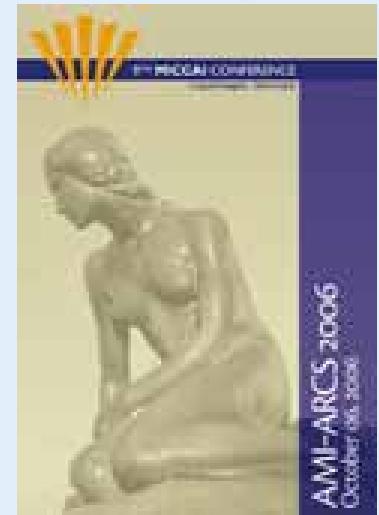
# Augmented Environments

—

## A Surgeon's Viewpoint



Sandro-Michael Heininger



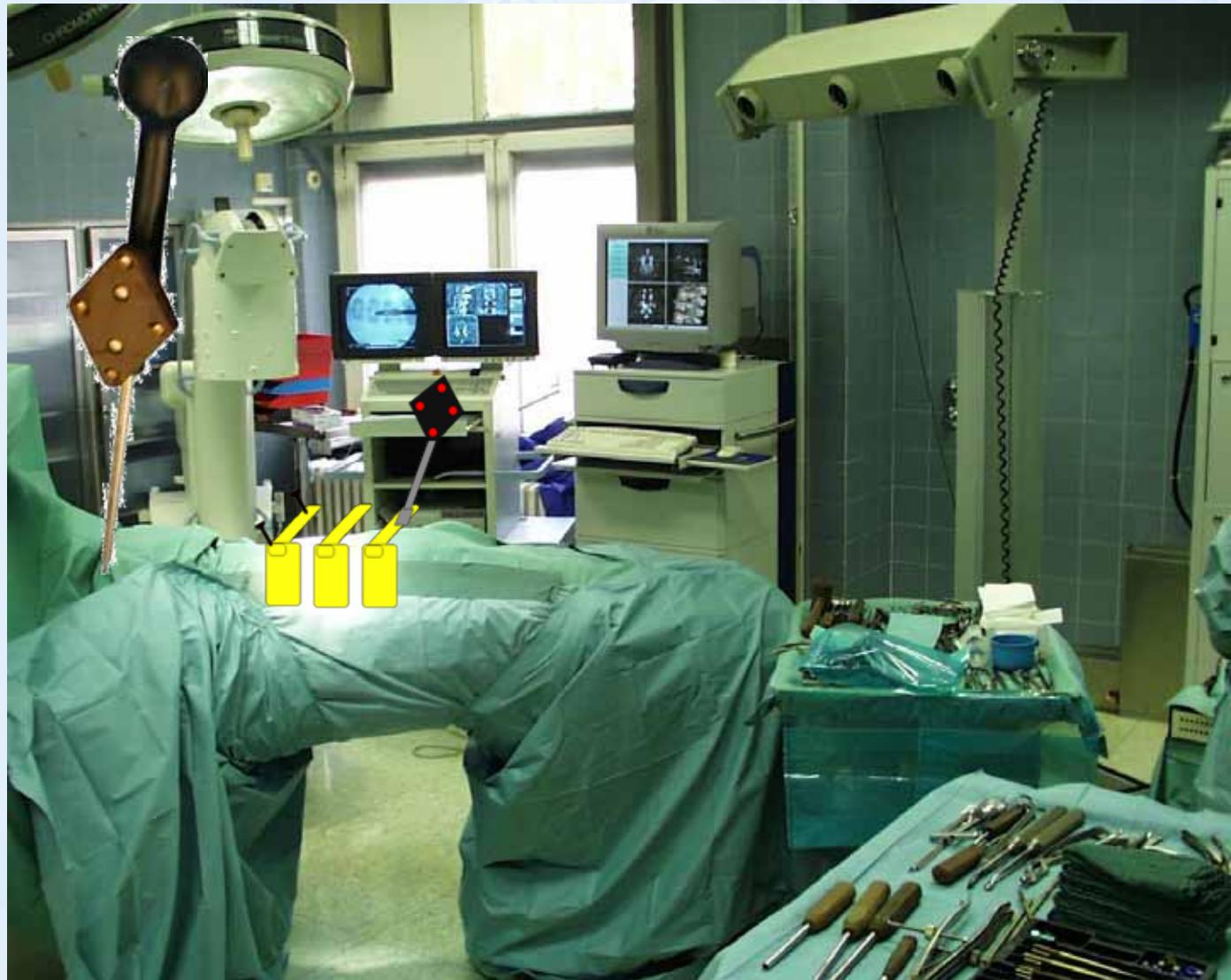
Chirurgische Klinik und Poliklinik · Innenstadt · LMU

**LMU**

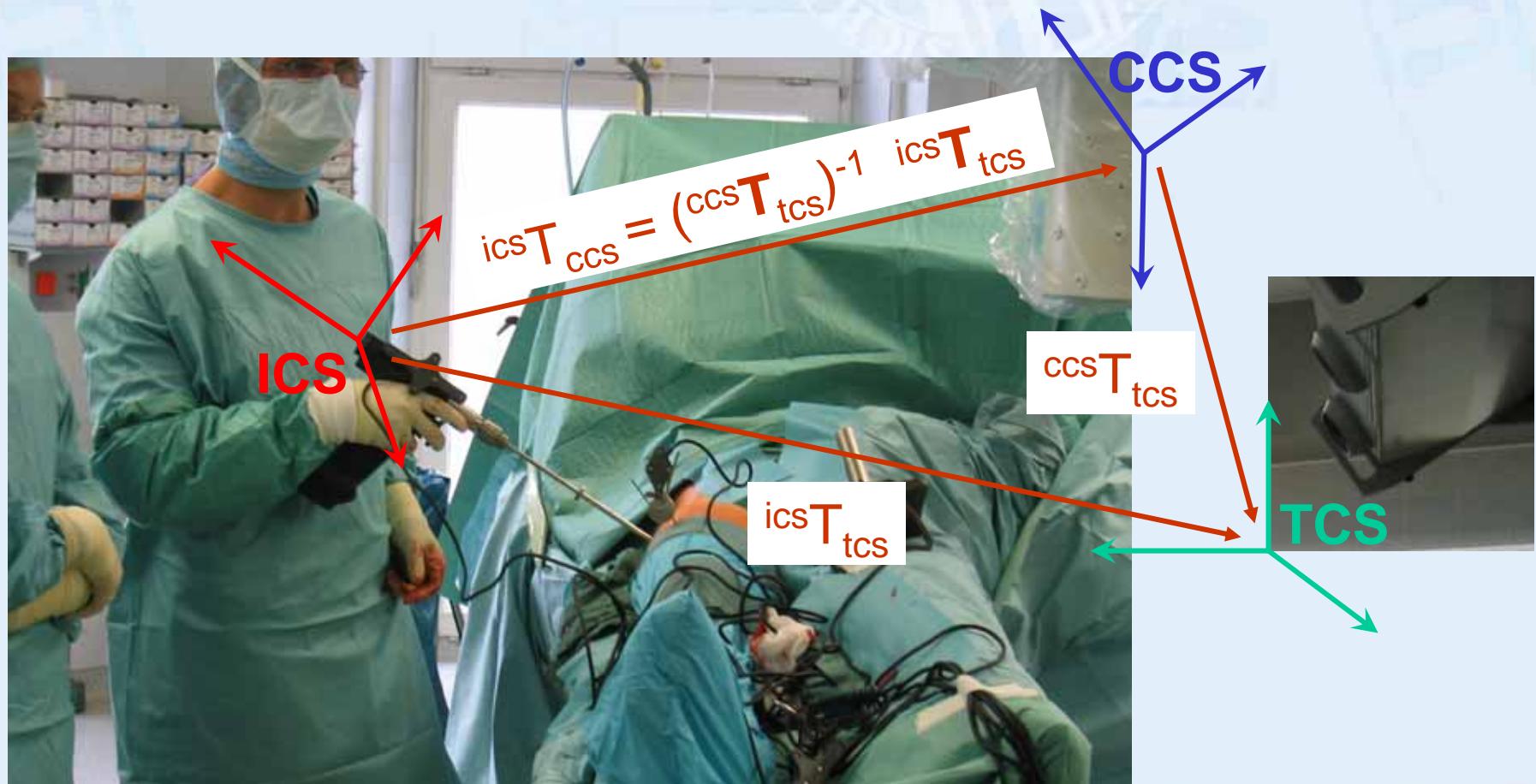


"hype cycles of innovation" by Gartner Group in:  
Technology Review - MIT's Magazine of Innovation 10/2006

since 2001 intraoperative 3D-imaging:  
Iso-C-3D + Medivision



# registrationfree surgical navigation

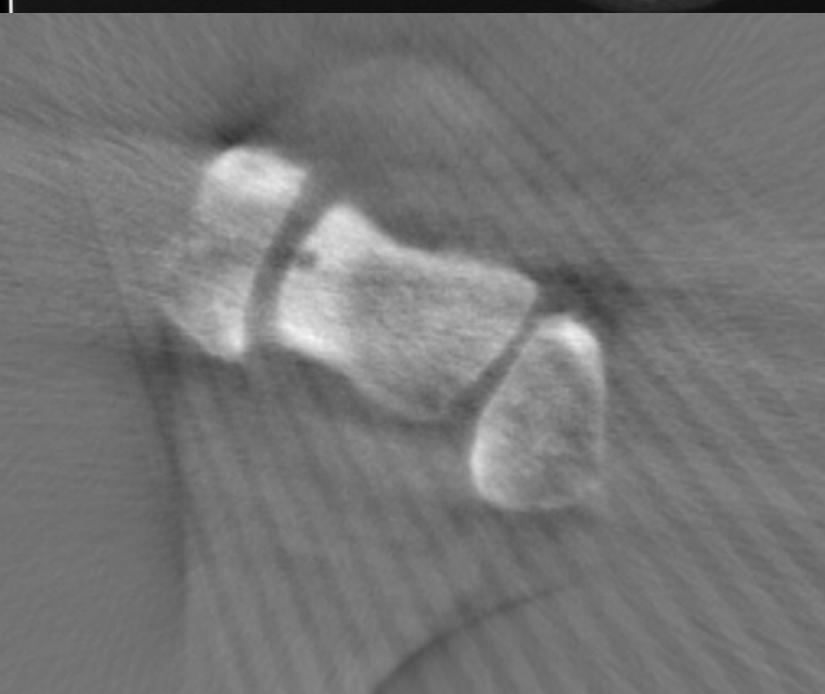


$$p_{2D} = P \cdot {}^{CCS}T_{OCS} \cdot ({}^{CCS}T_{TCS})^{-1} \cdot {}^{ICS}T_{TCS} \cdot {}^{MCS}T_{ICS} \cdot p_{3D}$$

IMAGE 40  
SER 1-4

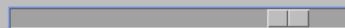


16:22  
09-MAR-2004  
IMAGE 10  
SER 1-2



**Patient Data****Planning Section****Alignment****Tools****Verification****Realtime****Guidance**

Brightness

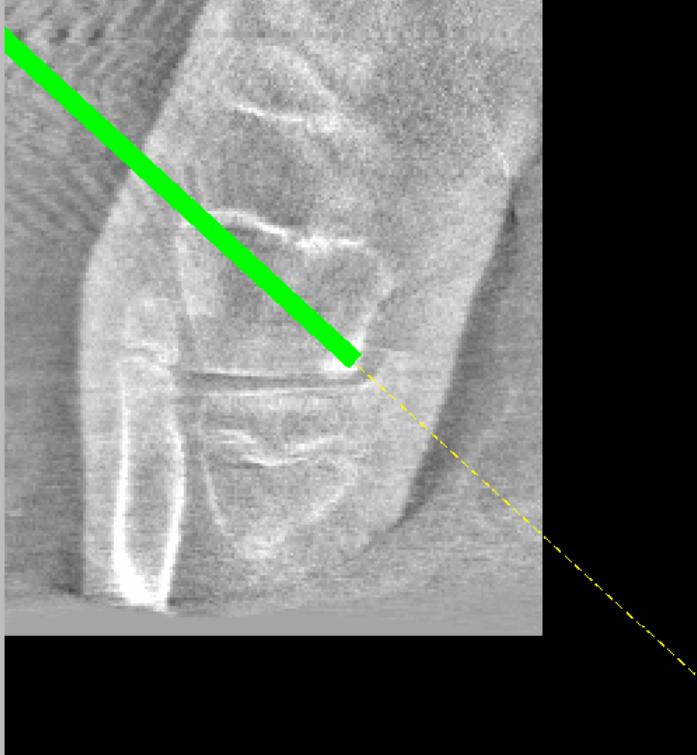
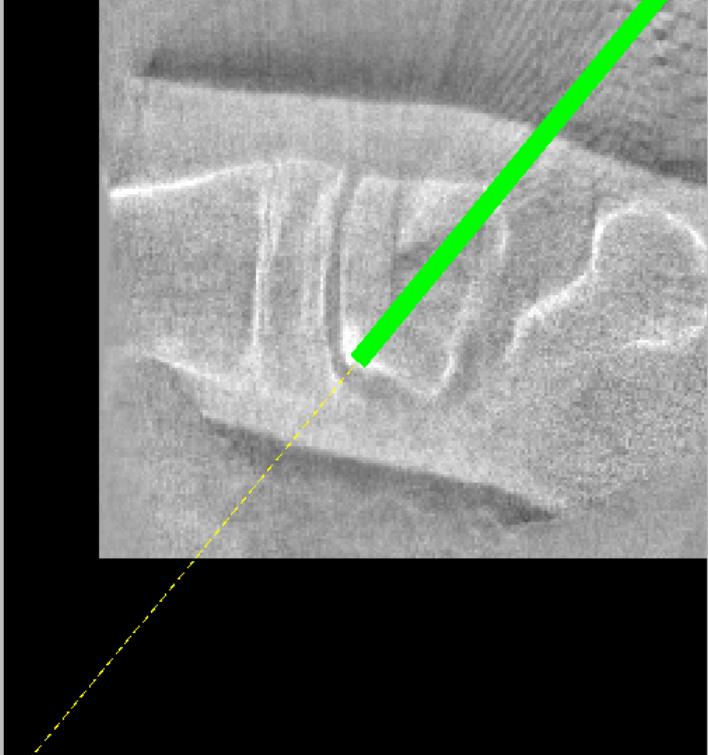
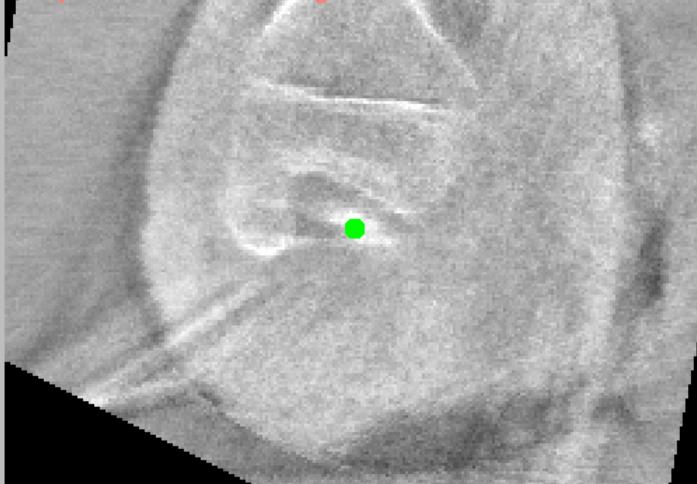
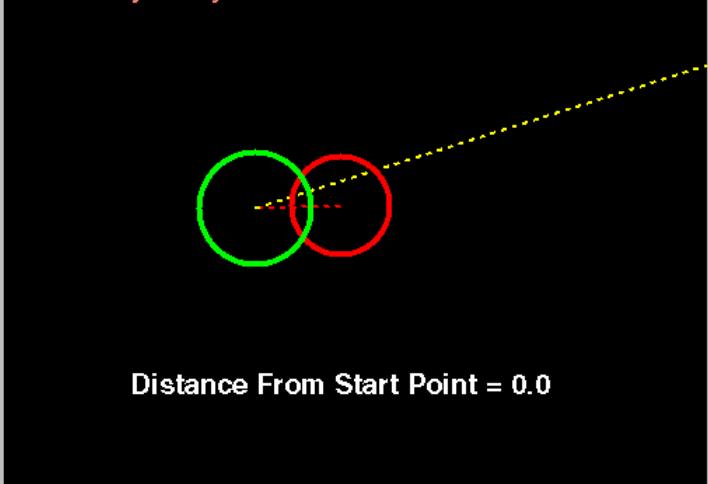


Contrast

 Manual Matching**Trajectory Set**

---

---

**Axial Tool Alignment****Sagittal Tool Alignment****Perpendicular Tool Alignment****Axial Trajectory View**

Distance From Start Point = 0.0

Current Tool: Drill



PAPIN,ROBERT  
4171938

1 7.08.2004 14:52:06 1  
C 019740 04 1

LMU Chirurgie Innenstadt

PAPIN,ROBERT  
1978.12.23  
2004.08.17  
15:00:00  
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SE:3

R  
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9  
4

L  
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S100

I164

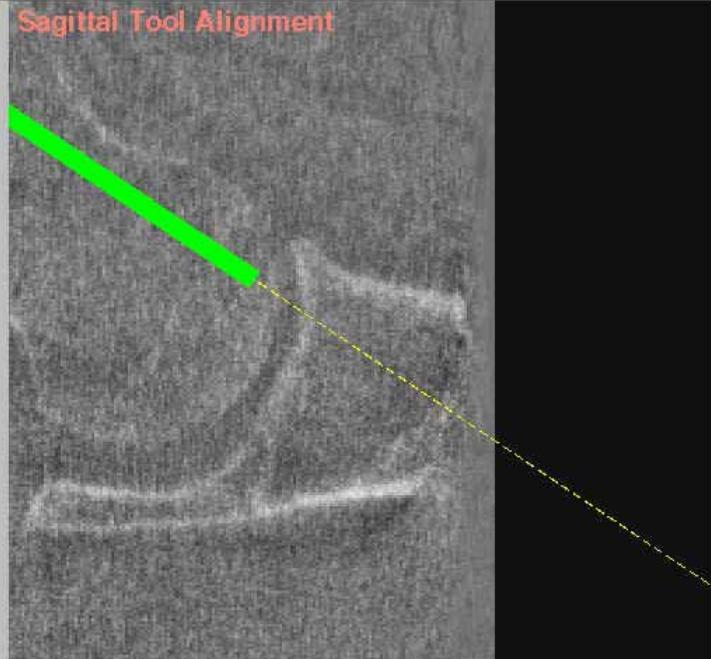
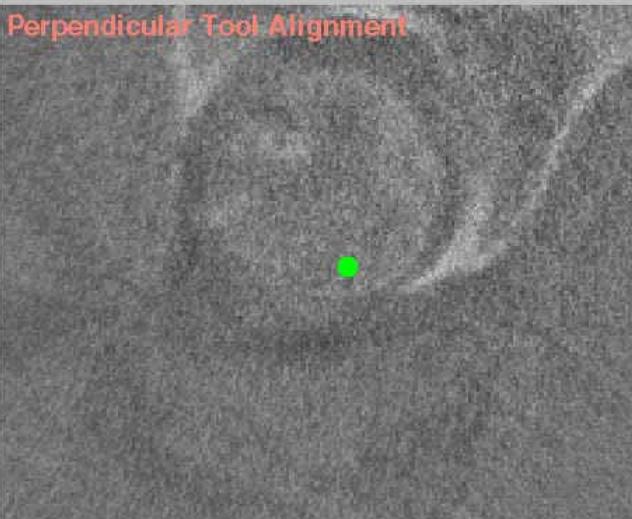
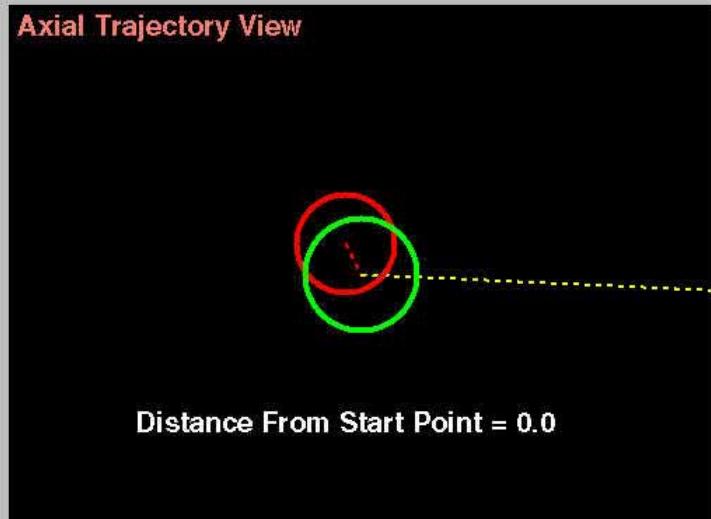
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-8.908  
FLIP:180  
CONTRAST:  
TR:560  
TE:14

T1 cor chir.  
W 1144 : L 529

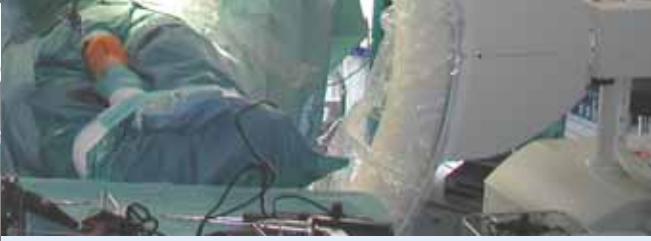
**Patient Data****Planning Section****Alignment****Tools****Verification****Realtime****Guidance**

