Technical University of Munich | Computer Aided Medical Procedures

Project Management and Software Development

Automatic Pose Synchronization

Final Presentation – 8 February 2017

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Project's Goal

Synchronize different pose streams in time automatically





https://www.sapling-inc.com/blog/wpcontent/uploads/2011/04/GettyImages_85406496.jpg (24/10/16)



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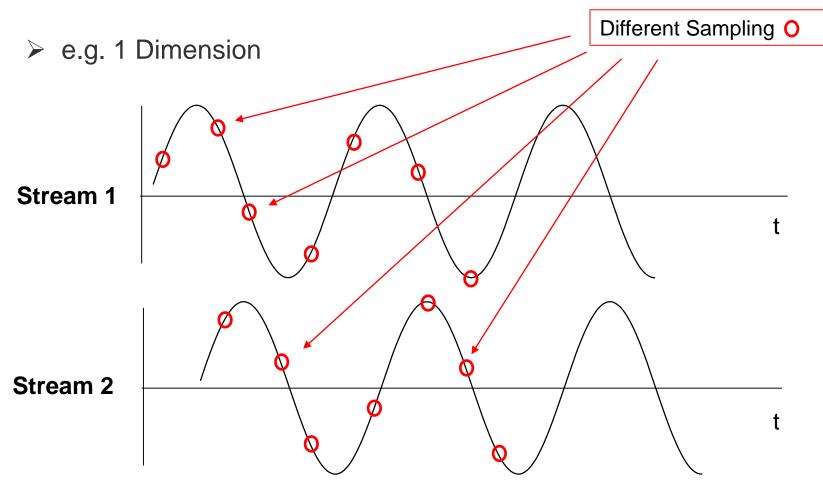
Requirements and Specifications

- Communication with tracking system
- Use of Quaternionic Upsampling¹
- Alignment of different tracking streams
- Visualization Framework
- Implementation in Matlab



[1] Source: B. Busam, M. Esposito, B. Frisch, N. Navab Quaternionic Upsampling: Hyperspherical Techniques for 6 D-o-F Pose Tracking International Conference on 3DVision (3DV), Stanford University, California, USA, October 2016

Synchronization Problem



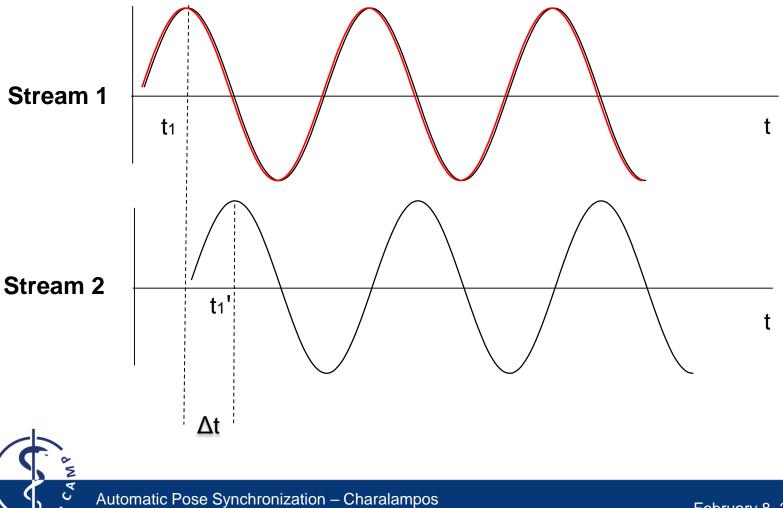
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Synchronization Problem

