Project Management and System Development Real-time Gaze Estimation

Final presentation – 09/07/2018 Project supervisor: Benjamin Busam Presented by: Matthieu Zhang matthieu.zhang@polytechnique.edu



The project

- Using a simple camera, estimate the point of gaze of a subject in real time
 - Medical application static/dynamic
- Camera Intel RealSense D435
 - RGB + stereo depth resolution
- Find eye regions
- Recognition of some points of interest in the eye region
 - Eye corner
 - Iris center
- Use linear algebra to predict gaze
 - Calibration
 - Polynomial regession or RBF Kernel for non parametric regression





• G. Anjith & R. Aurobind (2016). Fast and Accurate Algorithm for Eye Localization for Gaze Tracking in Low Resolution Images, IET CV 2016

July 18, 2018 Slide 2

Eye corner detection

- Low quality image detection
 - Need to find adapted algorithms
- Harris corner methods
 - Works well in some cases but parameters vary too much depending on light/type of eyes
- Regression trees
 - Library implementing 68 facial landmarks detection with regression trees
 - Usage really fast: < 10ms for both eye corners





• G. Santos & H. Proenc (2011). A Robust Eye-Corner Detection Method for Real-World Data, IEEE Biometrics Compendium



• V. Kazemi & J. Sullivan (2014). One Millisecond Face Alignment with an Ensemble of Regression Trees, IEEE Conference on Computer Vision and Pattern Recognition

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Estimating the gaze

- Calibration on a 3 x 3 square
- Could not make iris center detection work, need to reimplement it
 Detection of iris by hand
- Polynomial regression to predict point of gaze

$$screen X_{i} = a_{0}x_{i} + a_{1}y_{i} + a_{2}x_{i}y_{i} + a_{3}x_{i}^{2} + a_{4}y_{i}^{2} + a_{5}$$
$$screen Y_{i} = b_{0}x_{i} + b_{1}y_{i} + b_{2}x_{i}y_{i} + b_{3}x_{i}^{2} + b_{4}y_{i}^{2} + b_{5}$$

- (x_i, y_i) coordinates of EC IC
- screenX and screenY coordinates of the point of gaze



Improving precision

- More precision in the grid used to determine iris center coordinates
- On the left, without precision grid, on the right with



Real-time gaze estimation — Matthieu Zhang Questions ?