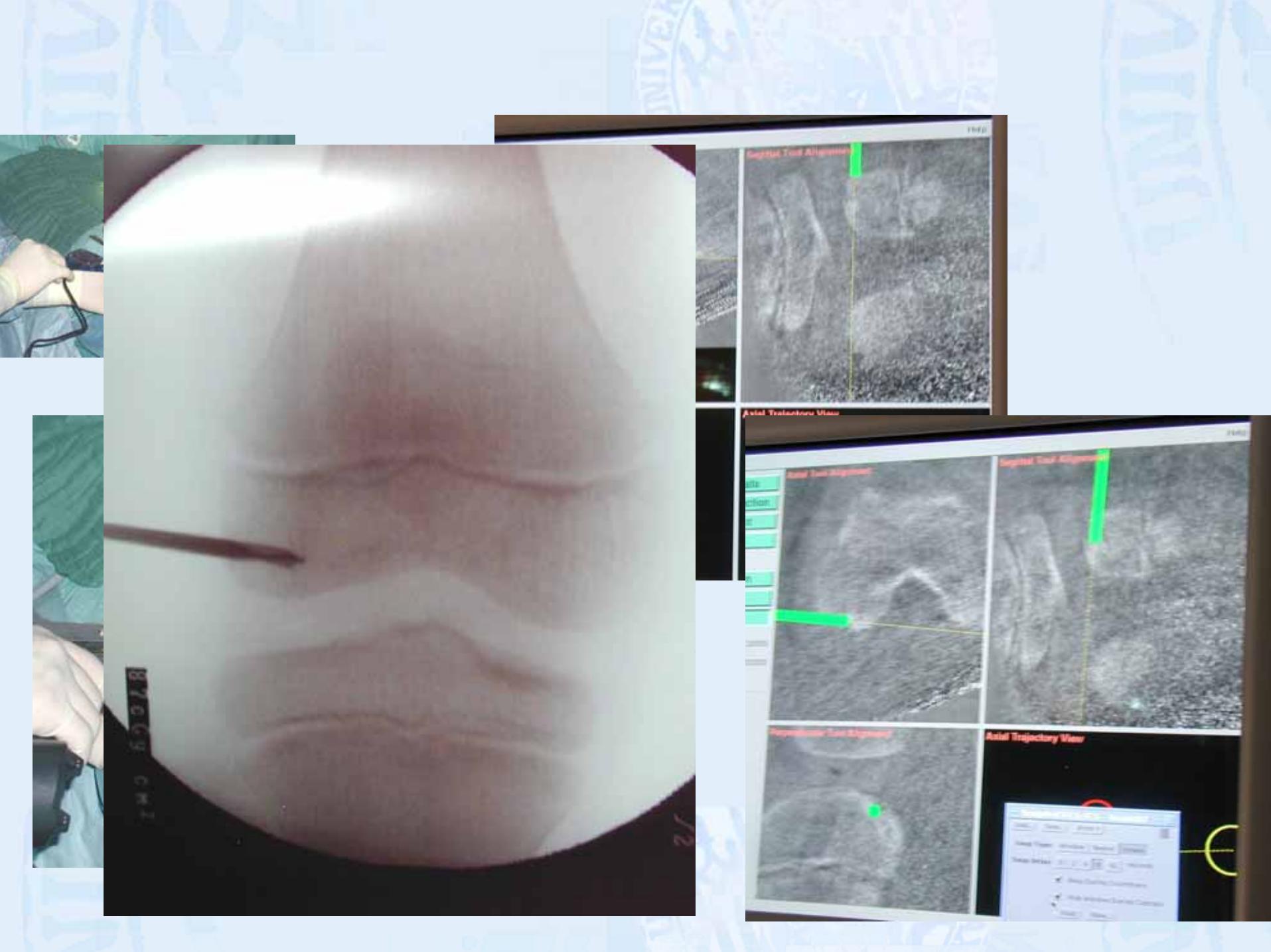
Brightness

Contrast

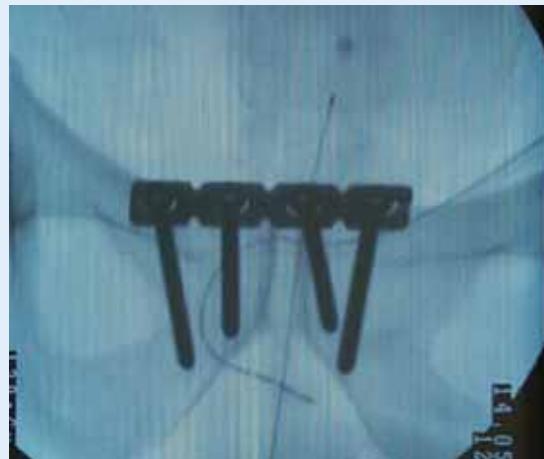
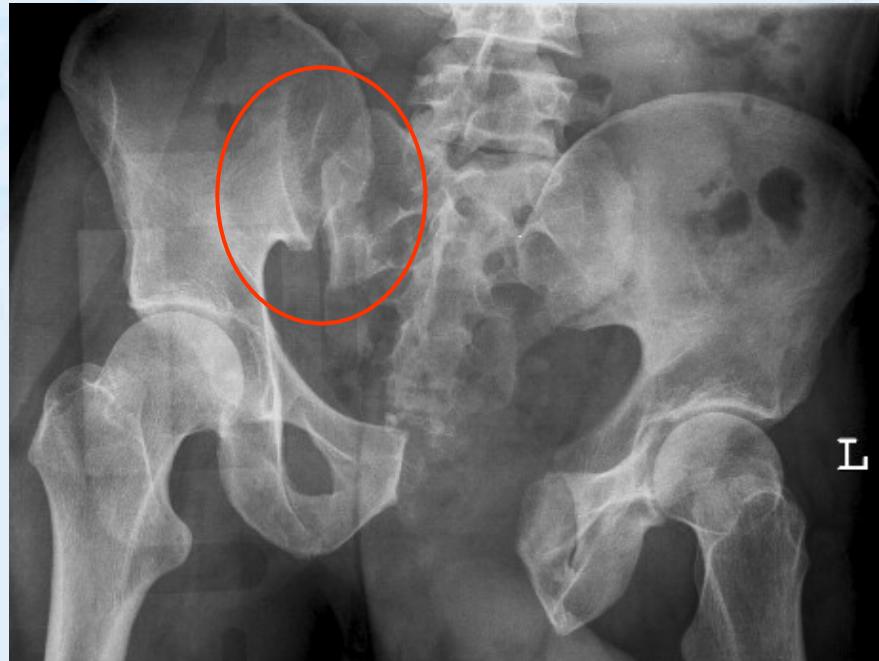
 Manual Matching**Trajectory Set****Axial Tool Alignment****Sagittal Tool Alignment****Perpendicular Tool Alignment****Axial Trajectory View**



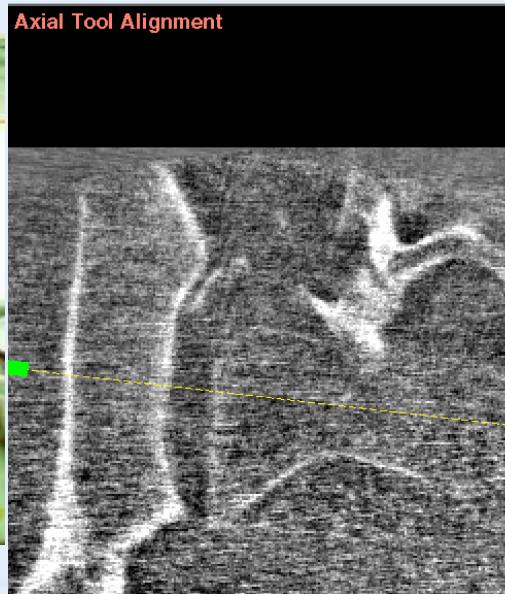




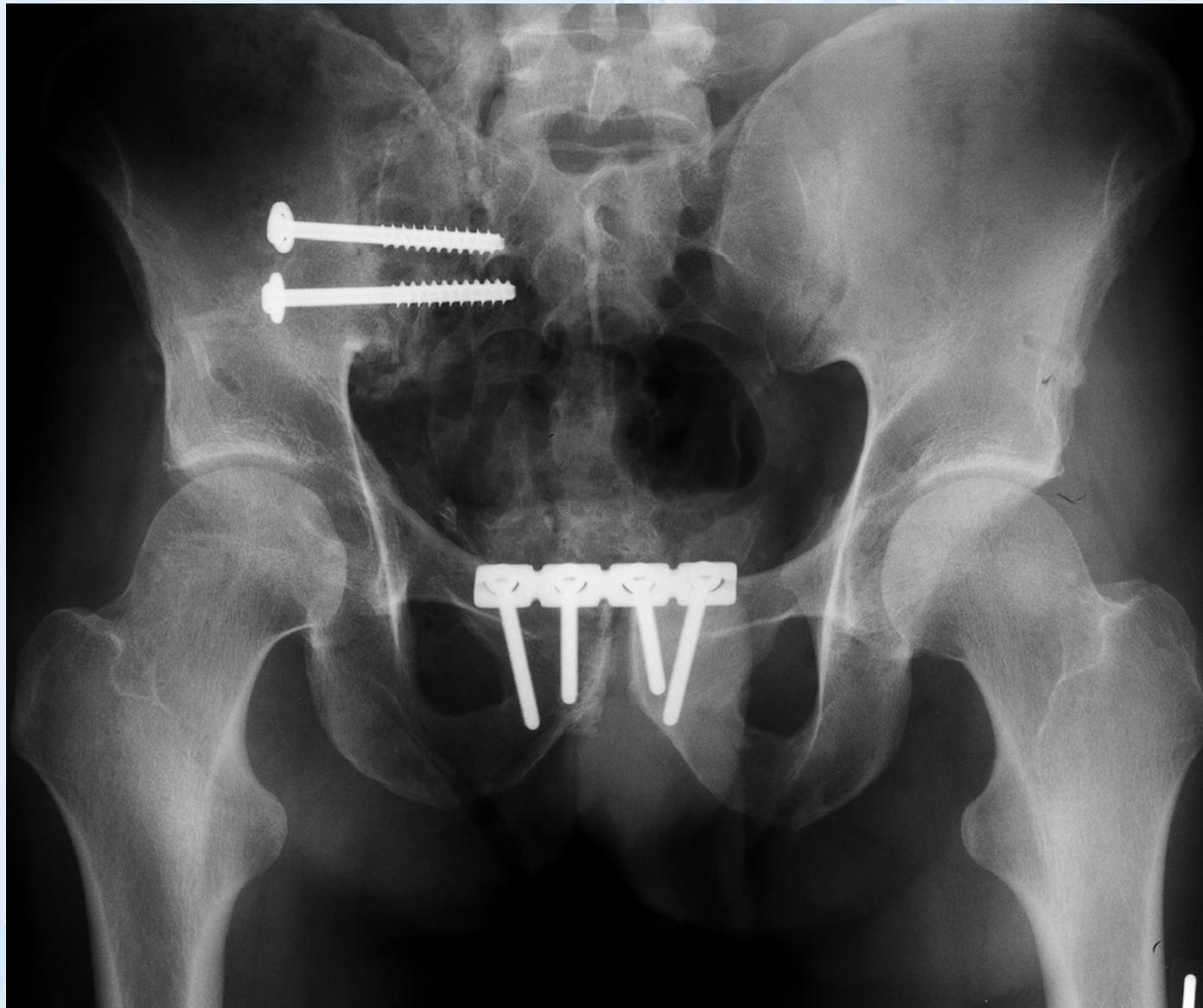
## 3 D Navigation: SI Screws



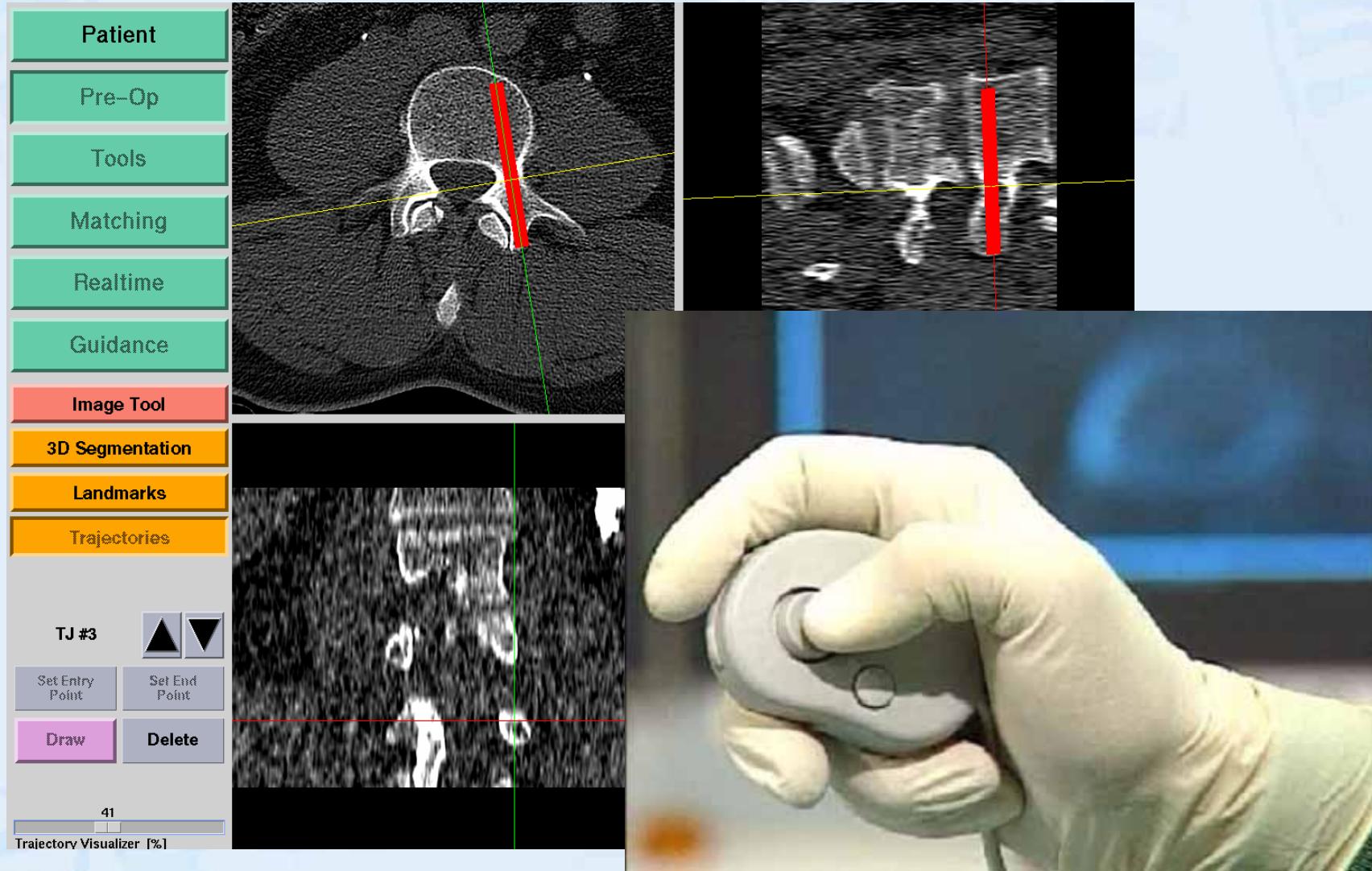
# 3 D Navigation: SI Screws



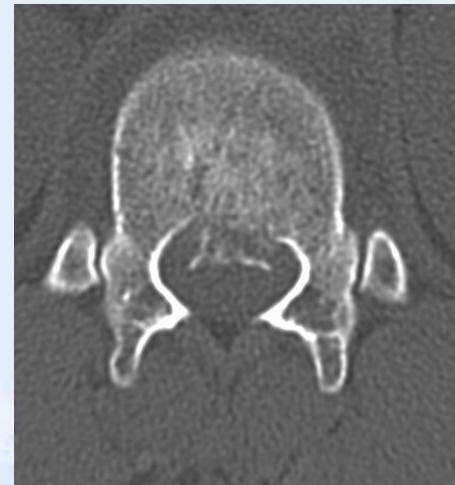
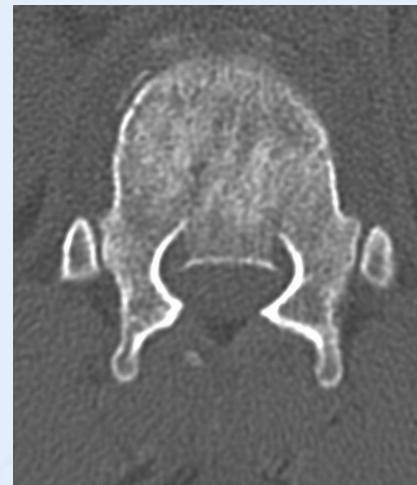
## 3 D Navigation: SI Screws