➢ e.g. 1 Dimension

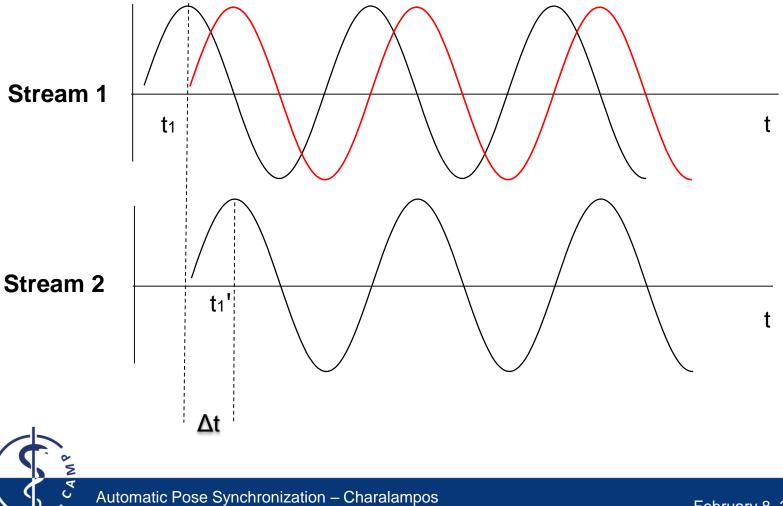
Papathanasis



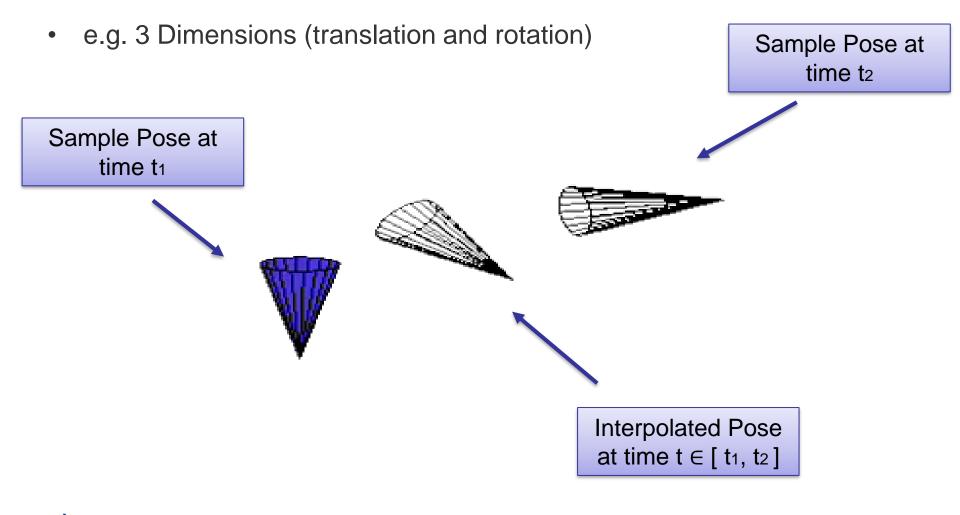
Synchronization Problem

➢ e.g. 1 Dimension

Papathanasis



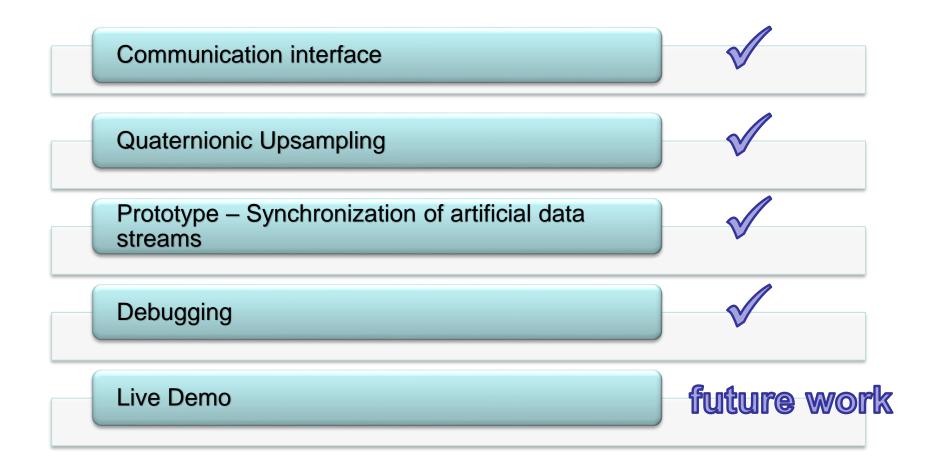
Upsampling





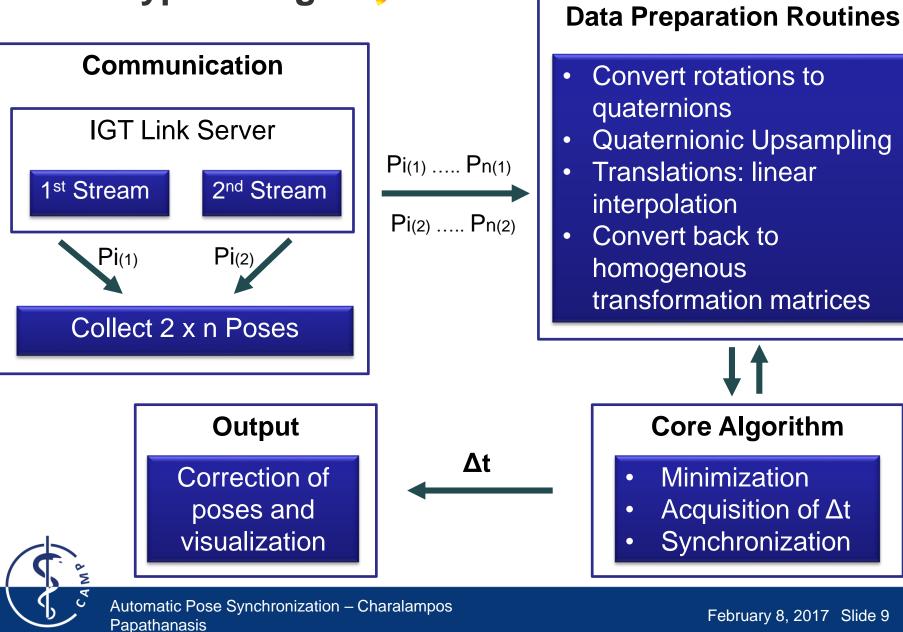
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Tasks and Achievements

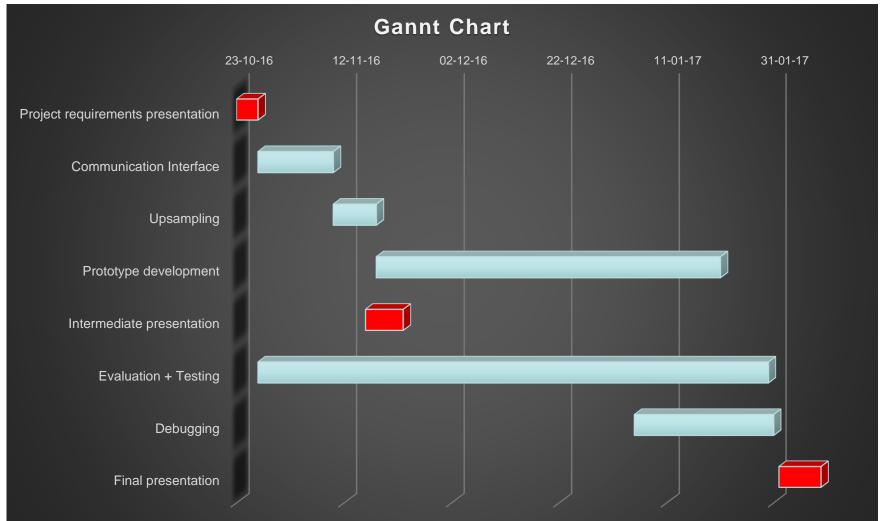








