Similarity Metrics and Efficient Optimization for Simultaneous Registration

Christian Wachinger, Nassir Navab

Motivation Analysis of a group of images requires their alignment • Alignment of 2D face images, 3D tomographic images, Ultrasound Mosaicing Pairwise registration methods with a priori chosen prior lead to bias introduction Simultaneous registration presents an interesting alternative but leads to a higher computational complexity because of multivariate similarity measures • optimization in higher dimensional parameter space Direct estimation of multivariate measures is prohibitive because the dimension grows with the number of images • We present multivariate similarity metrics and efficient optimization strategies **Multivariate Similarity Measures** Formulize intensity-based registration as maximum likelihood estimation I_i : Images $\hat{\mathbf{x}} = \arg\max_{\mathbf{x}} \log p(I_1, \dots, I_n; \mathbf{x})$ \mathbf{x} : Transformation Approximations to avoid the estimation of the high-dimensional PDF Update step: $p(I_1,\ldots,I_n)$ Congealing Accumulated Pairwise Estimates (APE) $\prod \prod p^k(I_i(s_k))$ Congealing w/ Markov $\prod \prod p(I_j|I_i)$ Property (CMP) Cost function $\prod \prod p^k(I_i(s_k)|I_{\mathcal{N}_i}(s_k))$ Taylor series • APE and CMP are classes of similarity metrics, while Congealing is a specific one • APE and CMP need the selection of a noise model Deduction of APE: Congealing: $p(I_1,\ldots,I_n) \approx \prod p^k(I_1(s_k),\ldots,I_n(s_k))$ $p(I_1,\ldots,I_n) \stackrel{\text{Prod.Rule}}{=} p(I_1,\ldots,I_{n-1}|I_n) \cdot p(I_n)$ $s_k \in \Omega$ $\stackrel{\text{Cond.Indep.}}{=} \prod^{n-1} p(I_i|I_n) \cdot p(I_n)$ Markov Property Independence $\prod \prod p^k(I_i(s_k))$ $\prod \prod p^k(I_i(s_k)|I_{\mathcal{N}_i}(s_k))$ $||. \qquad p(I_1, \dots, I_n)^n = \prod_{i=1}^n p(I_i) \cdot \prod_{i=1}^n \prod_{j=1}^n p(I_j | I_i)$ $s_k \in \Omega i=1$ CMP like measure: Sum of Voxel Variances $\log p(I_1, ..., I_n) = \frac{1}{n} \sum_{i=1}^n \log p(I_i) + \frac{1}{n} \sum_{i=1}^n \sum_{j \neq i} \log p(I_j | I_i)$ $\log p(I_1,\ldots,I_n) \approx -\sum_{s_k \in \Omega} \sum_{i=1}^n (I_i(s_k) - \mu_k)^2$ $\approx \sum_{i=1}^{n} \sum_{j \neq i} \log p(I_j | I_i)$ $\mu_k = \frac{1}{n} \sum_{l=1}^n I_l(s_k)$

Transformation Parameterization

Rigid Transformations do not form vector spaces but Lie Groups. We perform a geometric optimization where the group structure is taken care of intrinsically. Special Euclidean Group:

$$\mathbf{x}_i = \begin{bmatrix} \mathbf{R} & \mathbf{t} \\ \mathbf{0} & 1 \end{bmatrix} \in \mathbb{SE}(3) \qquad \mathbf{x} = [\mathbf{x}_1, \mathbf{x}_2]$$

The tangent space is the Lie algebra

$$\mathfrak{se}(3) = \left\{ \begin{bmatrix} \Omega & \mathbf{v} \\ \mathbf{0} & 0 \end{bmatrix} | \Omega \in \mathbb{R}^{3 \times 3}, \mathbf{v} \in \mathbb{R}^{3}, \Omega \right\}$$

 $\mathbf{h}_{j} \in \mathfrak{se}(3)$ $\mathbf{h}_{j} = \sum_{i=1}^{6} h_{i} \mathbf{l}_{i}$ $\mathbf{h} = \begin{bmatrix} \mathbf{l} \end{bmatrix}$

Exponential map: Lie Algebra to Lie Group

$$\exp:\mathfrak{se}(3)\to\mathbb{SE}(3)$$

$$\mathbf{y} = \mathbf{x} + \mathbf{h}$$
$$\mathbf{y} = \mathbf{x} \circ \exp(\mathbf{h}) = \mathbf{x} \circ \exp\left(\sum_{i=1}^{6} h_i \mathbf{l}_i\right)$$

Optimization Methods

$$E(\mathbf{x}) = \sum_{i \neq j} F_{i,j}(\mathbf{x}) = \sum_{i \neq j} \frac{1}{2} ||\mathbf{f}_{i,j}(\mathbf{x})||$$

$$E(\mathbf{x} \circ \exp(\mathbf{h})) \approx E(\mathbf{x}) + \mathbf{J}_E(\mathbf{x}) \cdot \mathbf{h} + \frac{1}{2}\mathbf{h}^{\top}$$

• Newton-Raphson

$$\mathbf{H}_{F_{i,j}}\mathbf{h}_{i,j}^{\mathrm{NR}} = -\mathbf{J}_{F_{i,j}}^{\top} \qquad \mathbf{x} \leftarrow \mathbf{h}^{\mathrm{NR}} = \left[\sum_{i} \mathbf{h}_{i,1}^{\mathrm{NR}}, \dots, \sum_{i} \mathbf{h}_{i,n}^{\mathrm{NR}}\right]$$

Steepest Descent

$$\alpha \cdot \mathbf{h}^{\mathrm{SD}} = -\mathbf{J}_E^+(\mathbf{x})$$

• Gauß-Newton
$$(\mathbf{J}_{\mathbf{f}_{i,j}}^{ op}\mathbf{J}_{\mathbf{f}_{i,j}})\mathbf{h}_{i,j}^{ ext{GN}} = -\mathbf{J}_{\mathbf{f}_{i,j}}^{ op}\mathbf{f}_{i,j}$$

• ESM
$$\left(\mathbf{J}_{\mathbf{f}_{i,j}}^{\mathrm{ESM}^{\top}}\mathbf{J}_{\mathbf{f}_{i,j}}^{\mathrm{ESM}}\right)\mathbf{h}_{\mathbf{f}_{i,j}}^{\mathrm{ESM}} = -\mathbf{J}_{\mathbf{f}_{i,j}}^{\mathrm{ESM}^{\top}}$$