# User interfaces



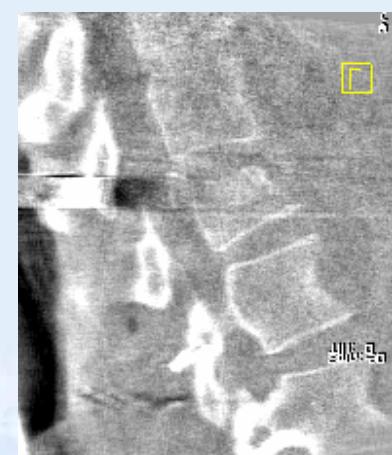
## T12 burst fracture



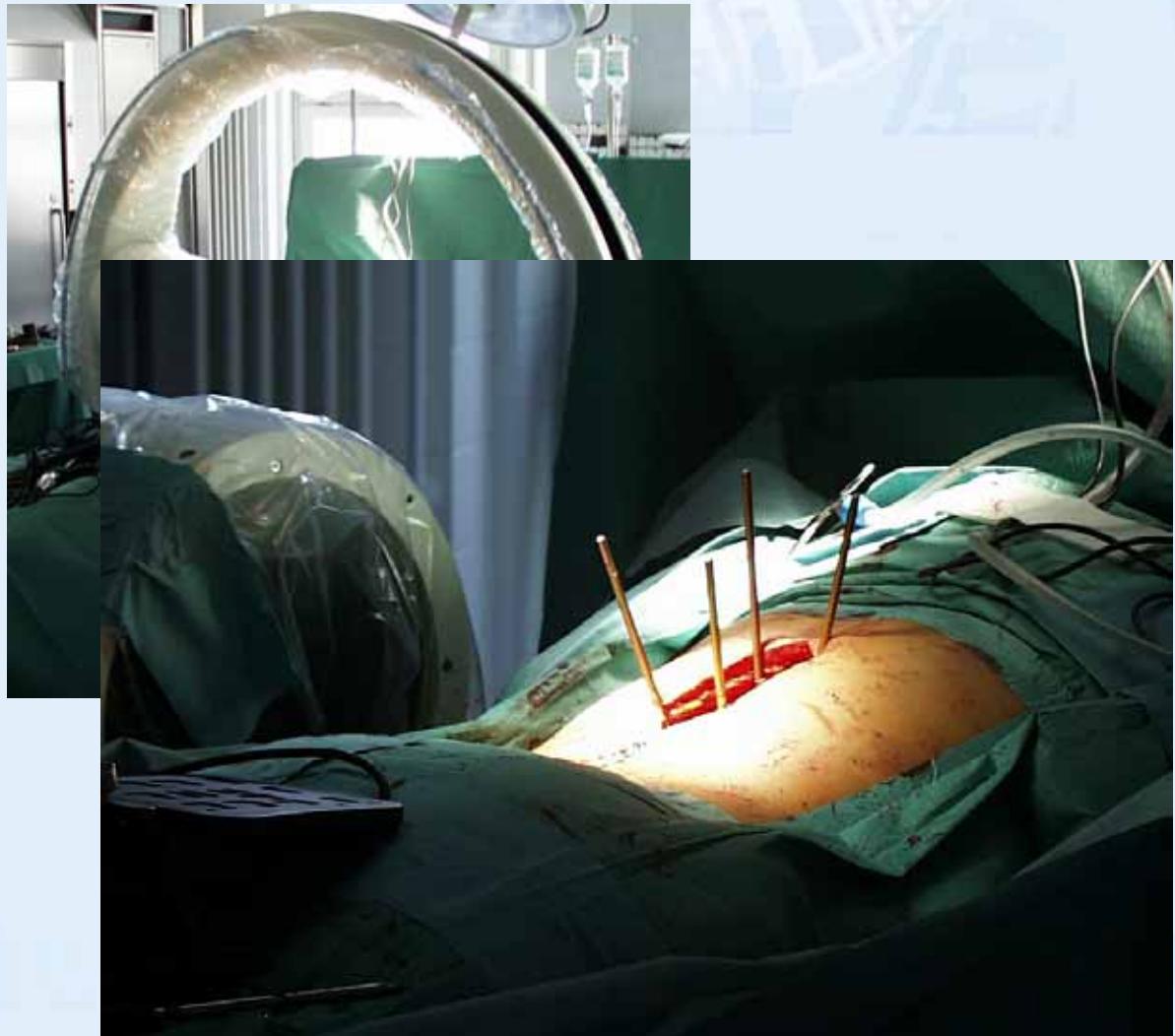
CMO 26 w



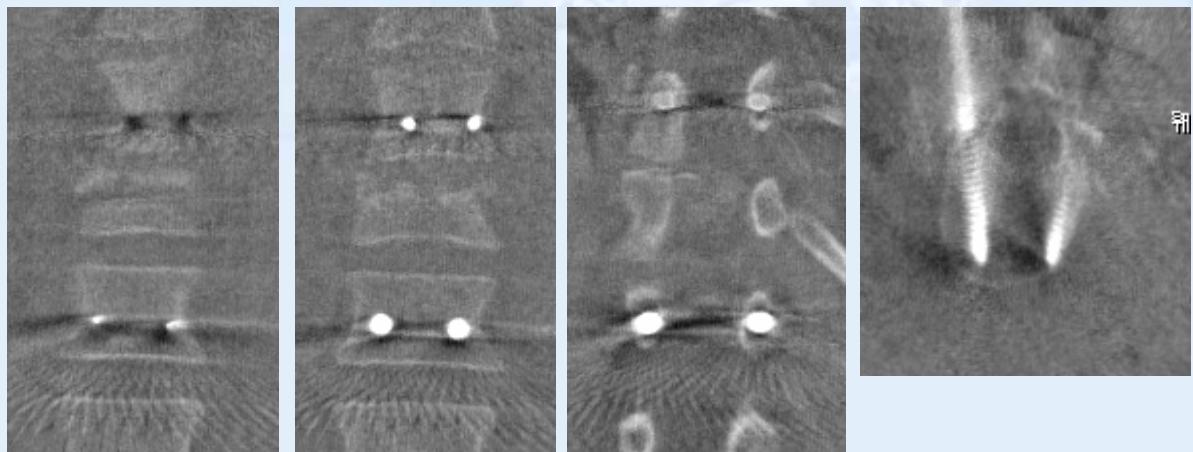
CMO 26 w



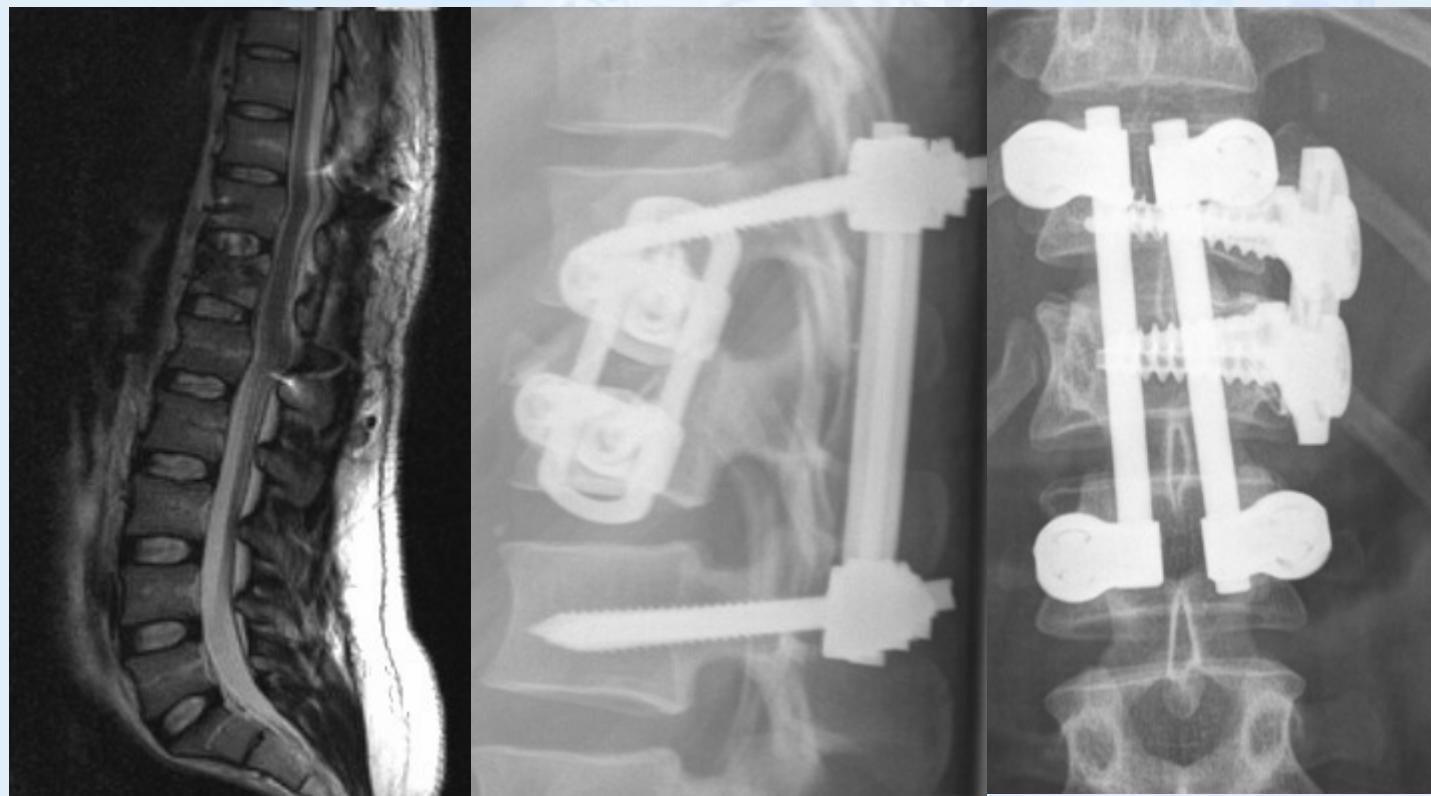
CMO 26 w



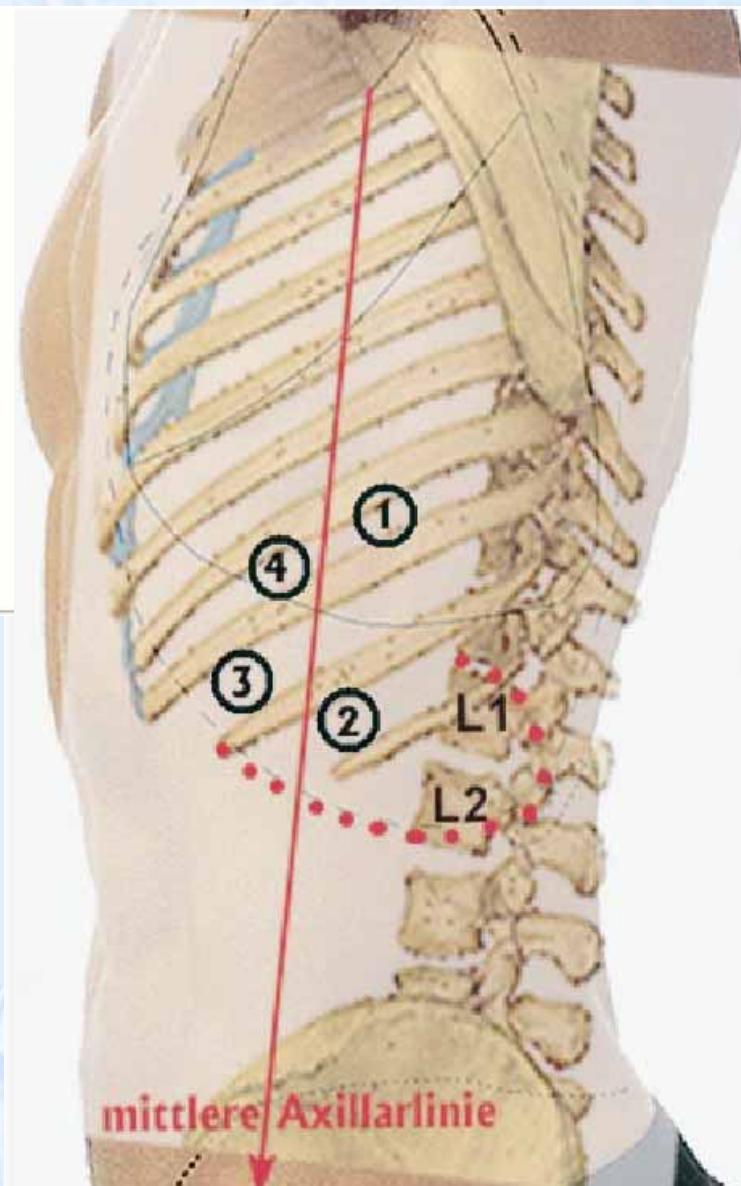
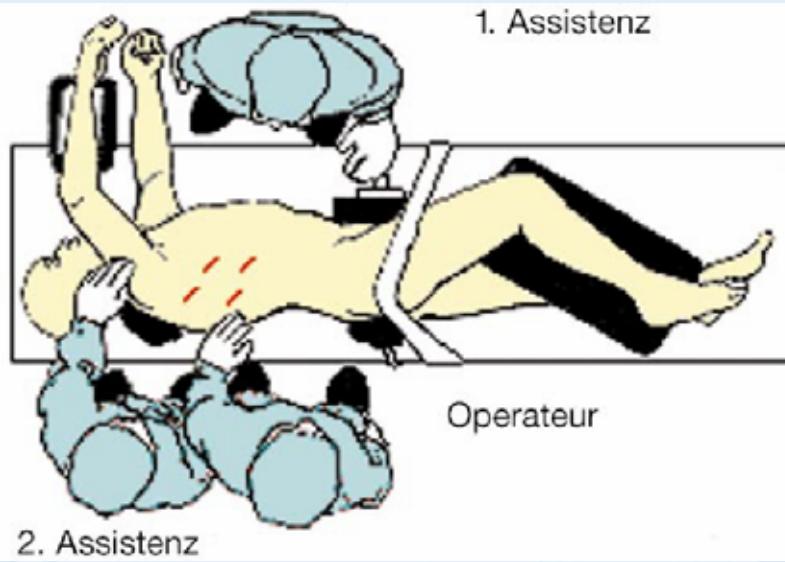
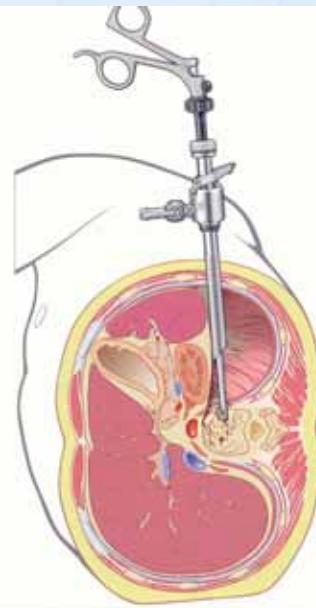
CMO 26 w



CMO 26 w

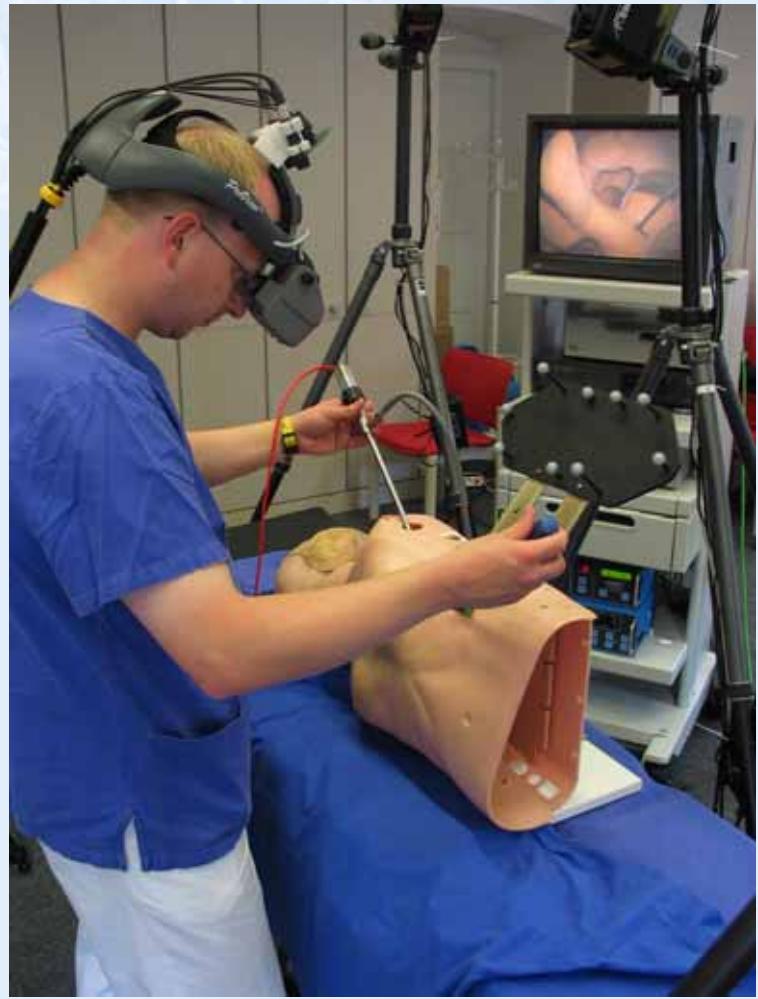


CMO 26 w





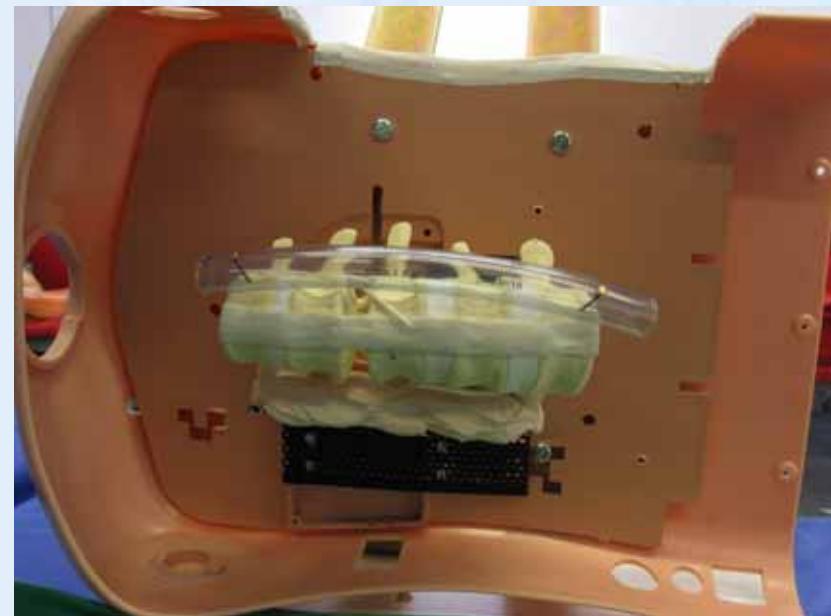
OR  
integration

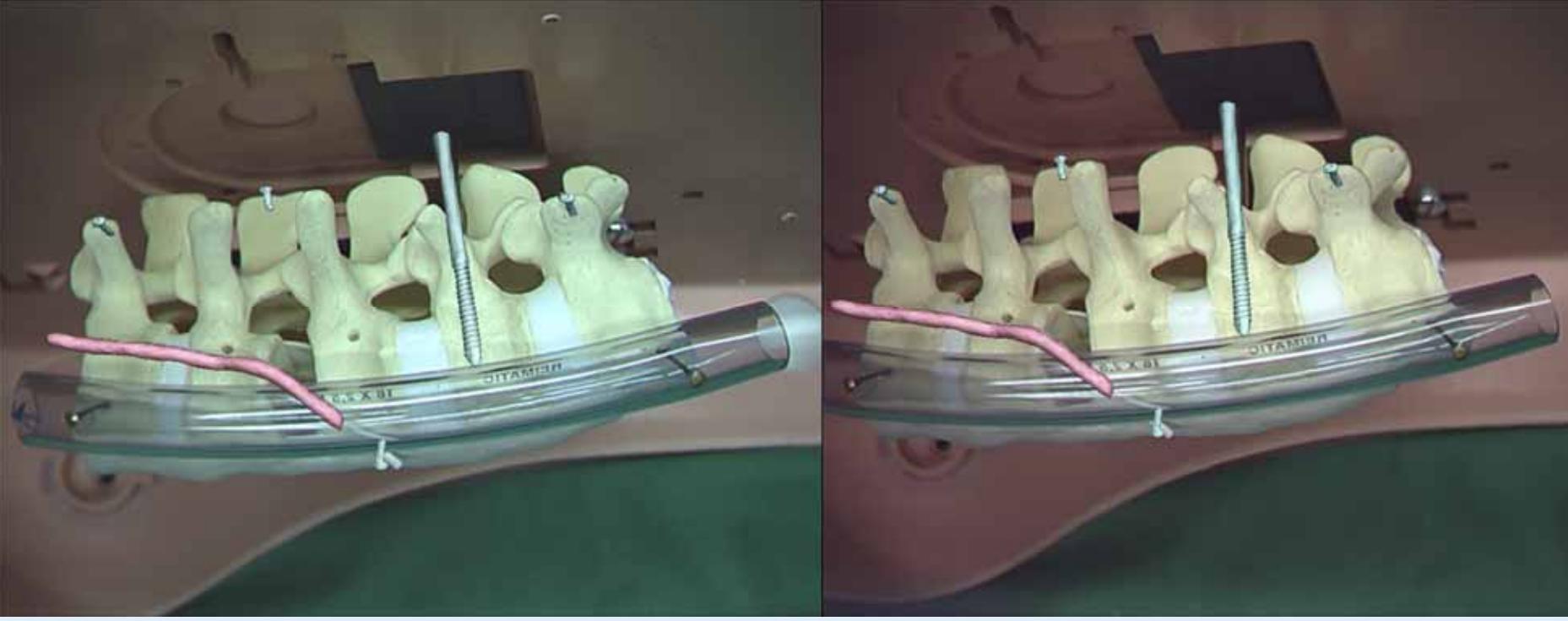


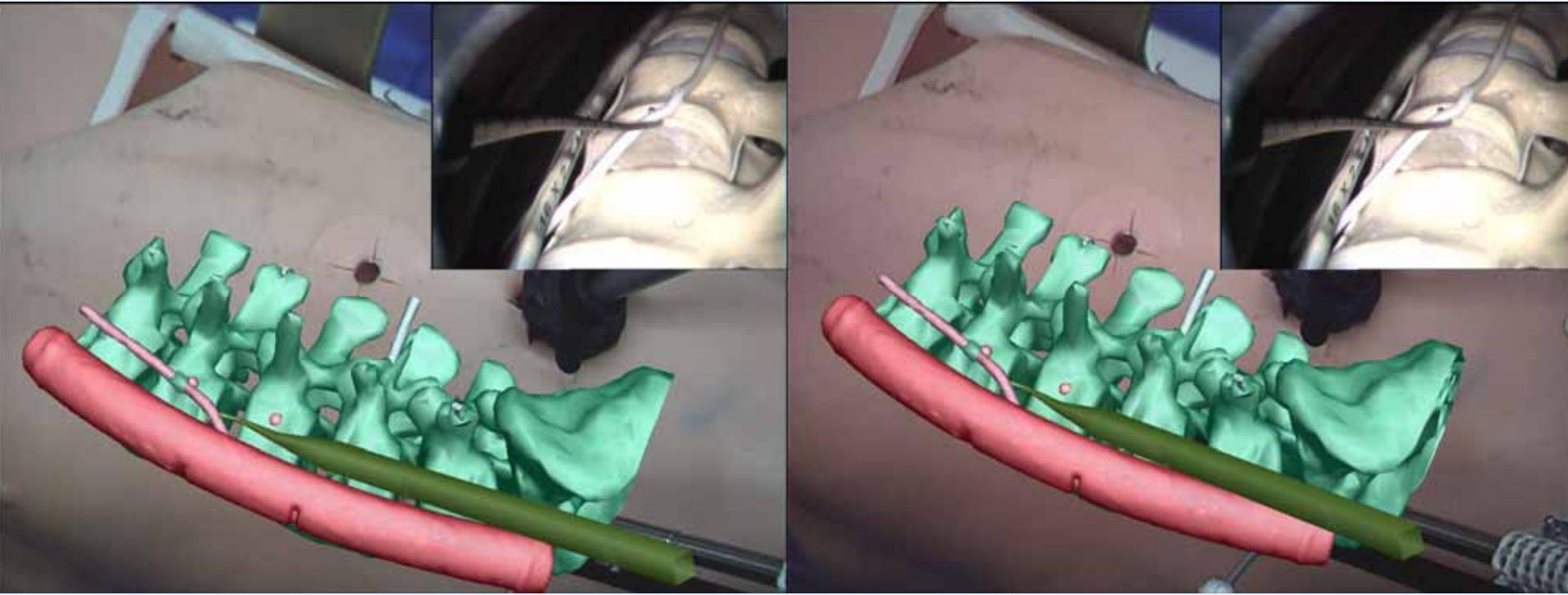
RAMP-System 08/2003:

Frank Sauer, Sebastian Vogt, Ali Khamene *SCR*

# building spine phantoms

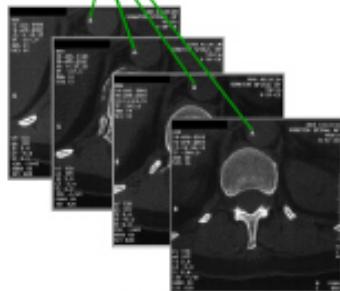
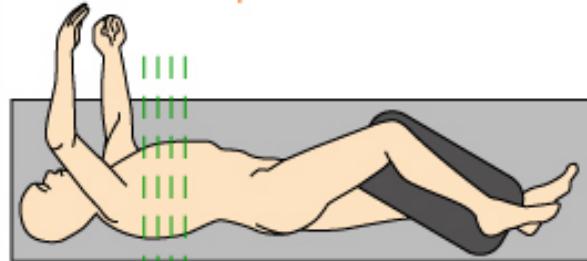








### Präoperative Daten

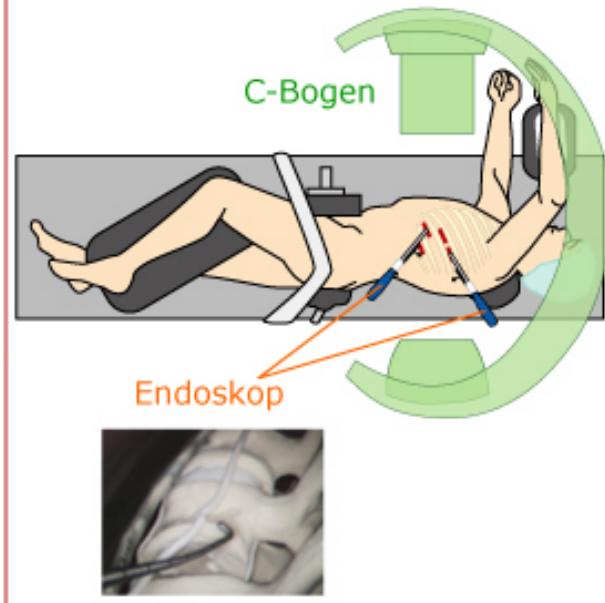


2D → 3D

### Natürliche Sicht

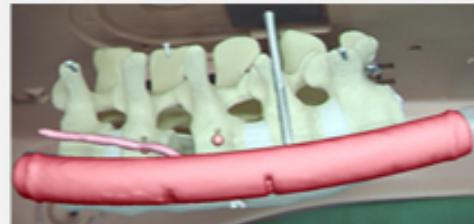


### Intraoperative Bilddaten

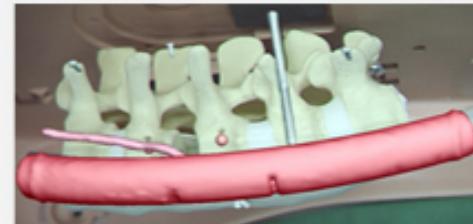


lagerrichtige 3D-Datenfusion und Ausgabe auf dem **HMD**

für linkes Auge



für rechtes Auge



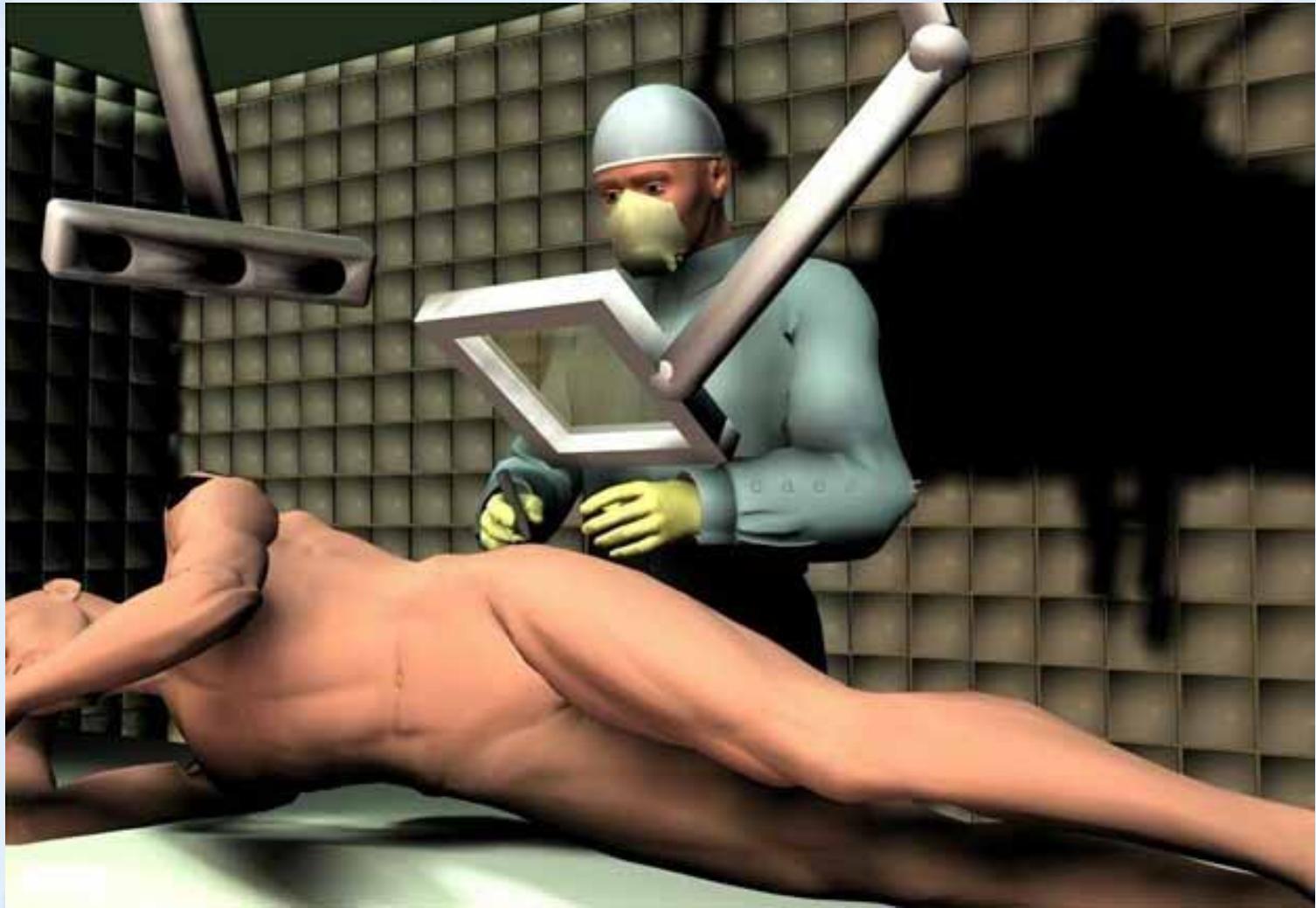
# Augmented reality und in-situ-visualisation