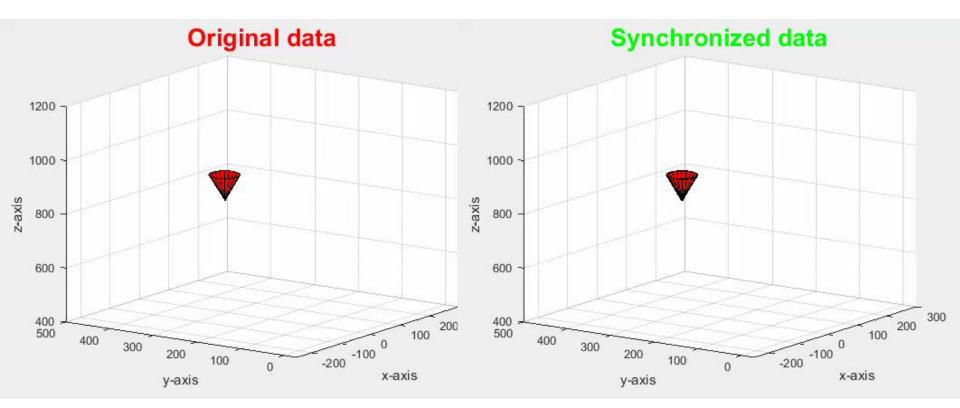
Time Schedule





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Results

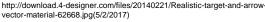




In conclusion

- Project's main goal accomplished
- Quaternionic Upsampling proved a good approach for interpolation
- Promising results
- Room for improvement
- Possibilities for integration with other applications







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