Bayerische  
Forschungsstiftung

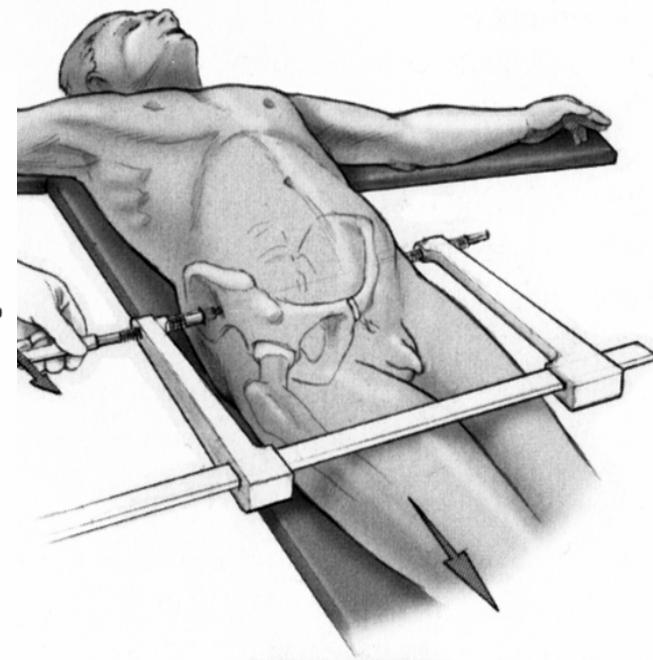
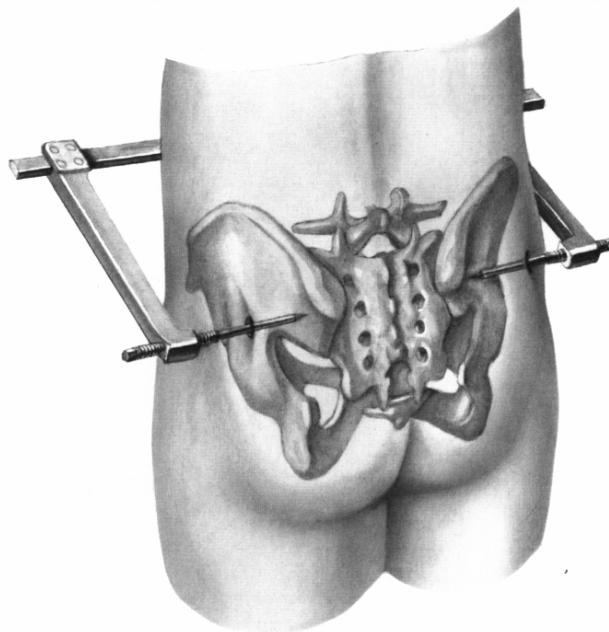
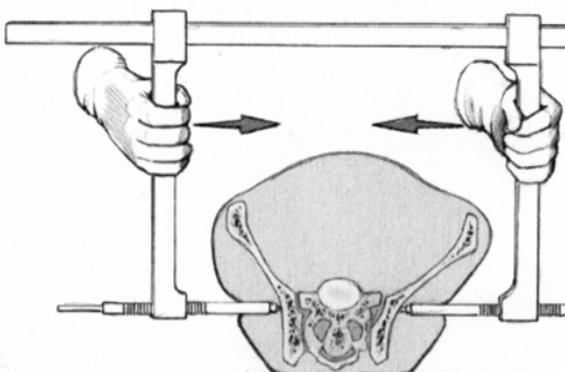


NARVIS 09/2004 – 09/2007



A. DiGioia, B. Jaramaz

## cadaver studies: pelvic c-clamp

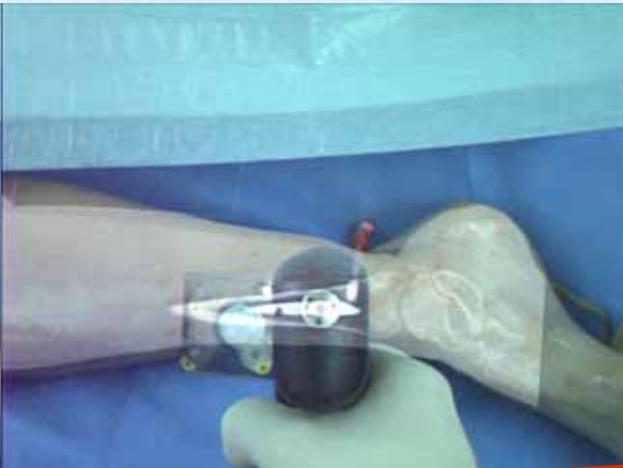
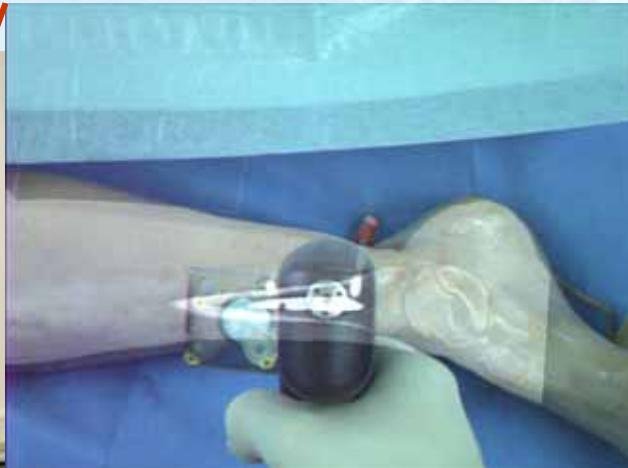
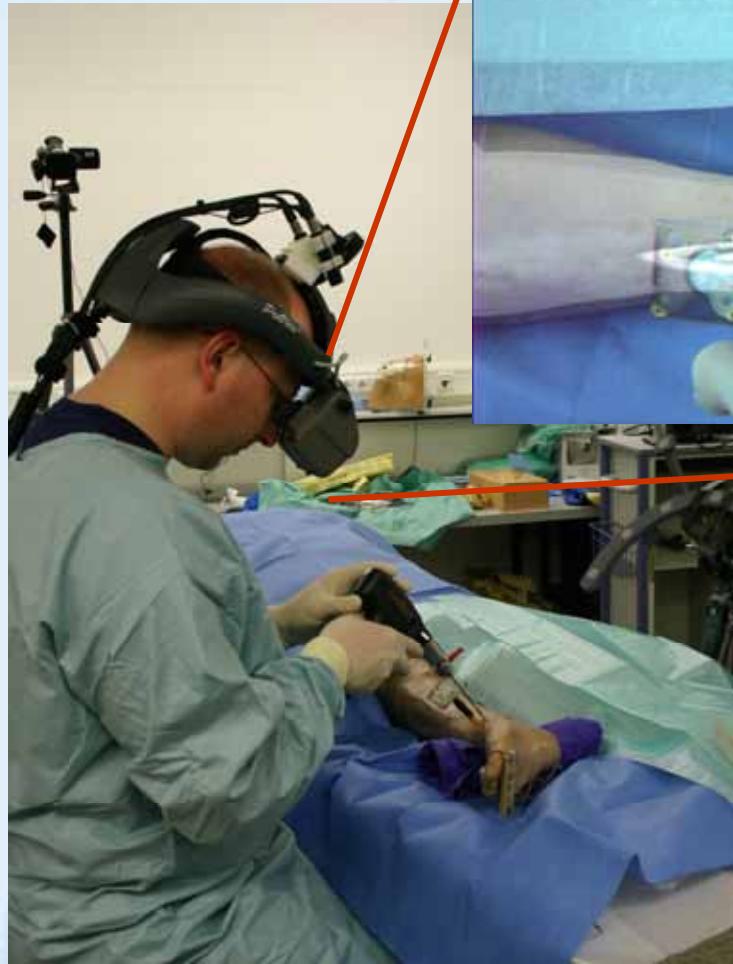


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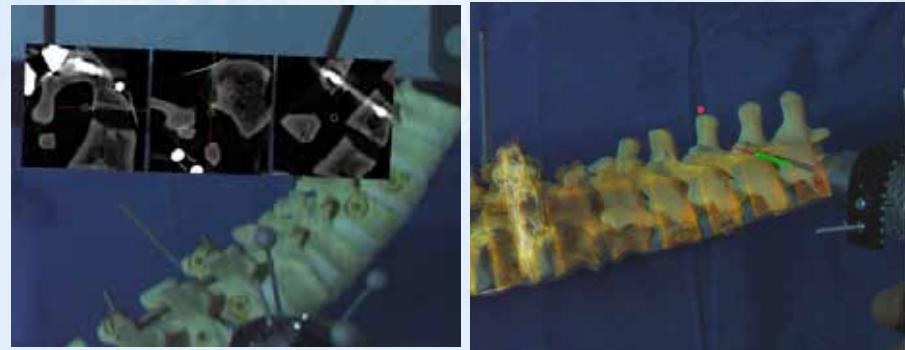
## cadaver studies: pelvic c-clamp



J. Traub, S. Philipp, N. Navab, S.M. Heining: EVI - Easy visualization interface for trauma surgery;  
ISMAR 2005, Vienna 2005

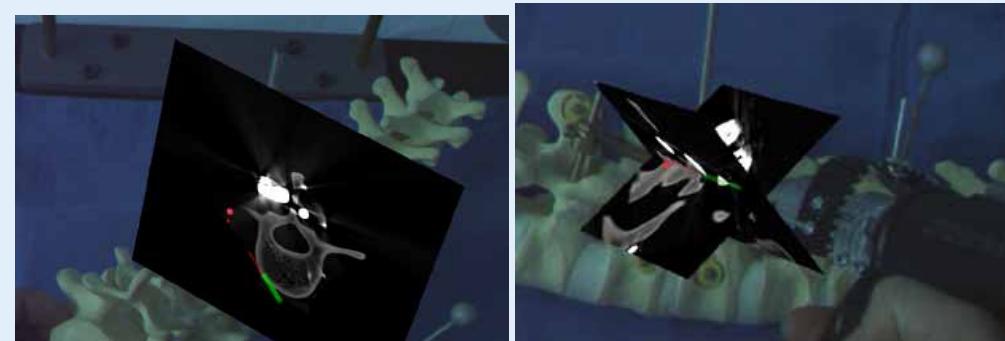


# Lessons Learned: Improvements in Visualization Modes



NAV  
Standard Navigation

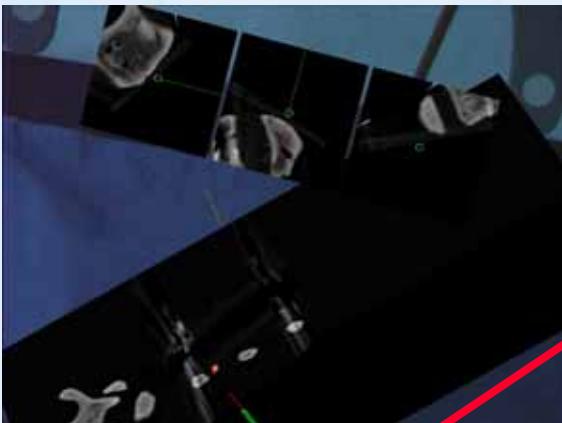
VOLREN  
Volume Rendering



ASV  
Aligned Slice View

IOV  
Instrument Orthoslice View

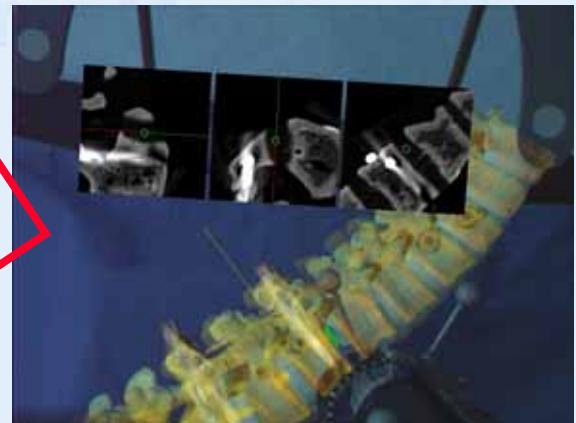
## Hybrid Visualization Modes



NAV + IOV  
Slice Navigation and  
Instrument Orthoslice View



NAV+ASV  
Slice Navigation and  
Aligned Slice View



NAV+VOLREN  
Slice Navigation and  
Volume Rendering

adequate  
visualization

# LCP® DHHS™ Dynamic Helical Hip System



338.044 LCP DHHS Angle Guide-Variable

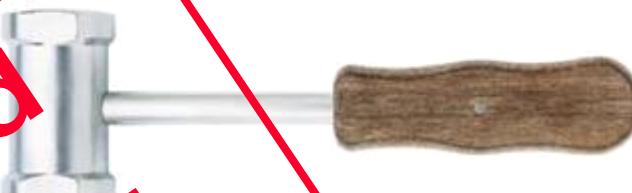


338.329 Calibrated Depth Gauge for  
LCP DHHS Angle Guide-Variable



338.332 Contoured Reamer 60 mm

900.723 2.5 mm Threaded Guide Wire Spade Point 230 mm



399.43 Hammer 700 Grams

338.345 LCP DHHS Coupling Screw 324 mm



338.342 LCP DHHS Key Inserter Shaft

338.346 LCP DHHS Inserter Shaft



338.347 LCP DHHS Key Impactor

338.341 LCP DHHS Inserter Guide



338.348 LCP DHHS Impactor Cap

## LCP DHHS Instruments for Implantation



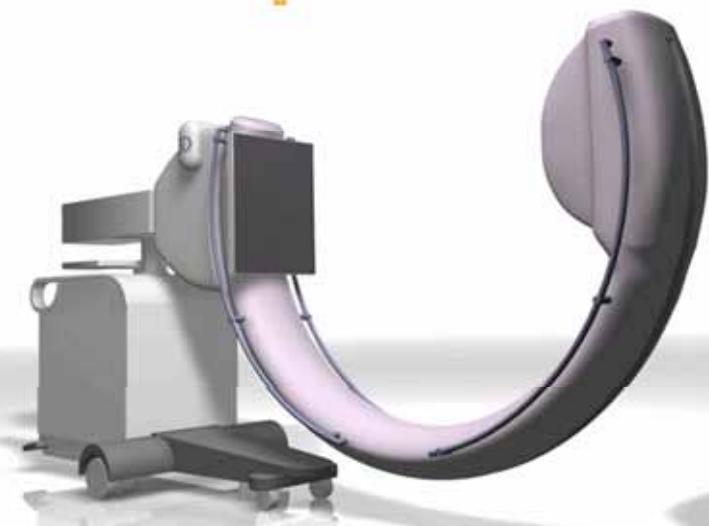
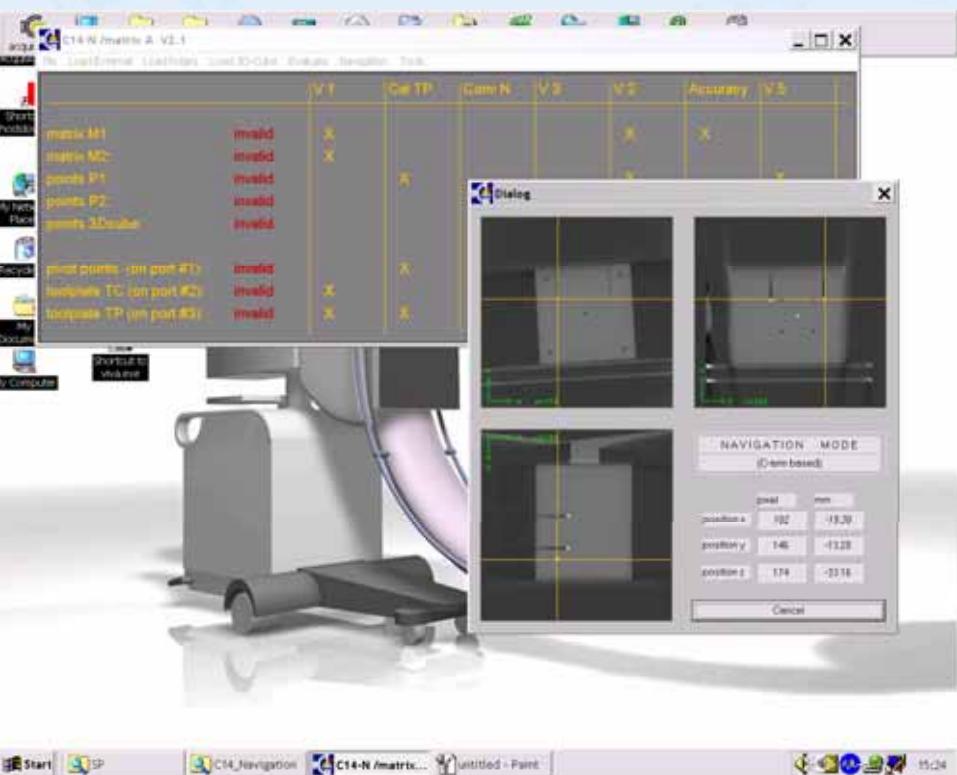
DETROIT | ANN ARBOR | FLORIDA | NEW YORK

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# System Alpha



3D scan sequence

Online initialization

2D fluoro images

3D start position

Parameters...

3D stop position

Images / time:

200p, 64s, 3.1fps

FD / mode type:

4030CB / 2x1DGR

Image dimensions:

1024\*1536\*2, 2x2

Analog gain:

g=1 (Saturation: 14000)

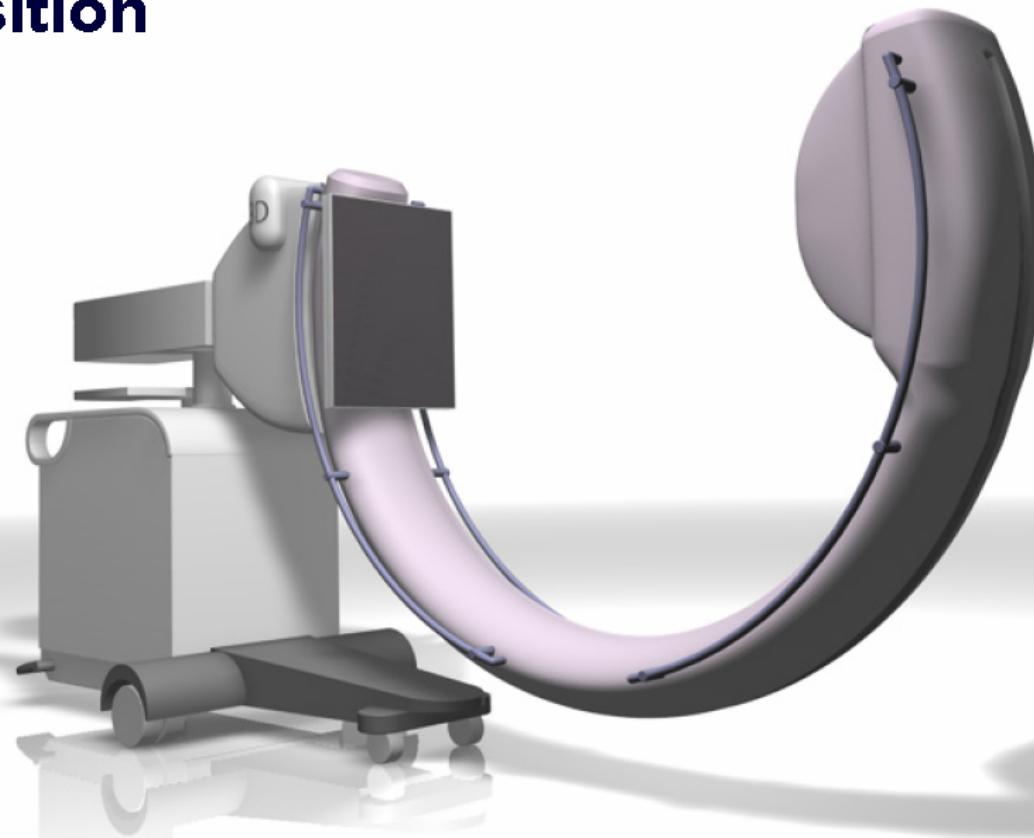
PaxScan mode info:

3 2x1 15 fps Gn1 0p5/4p DGR

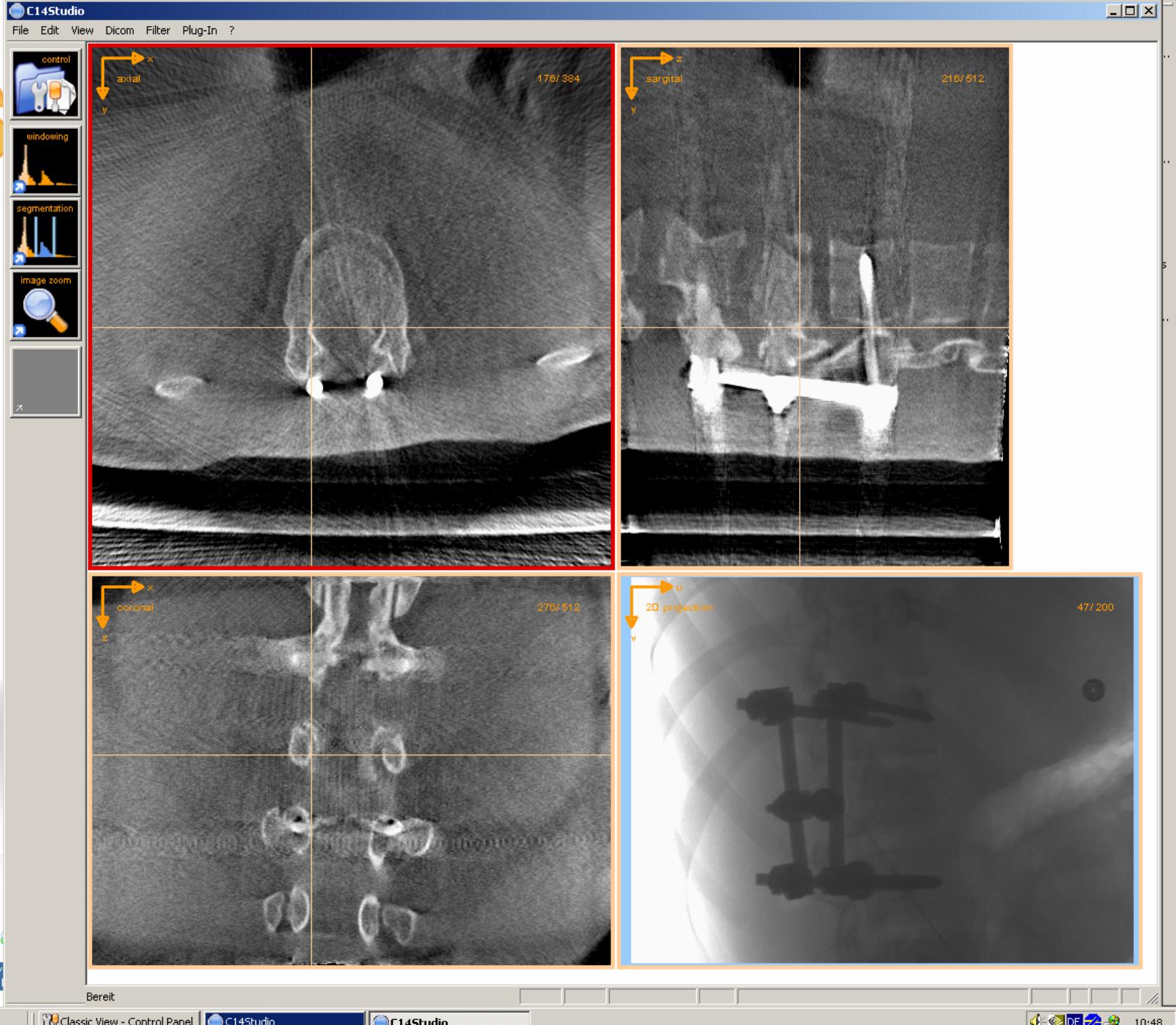
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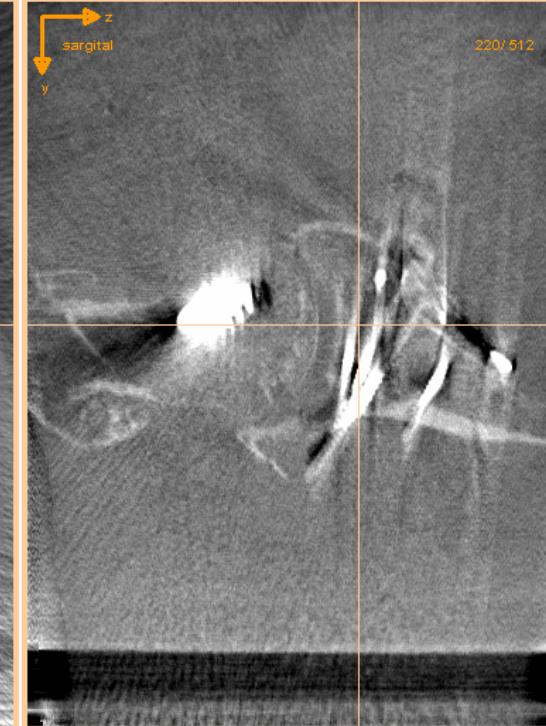
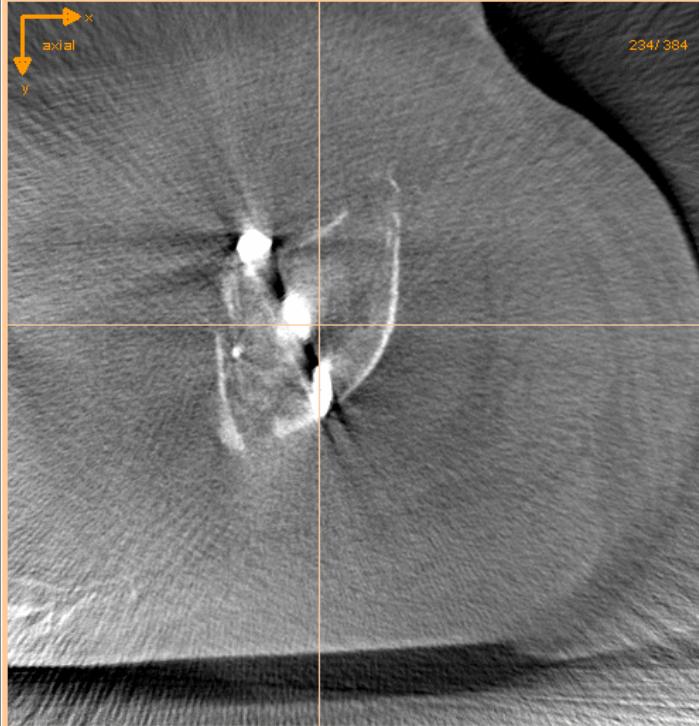
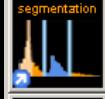
# SIEMENS

C14 - prototype system  
Acquisition

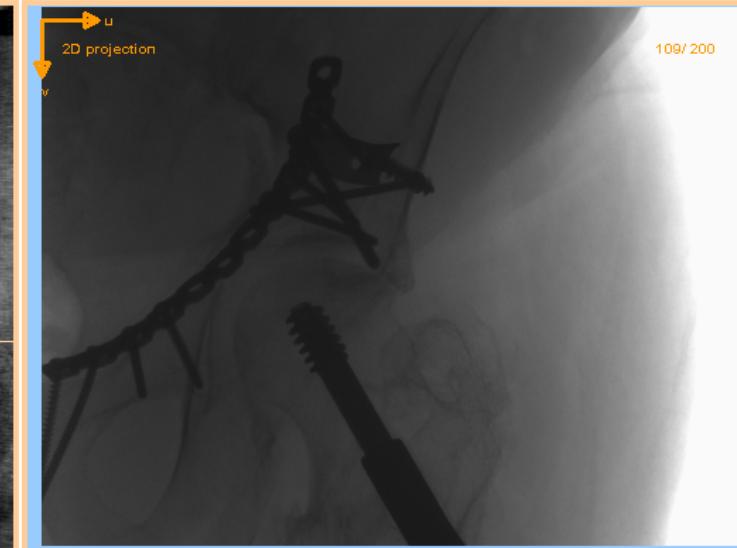
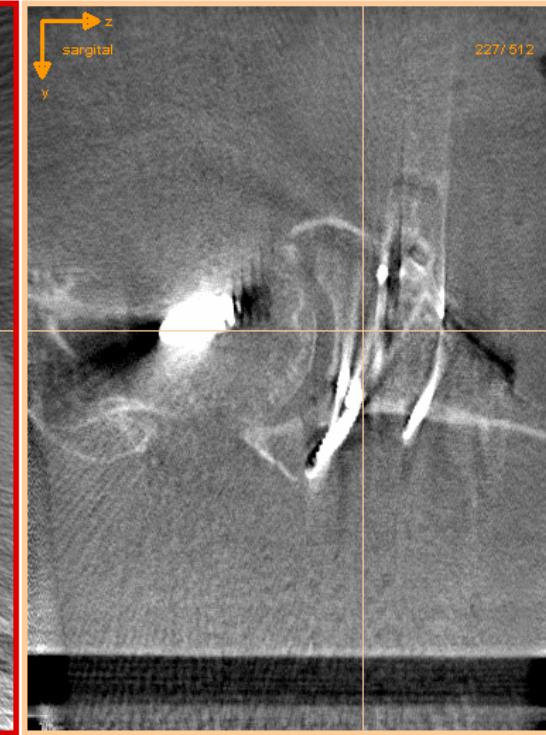
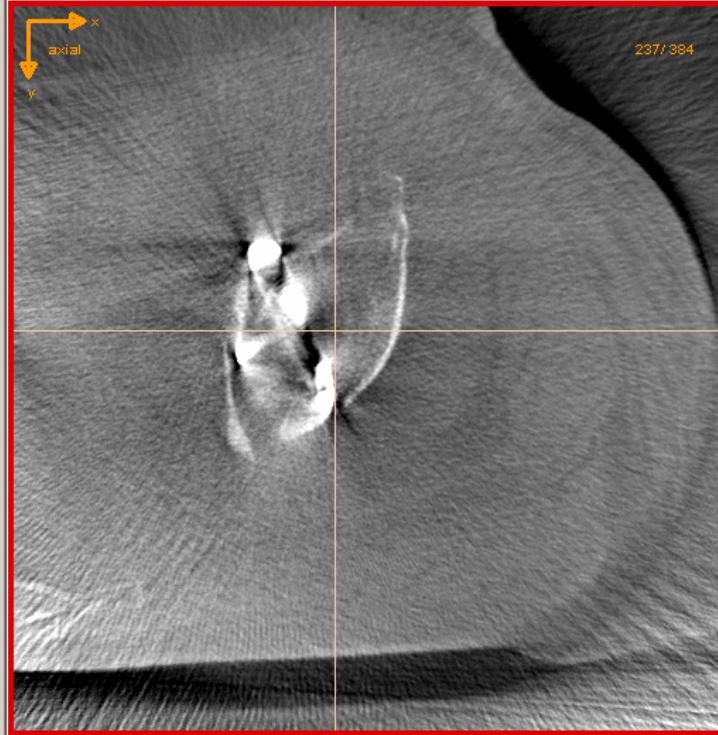
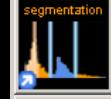


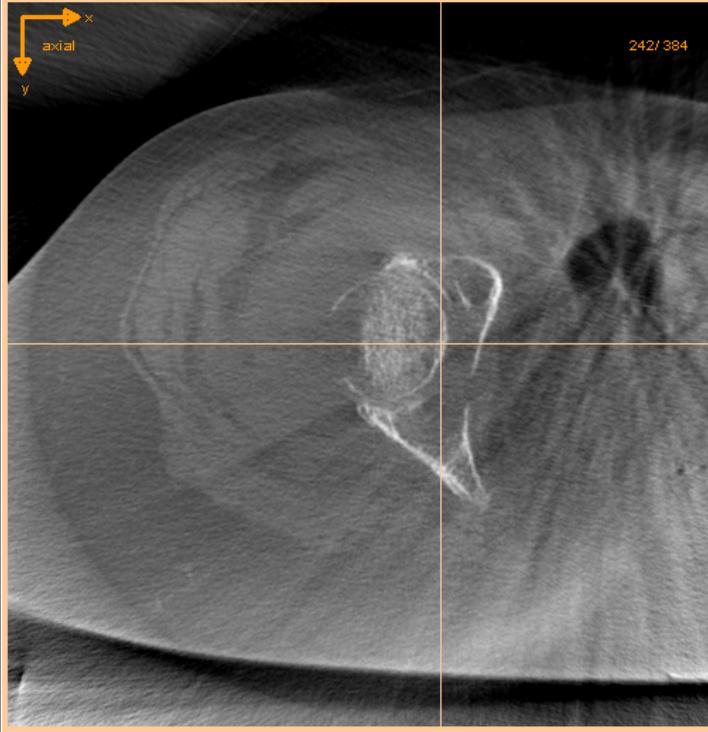
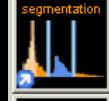




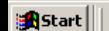


Bereit





Bereit

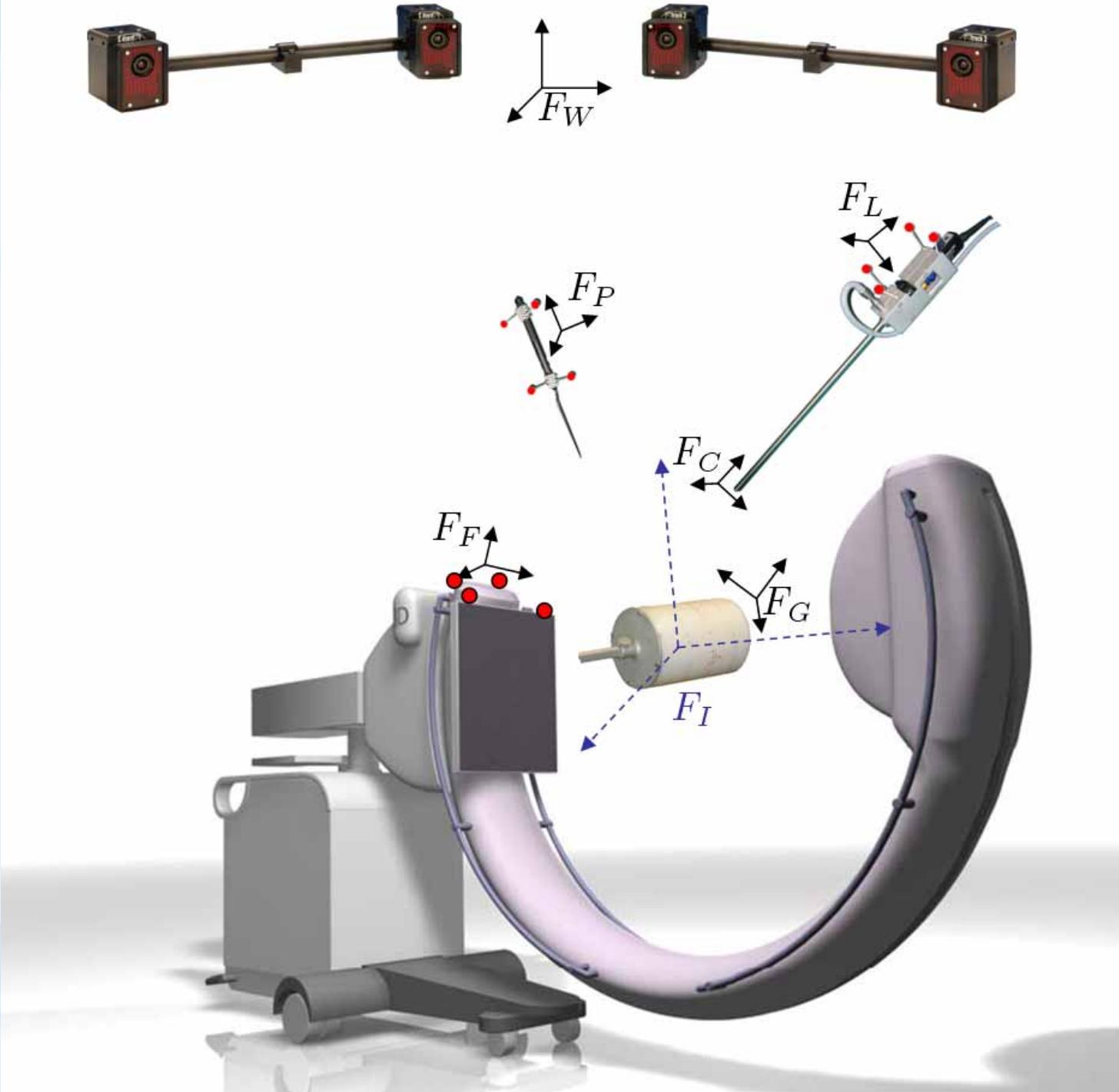


C14Studio

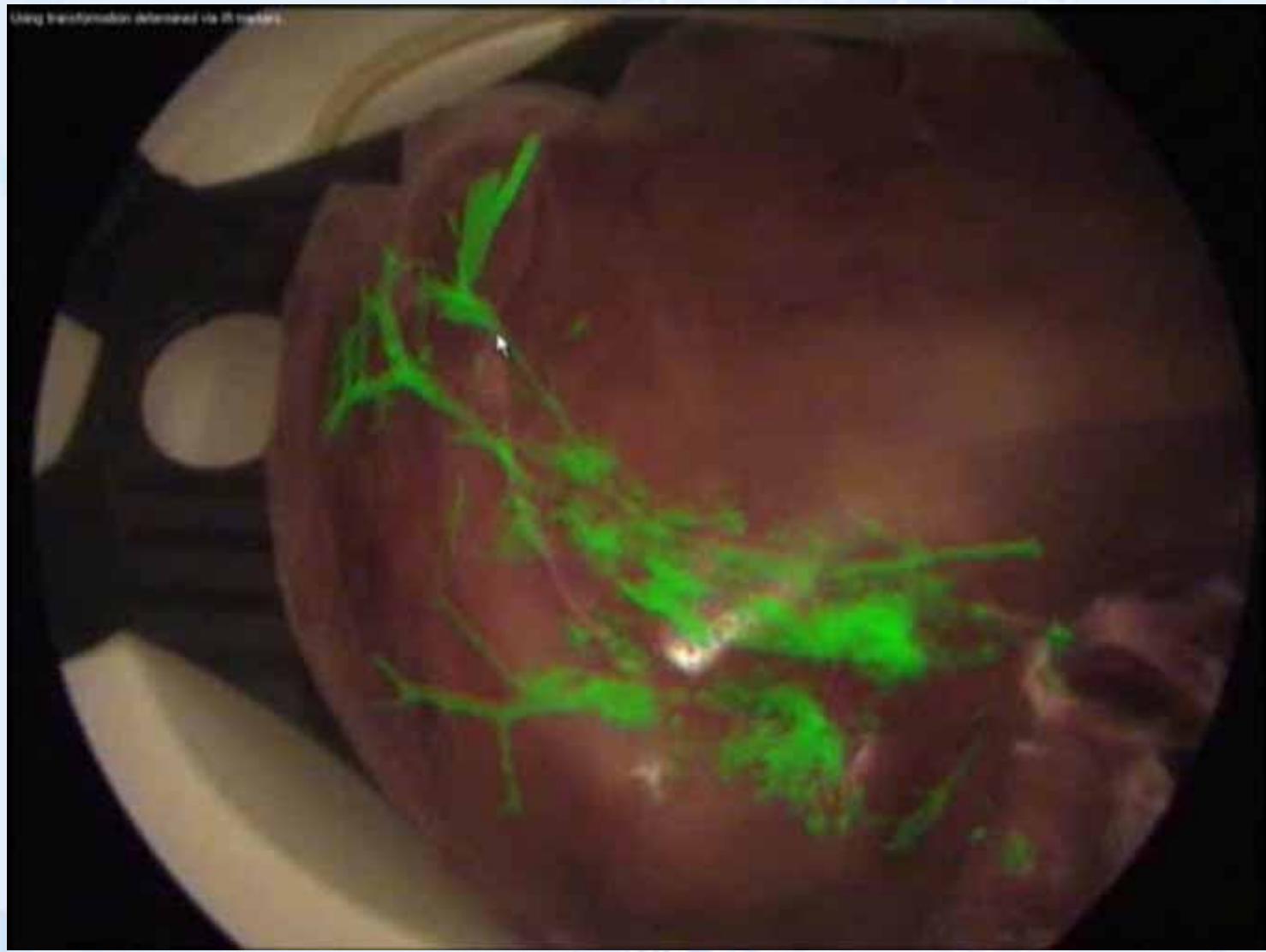
omercic2.bmp - Paint

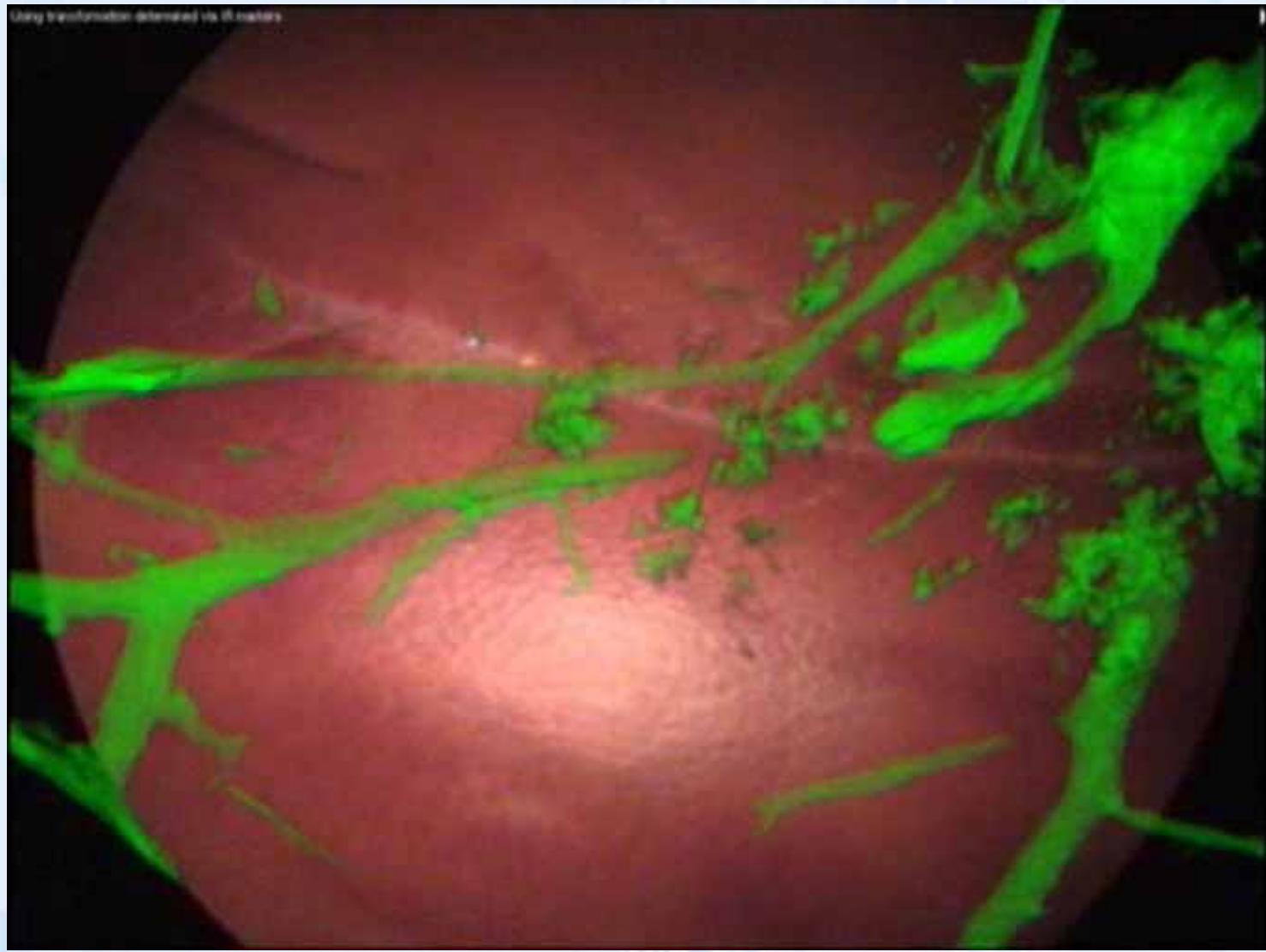
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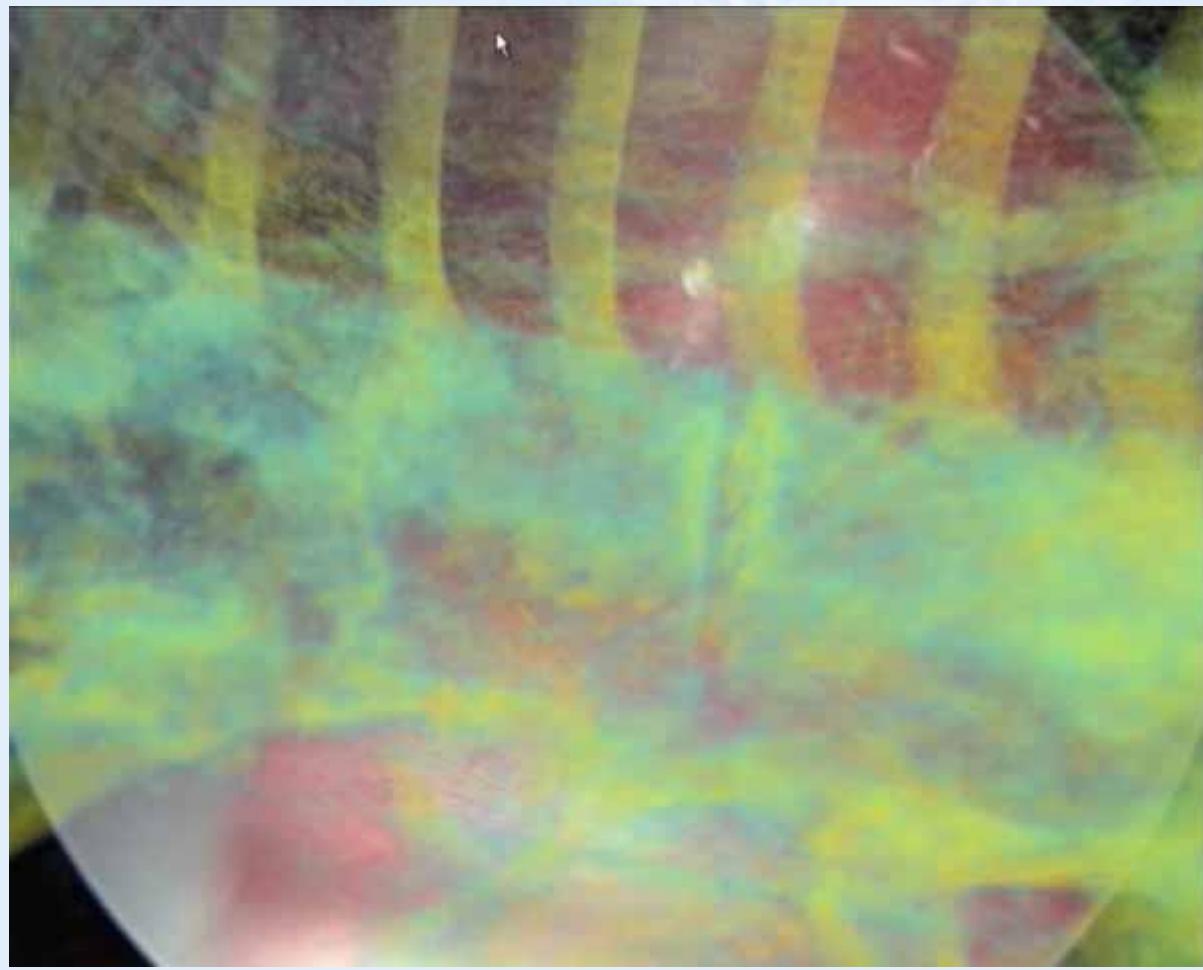






# Registration-Free Laparoscope Augmentation for Liver Resection

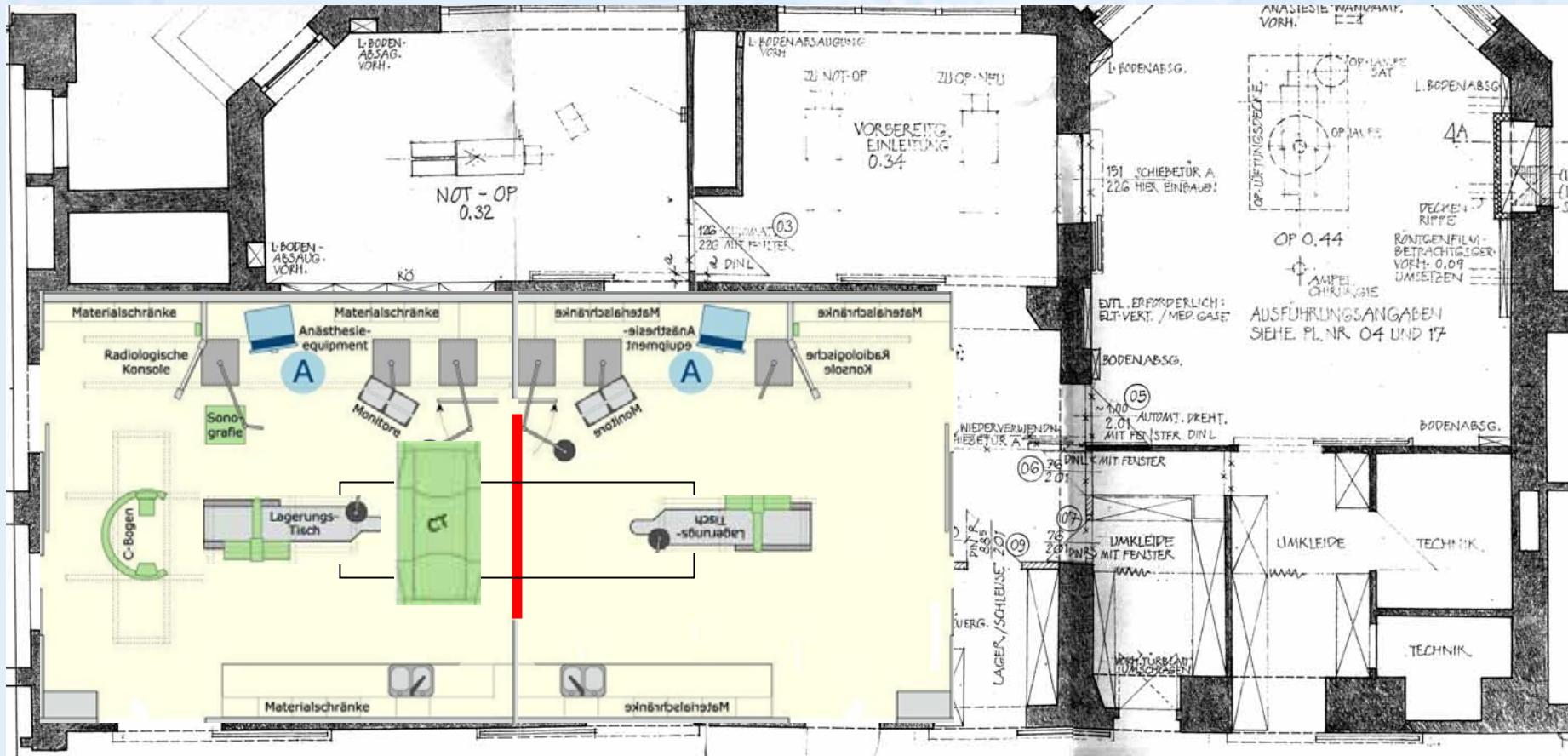


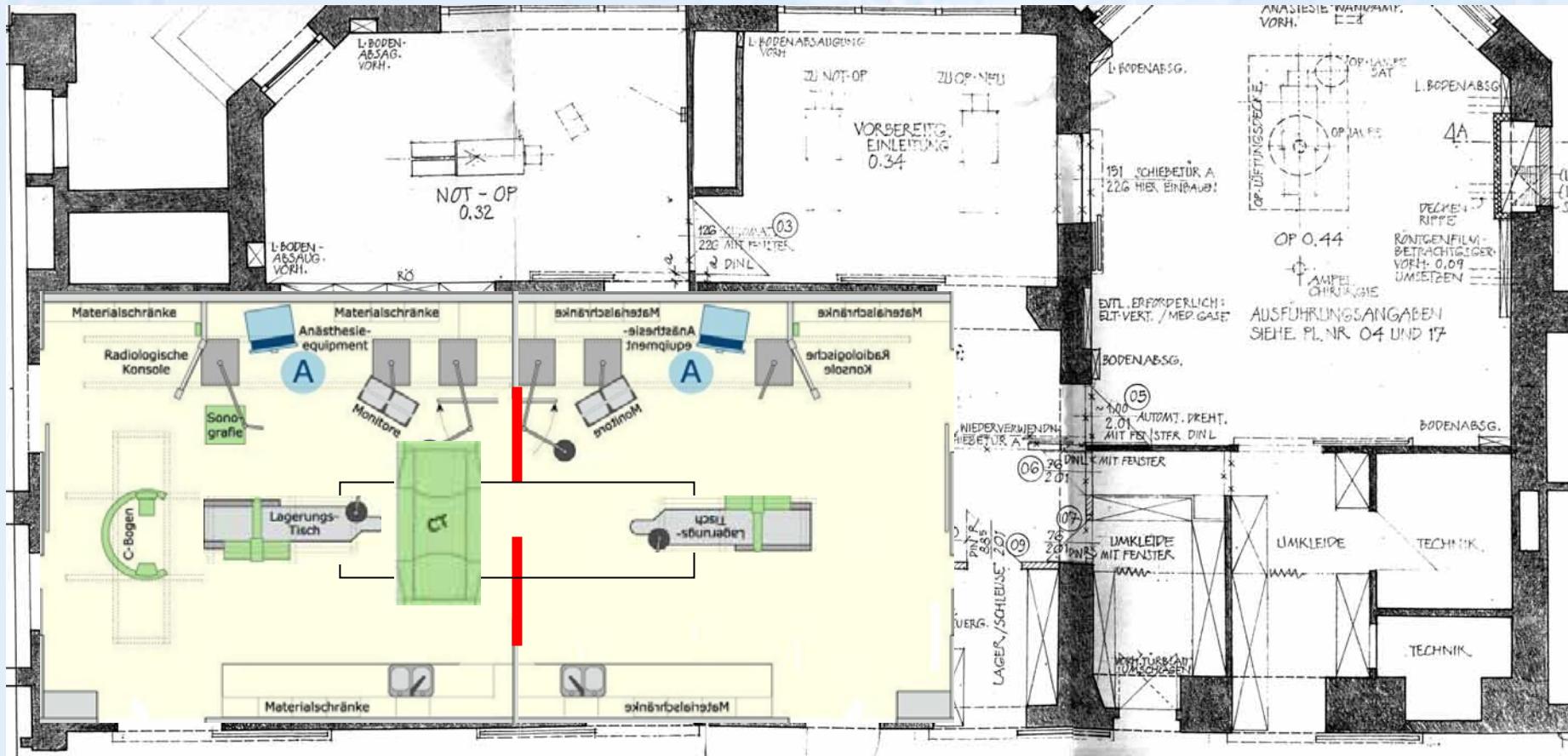


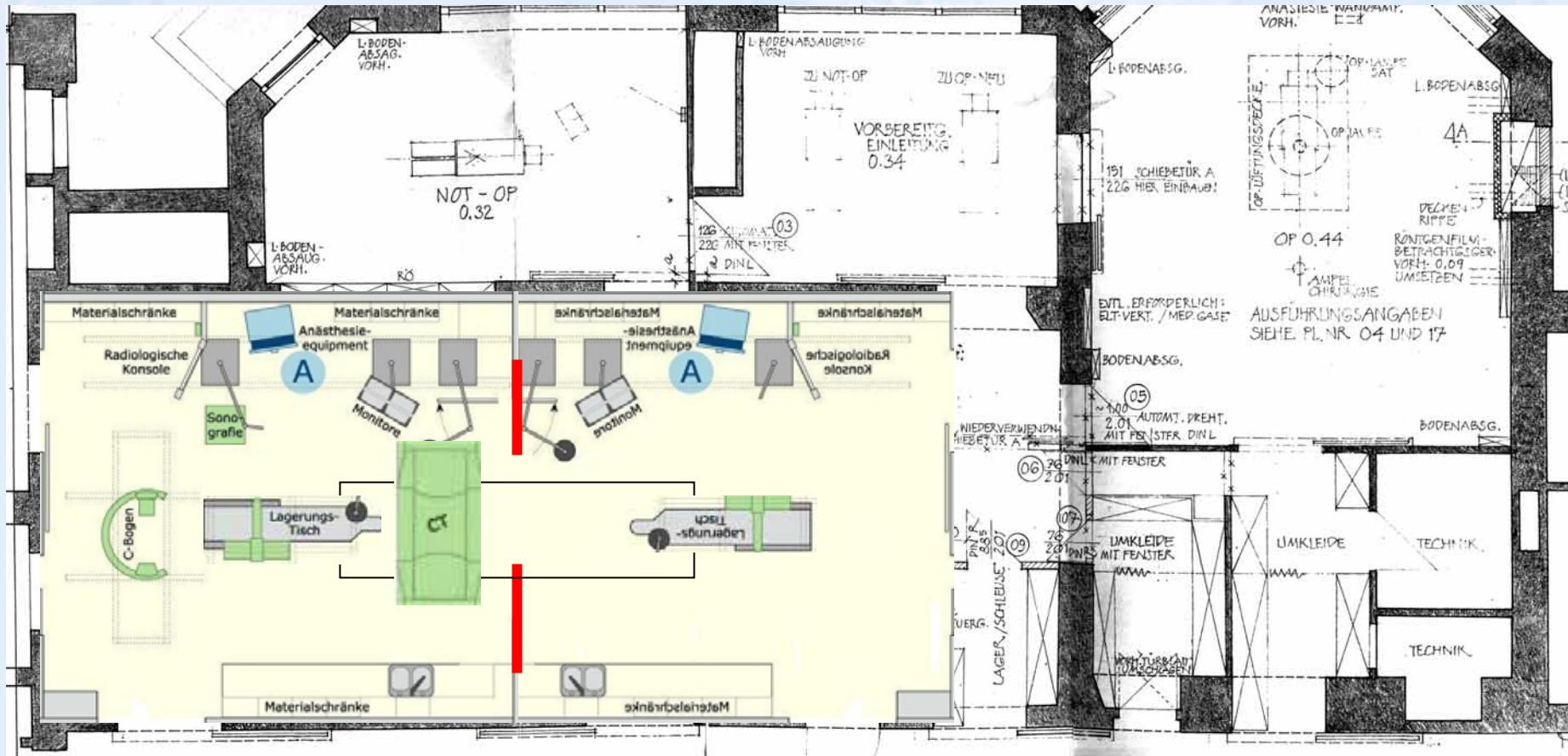
# Video-Augmented X-ray Fluoroscopy CAMC

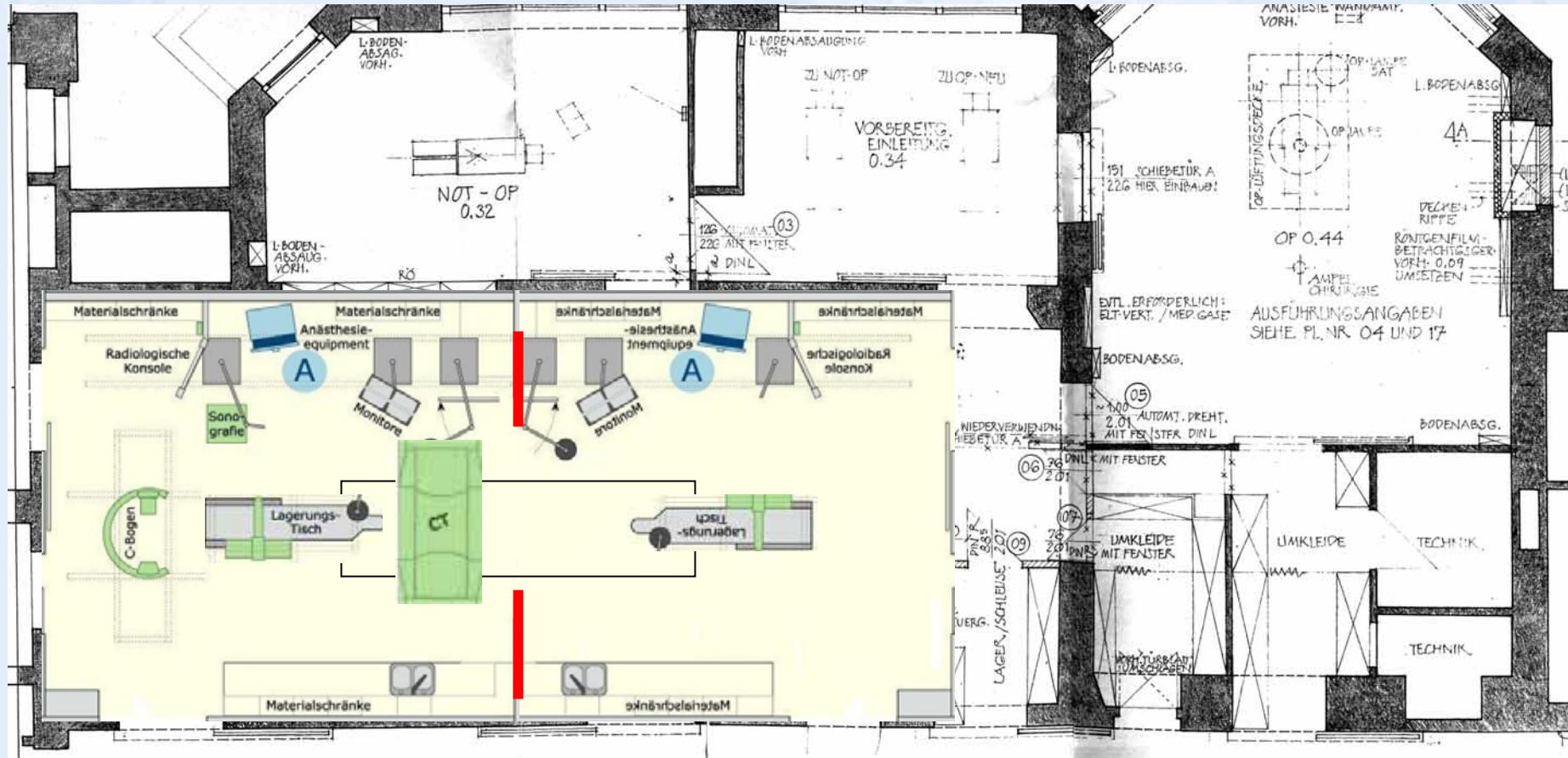


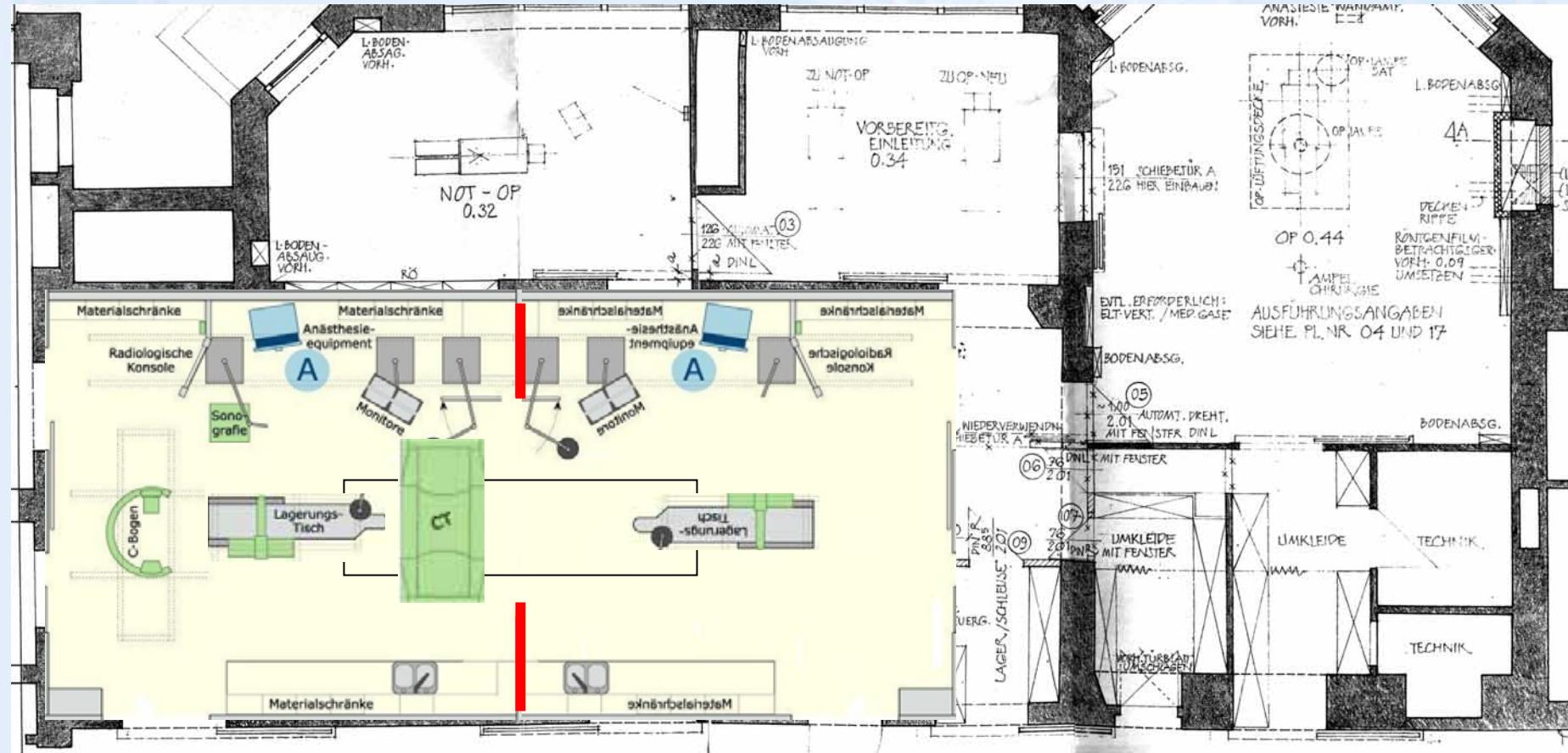


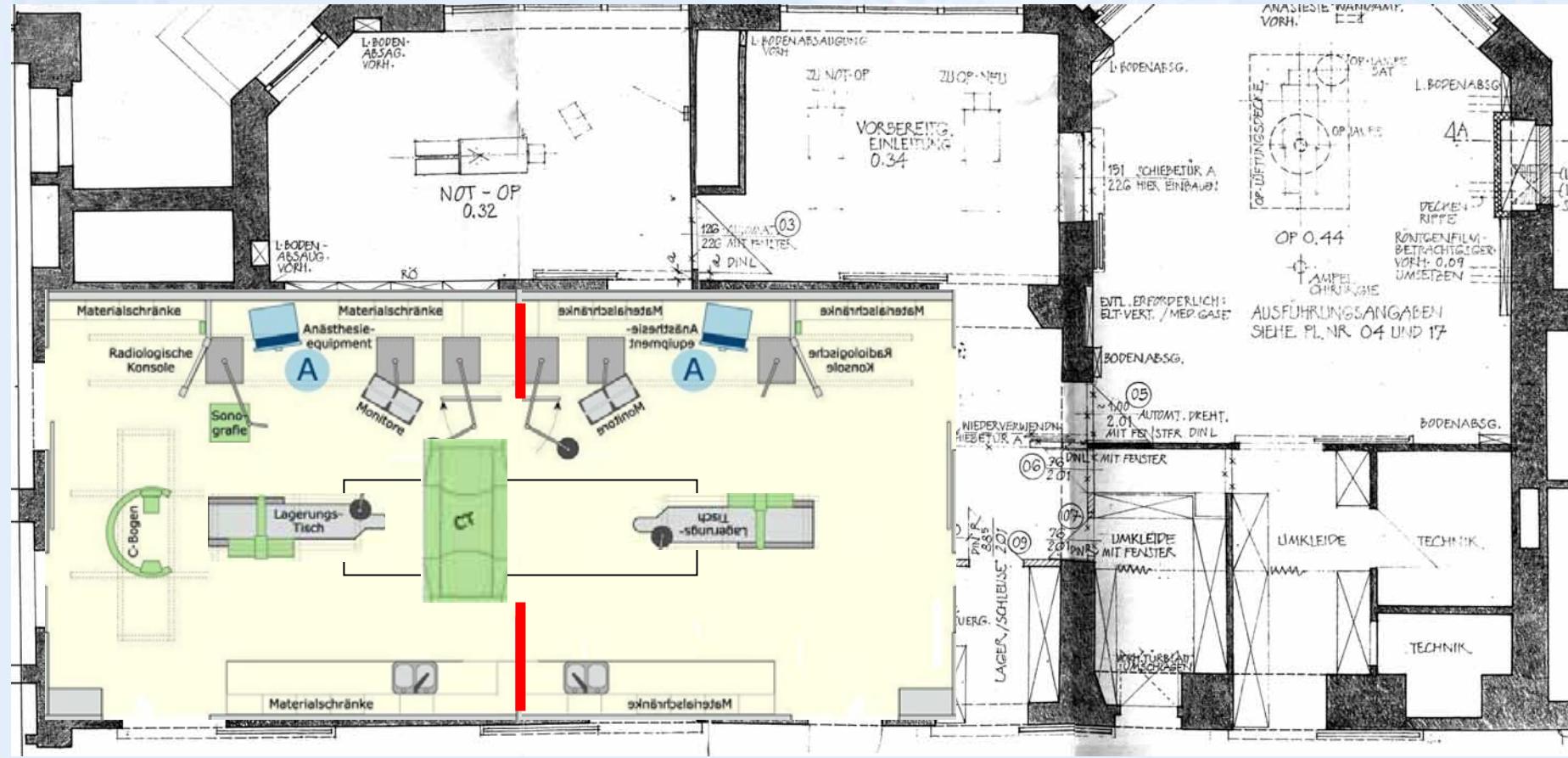


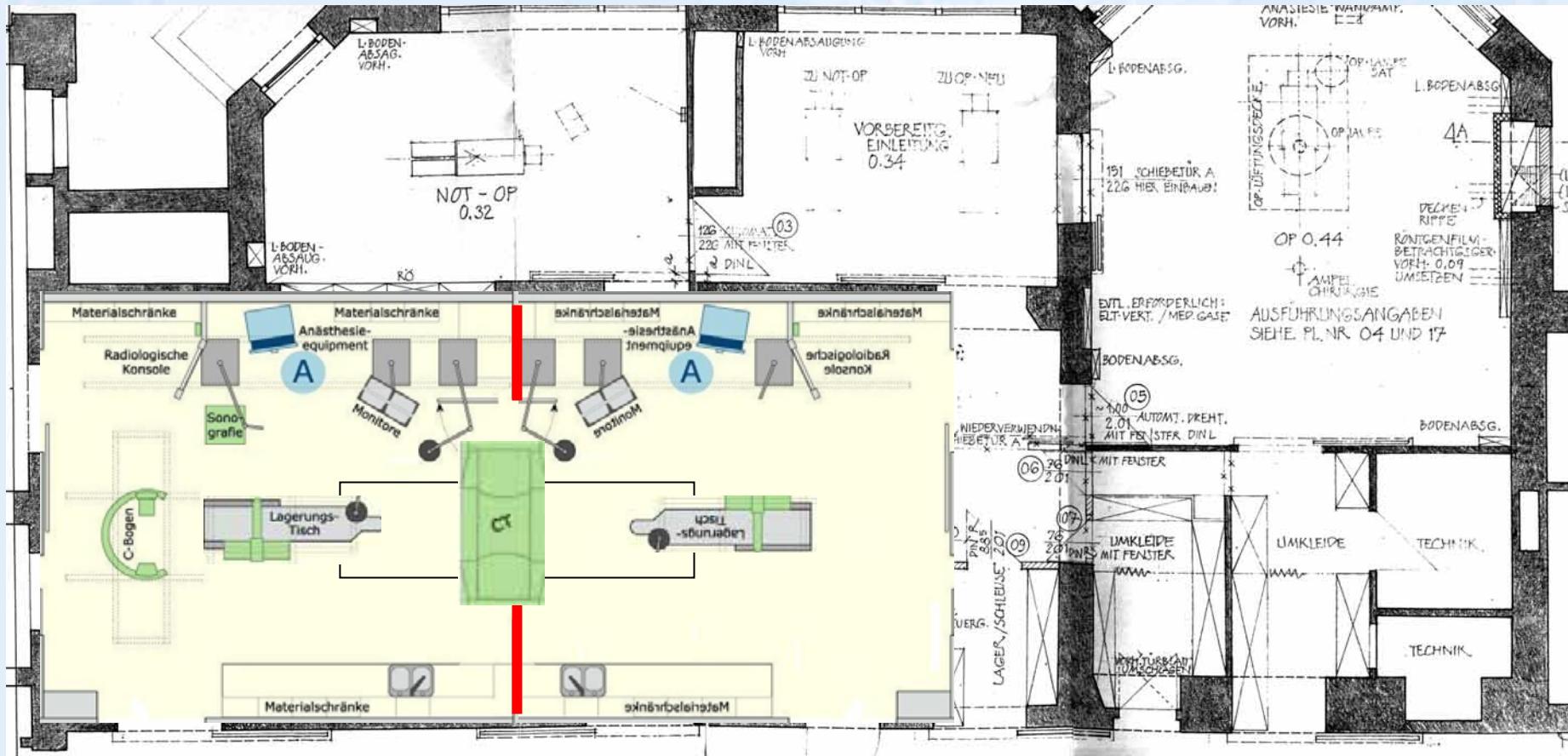


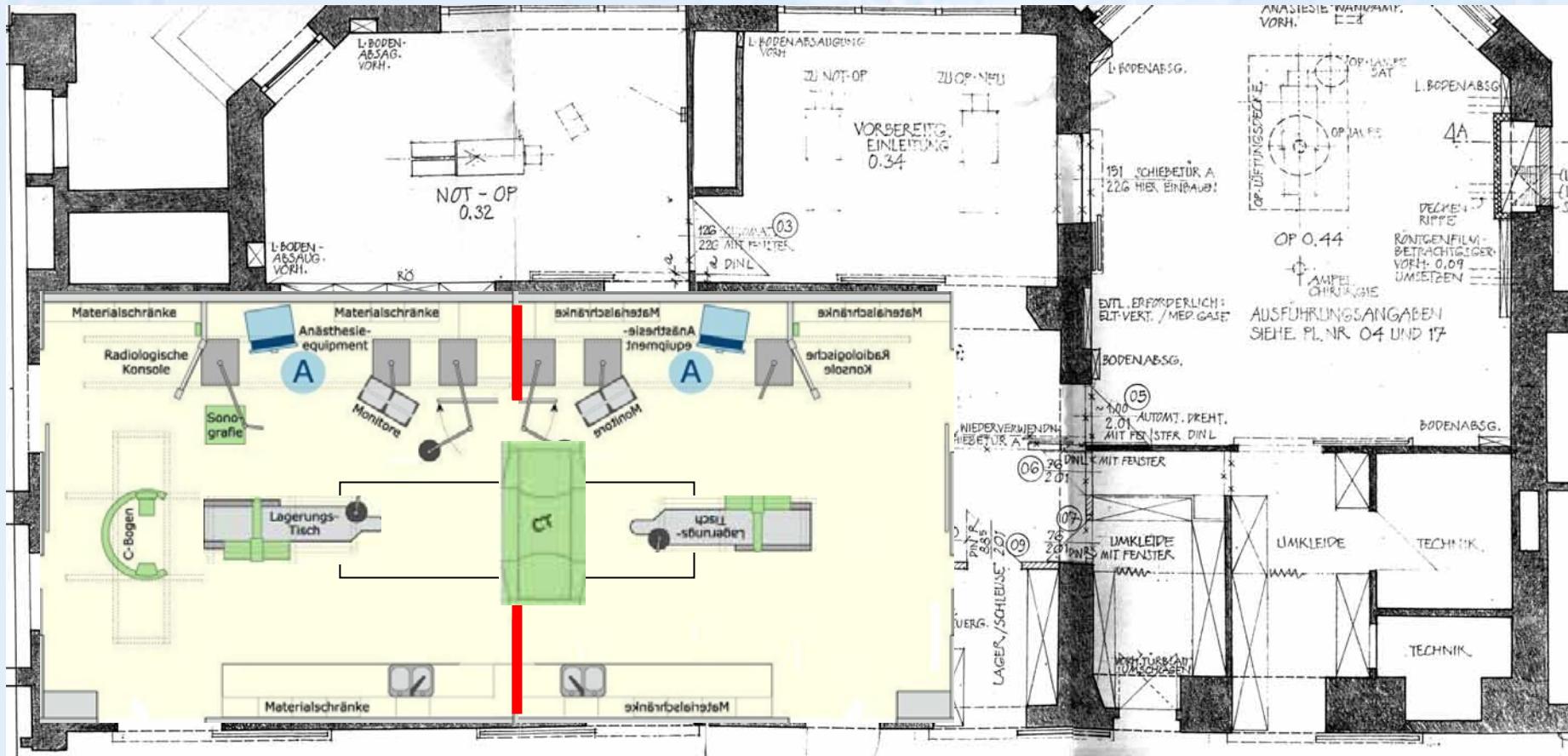


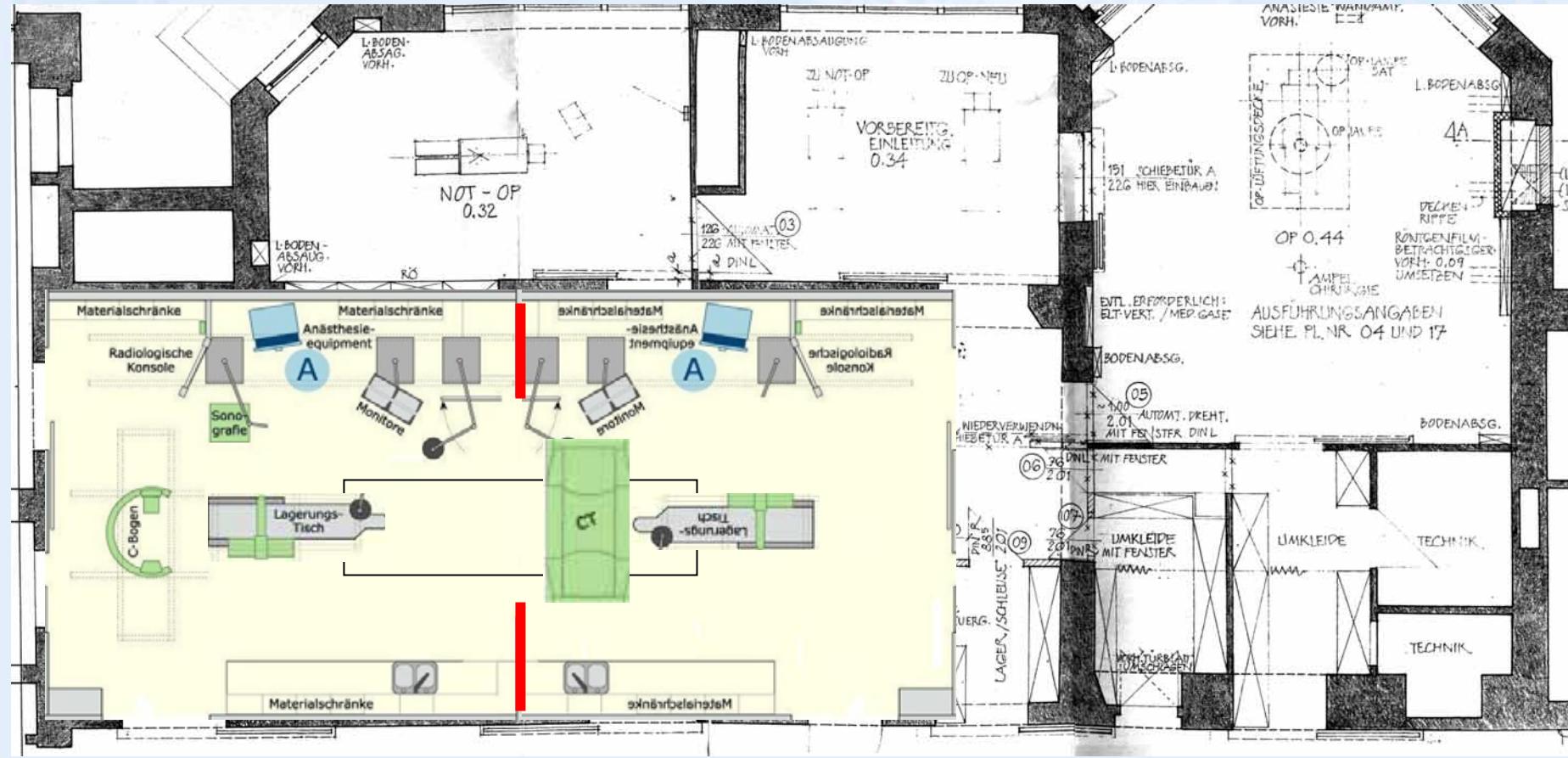


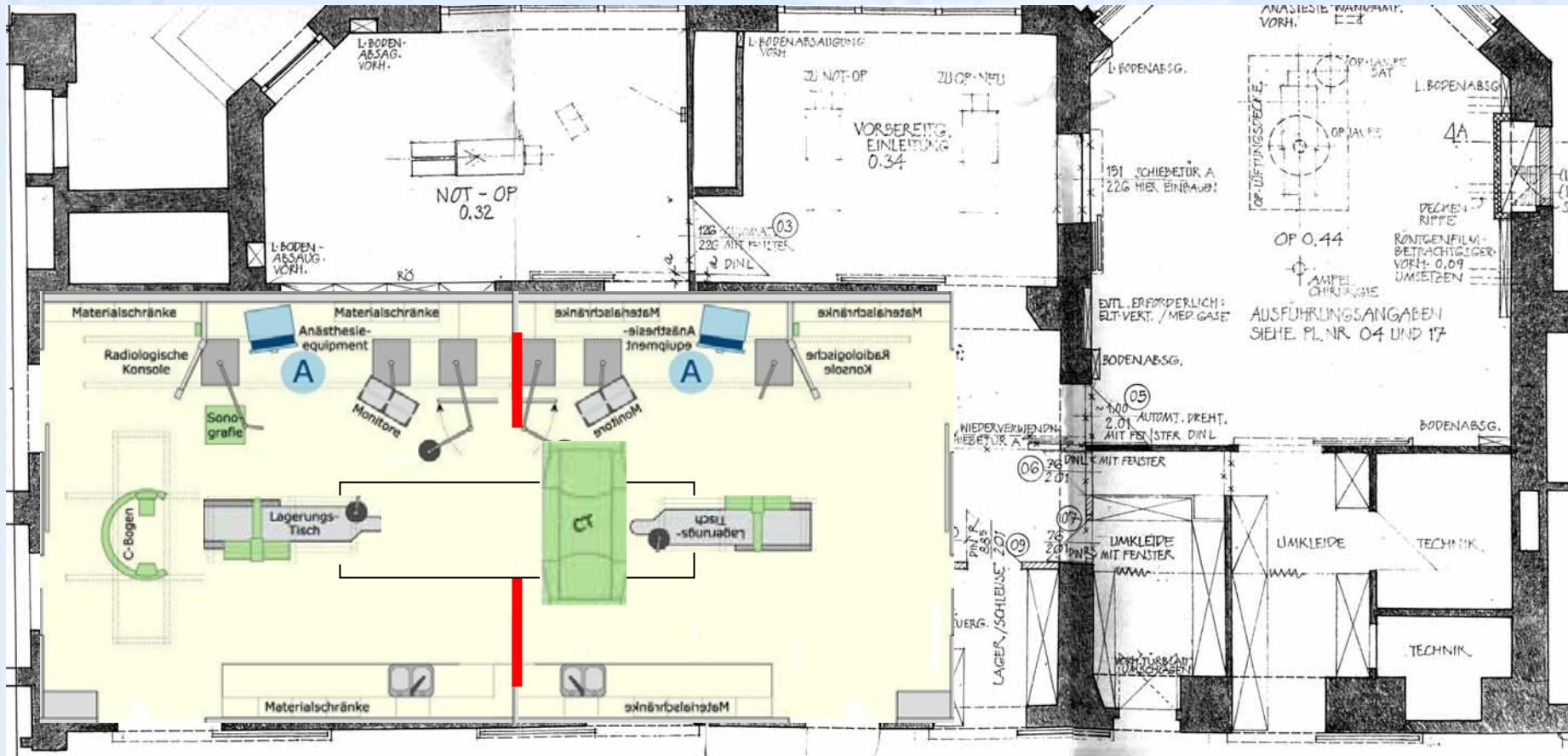


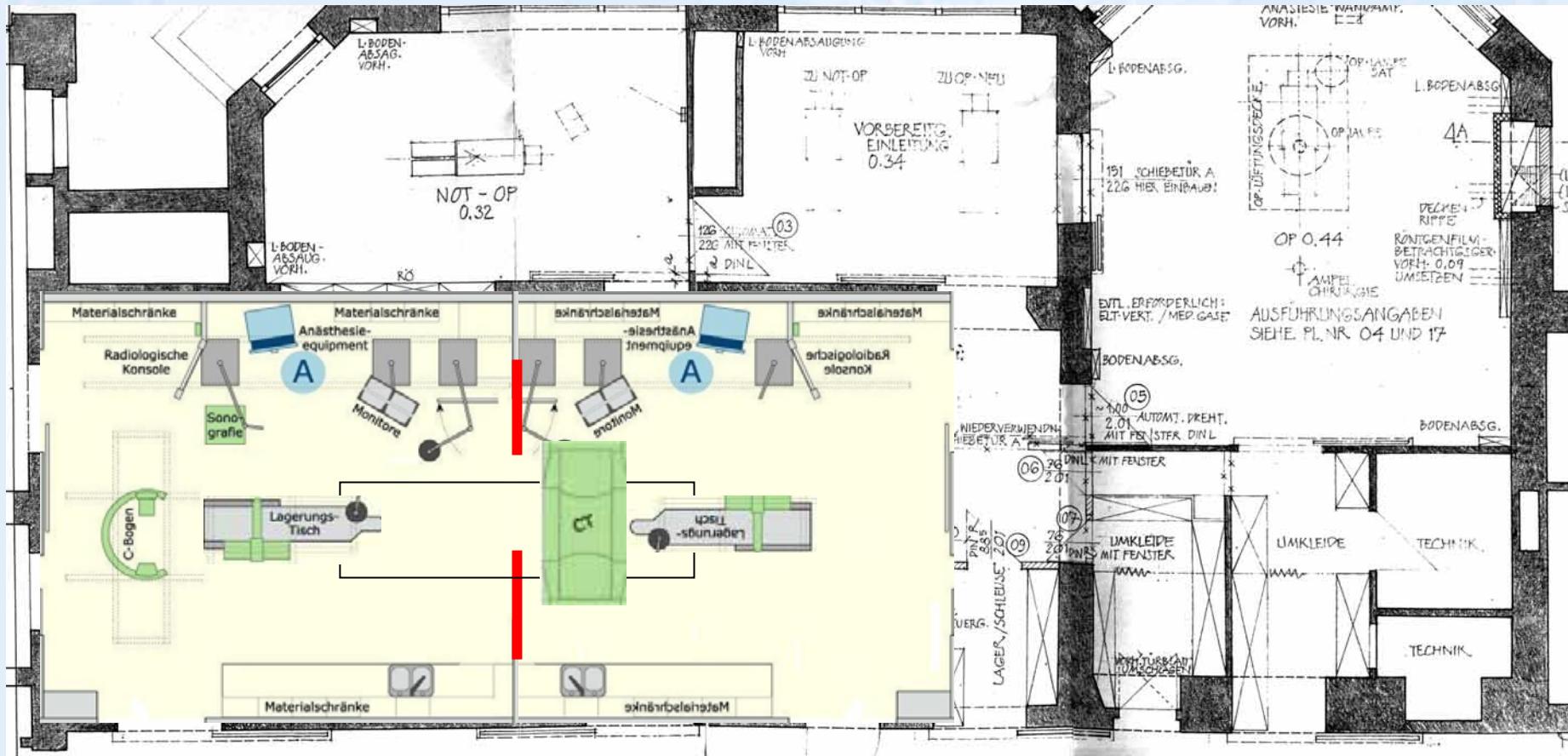


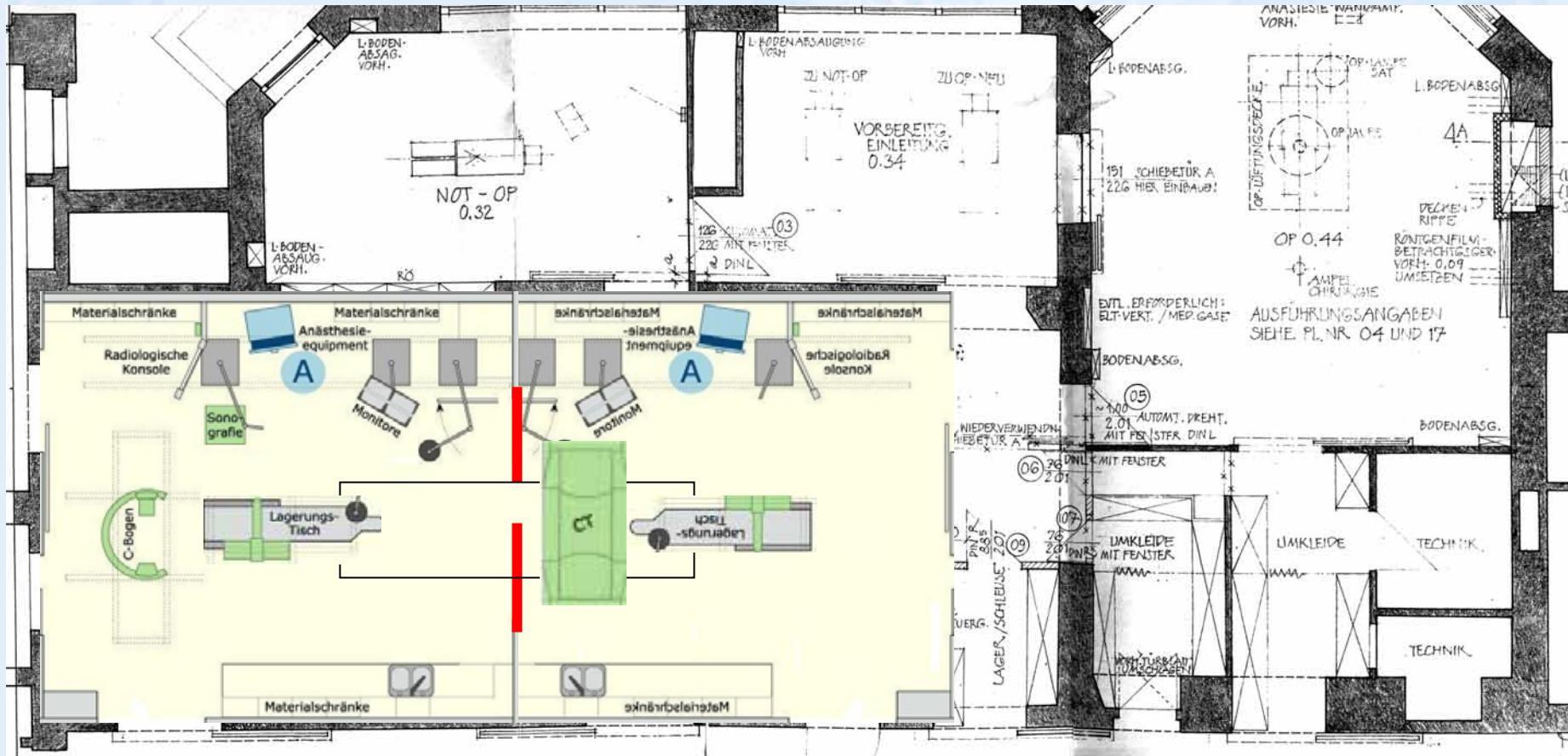


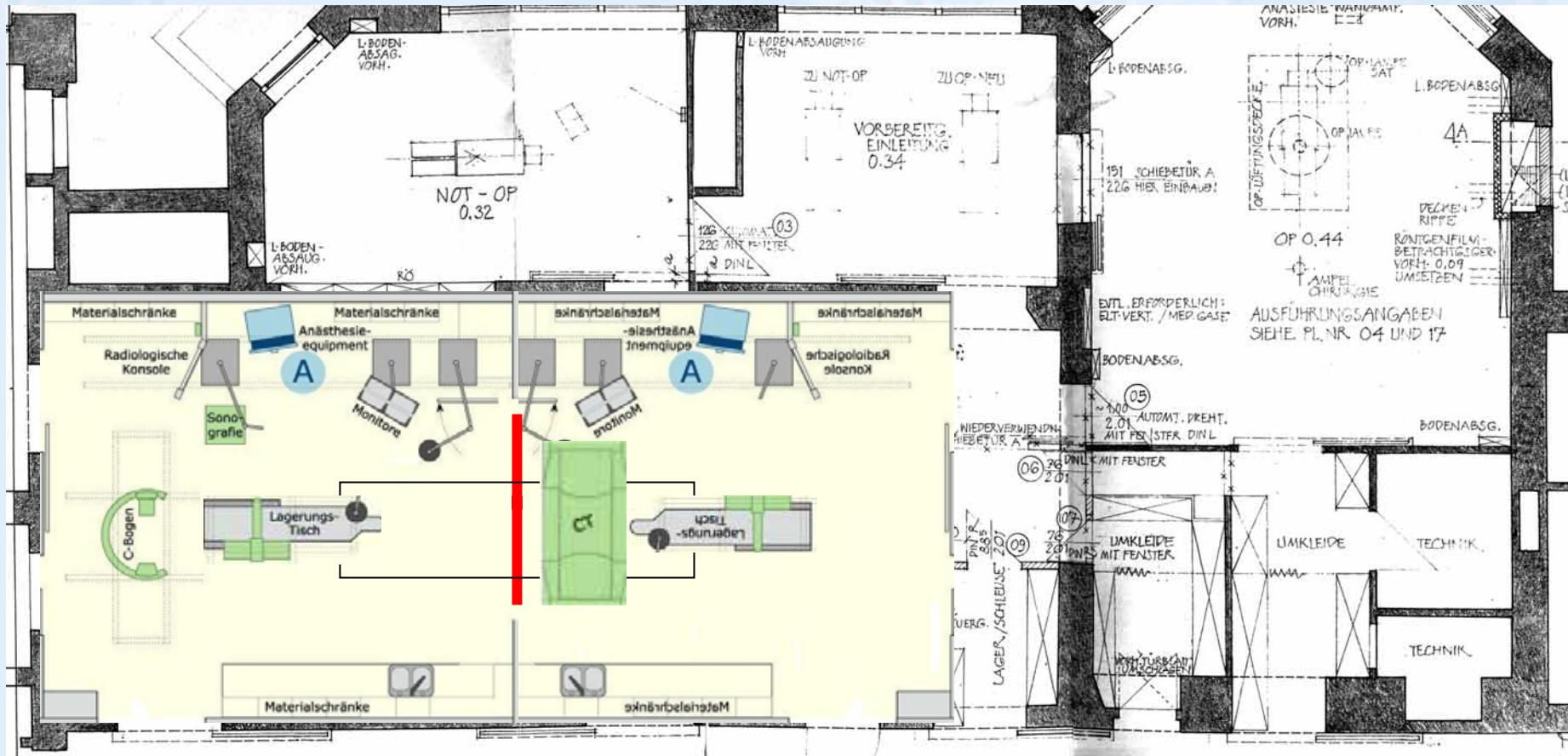


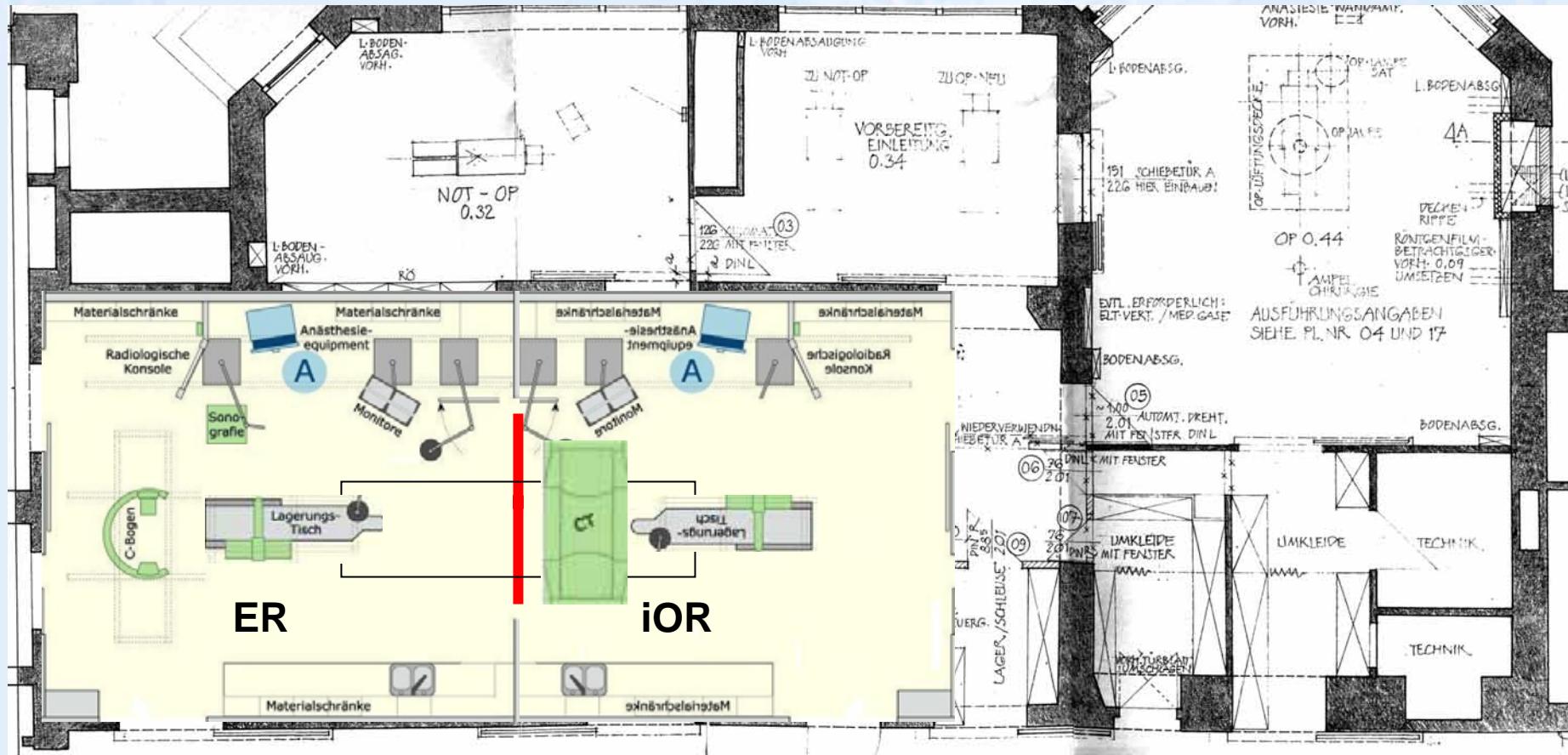


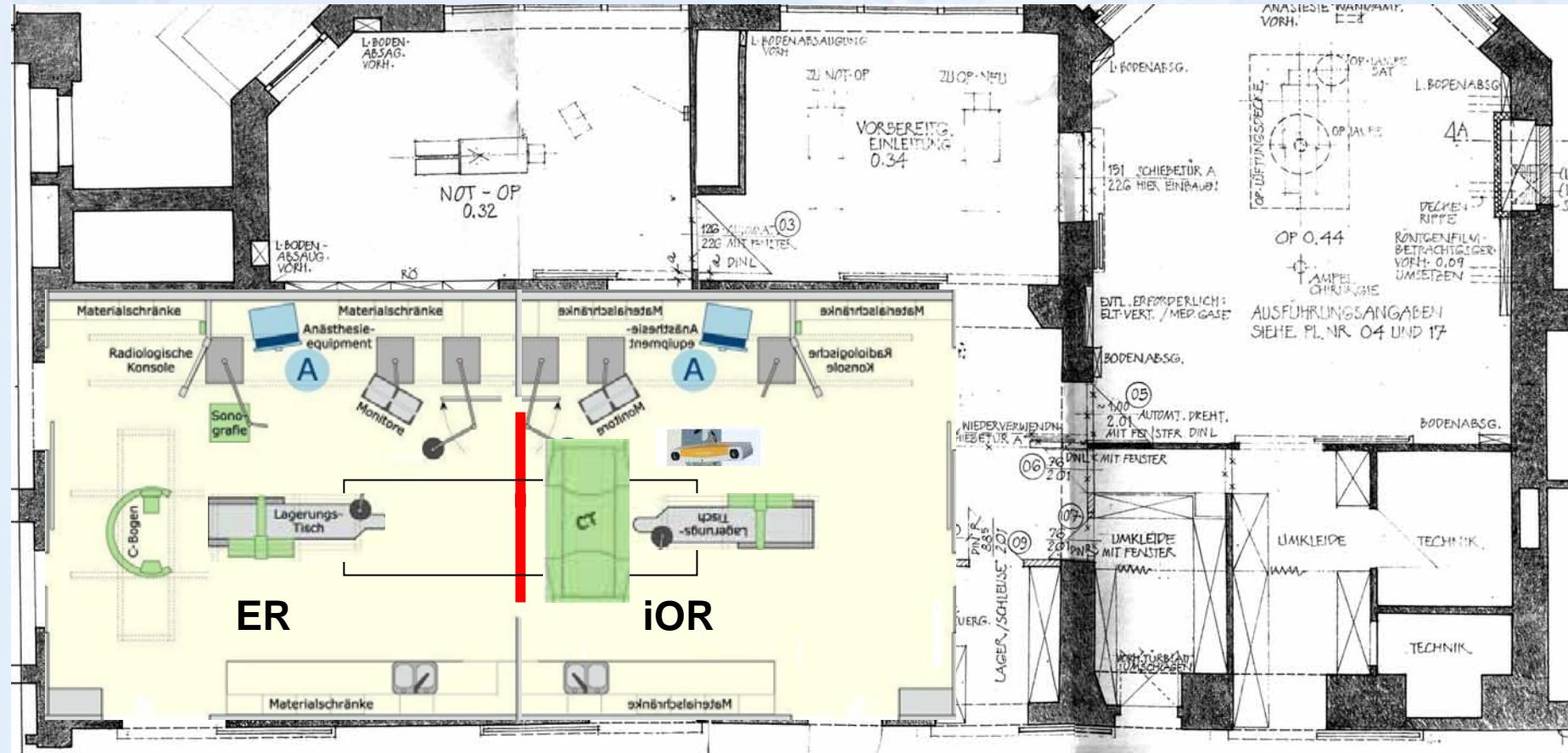


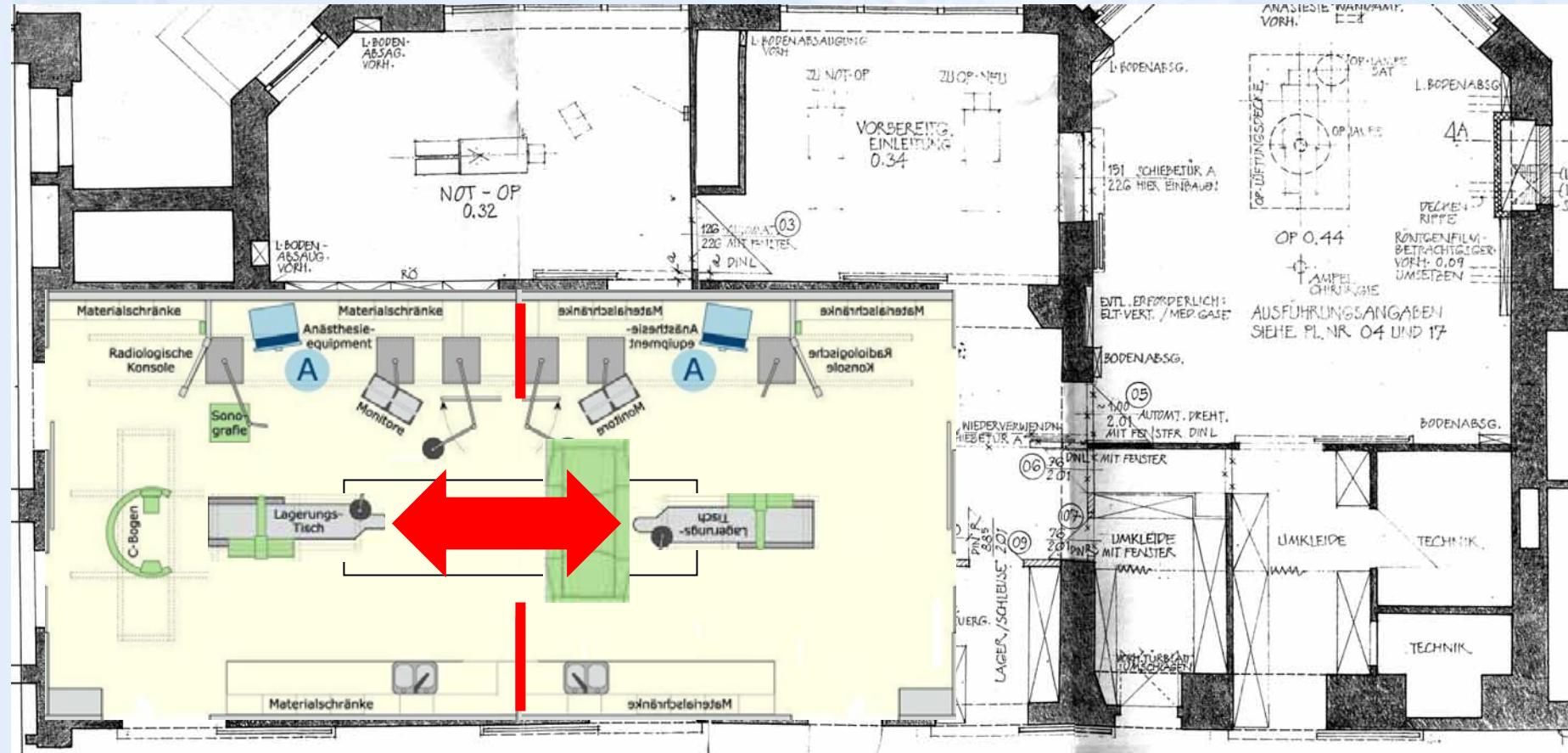


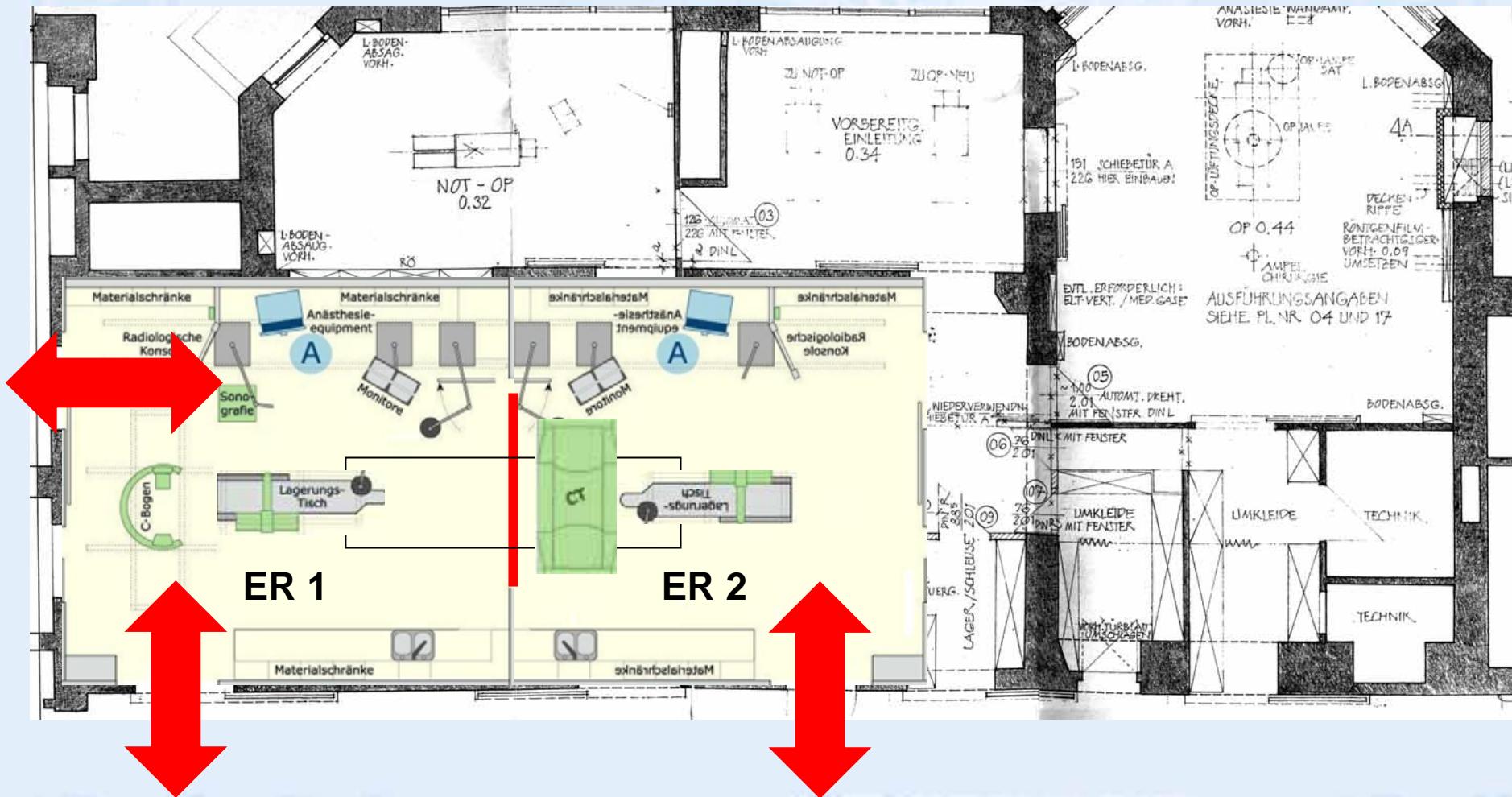






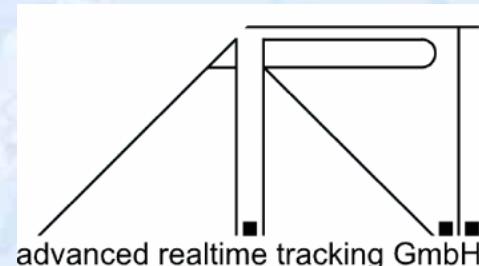








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